



A Generic and Robust Model Validation & Calibration Software

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WAMS-based Dynamic Model Validation & Calibration

Value Proposition

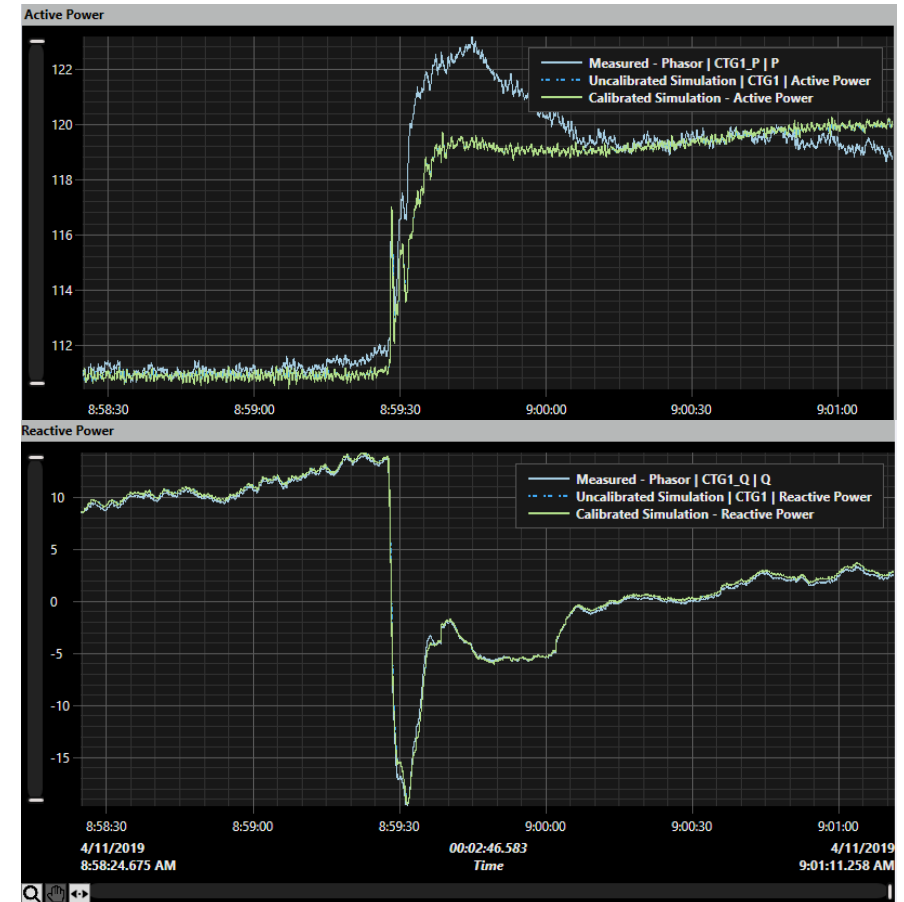
Drivers:

- **Inaccurate Dynamic models:** Inability to predict grid conditions
 - PG&E case (see figure)
 - BPA experience suggests 60-70% of power plant models did not match disturbance recordings even after the baseline test was performed.
- **Mandated Reliability Standards:**
 - **PRC-012-2 Remedial Action Schemes** requiring PCs to evaluate existing RAS within its planning area.
 - **NERC MOD-026 and MOD-027** requiring transmission planners and operators to verify generator models (turbine and excitation controls) on a periodic basis.
 - **MOD-033-1 Steady-State and Dynamic System Model Validation** requiring PCs to validate system planning models against real-time system data.
 - Validate Dynamic model for Real time operational studies

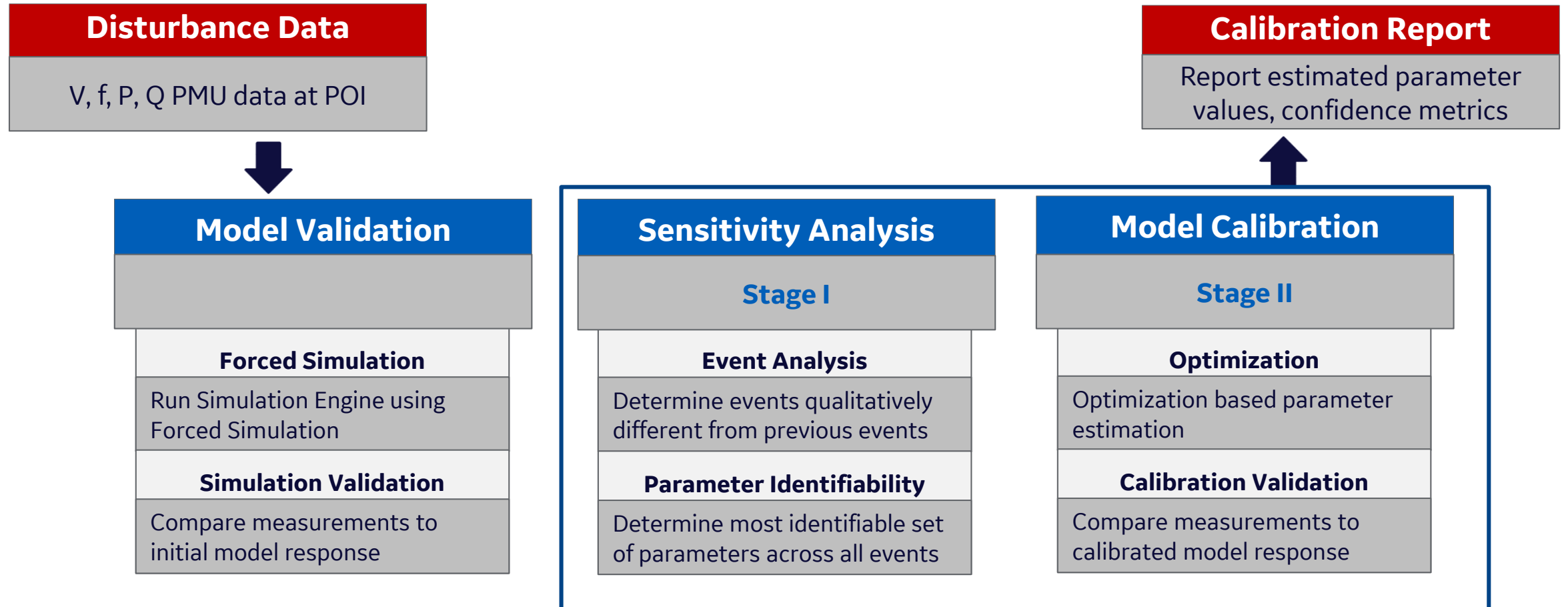
Benefits:

- **Cost-effective** method for TOs and GOs to **satisfy NERC Reliability Standards**.
- **Non-invasive online approach** that allows asset owners to continue operating the plant (and realizing revenue) without stopping operations.
- More accurate models for stability analysis => **Improved Reliability**
- More accurate calculation of system operating limits => **Better Asset Utilization**

PG&E Colusa case



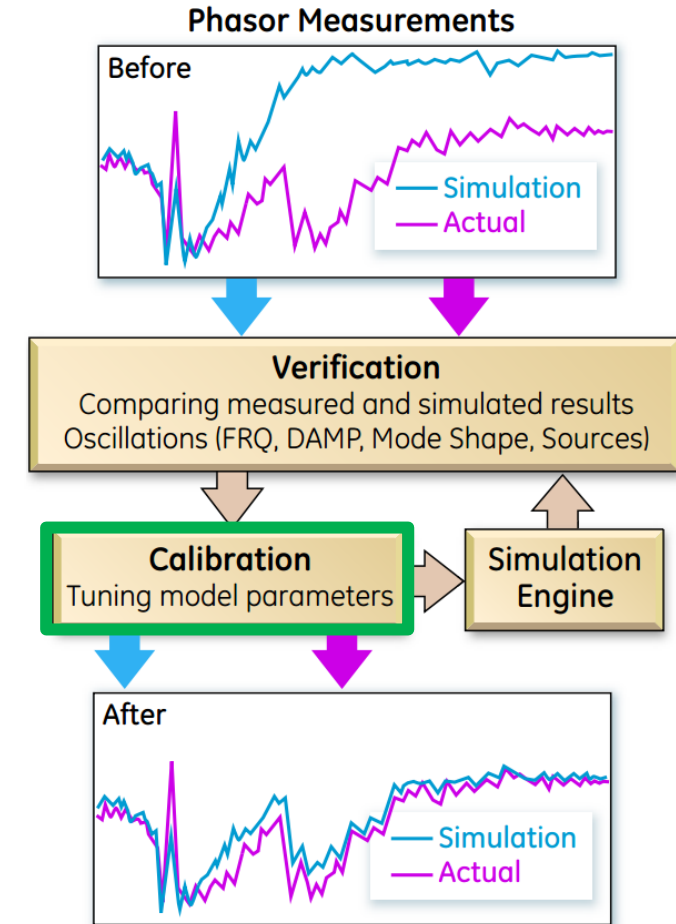
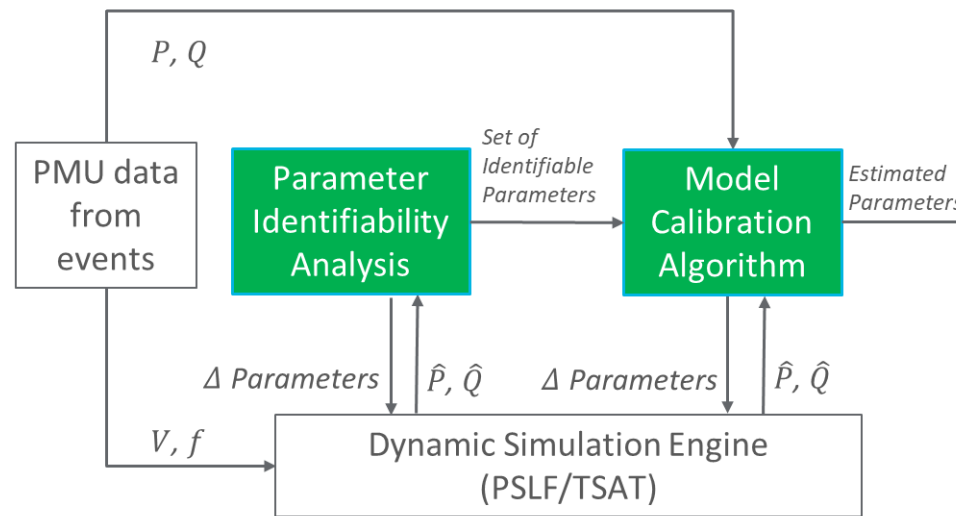
Conceptual Approach



Two Stage Approach for Model Calibration

Design Considerations

- **Production-grade** software tool
- **Generic** for wide variety of models (PSLF, TSAT and PTI PSS/E)
- **Minimal data flow change** on existing tools
- Account for **non-linearity** in models
- Quality of solution with **reasonable speed**
- Account for **multiple different events**
- Avoid tuning parameters that may already be at their true values



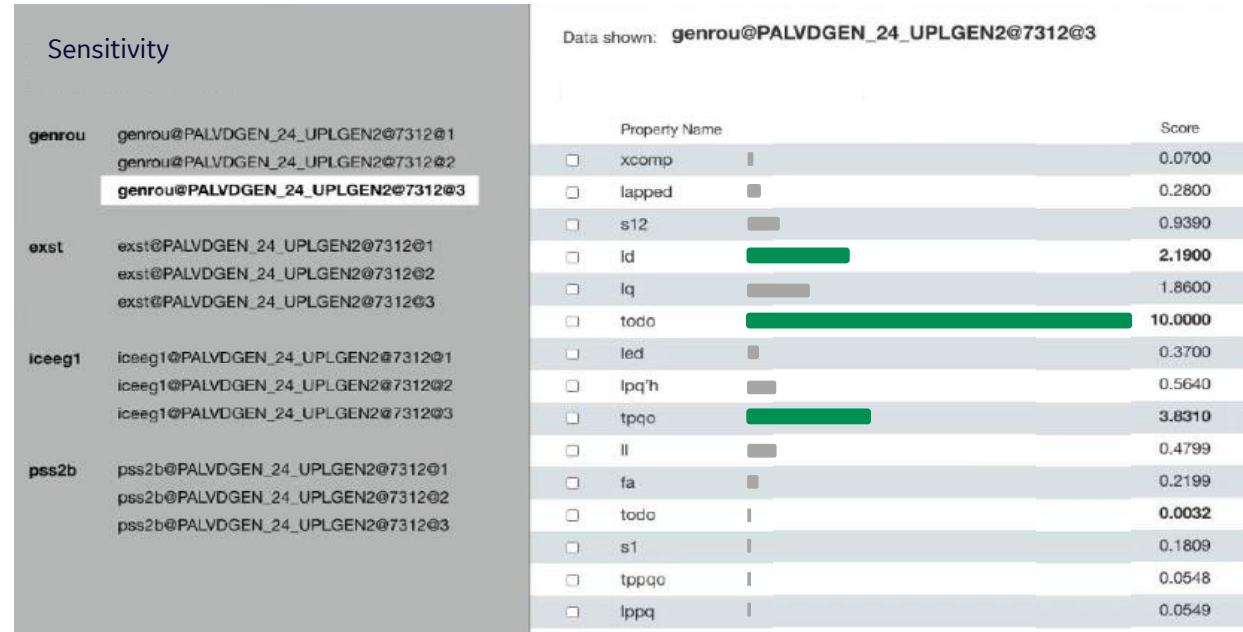
Stage I: Sensitivity Analysis

Determine most identifiable set of parameters across all events

- Jacobian matrix, $A =$

$$\begin{bmatrix}
 \frac{\partial P(t_1)}{\partial \theta_1} & \frac{\partial P(t_1)}{\partial \theta_2} & \dots & \frac{\partial P(t_1)}{\partial \theta_k} \\
 \frac{\partial P(t_2)}{\partial \theta_1} & \frac{\partial P(t_2)}{\partial \theta_2} & \dots & \frac{\partial P(t_2)}{\partial \theta_k} \\
 \vdots & \vdots & \ddots & \vdots \\
 \frac{\partial P(t_N)}{\partial \theta_1} & \frac{\partial P(t_N)}{\partial \theta_2} & \dots & \frac{\partial P(t_N)}{\partial \theta_k} \\
 \frac{\partial Q(t_1)}{\partial \theta_1} & \frac{\partial Q(t_1)}{\partial \theta_2} & \dots & \frac{\partial Q(t_1)}{\partial \theta_k} \\
 \frac{\partial Q(t_2)}{\partial \theta_1} & \frac{\partial Q(t_2)}{\partial \theta_2} & \dots & \frac{\partial Q(t_2)}{\partial \theta_k} \\
 \vdots & \vdots & \ddots & \vdots \\
 \frac{\partial Q(t_N)}{\partial \theta_1} & \frac{\partial Q(t_N)}{\partial \theta_2} & \dots & \frac{\partial Q(t_N)}{\partial \theta_k}
 \end{bmatrix}$$

- Rank deficiency of A can result from:
 - very small entries in columns of A
 - columns of A being nearly linearly dependent



Stage II -Multi-Event Calibration

Performance (in r.m.s. terms) of events calibrated for only one event (in corresponding column) evaluated against all other events (listed in the rows). It shows the generator parameters tuned by single event could not explain other event very well.

Models and data sets obtained via NASPI-NERC model verification workshop, 2016*

2 orders of magnitude reduction from initial error
1 order of magnitude reduction from initial error
reduction from initial error
Increase from initial error

Event no.		True set	Def	Tuned for event 1	Tuned for event 2	Tuned for event 3	Tuned for event 4	Tuned for event 5	Tuned for event 6	Tuned for event 7	Tuned for event 8	Tuned for event 9	Tuned for event 10	Tuned for event 11	Tuned for event 12
1	Perr rms	0.19	2.80	2.33	3.06	1.83	3.36	49.35	52.00	49.04	47.79	49.51	5.78	49.93	2.00
2		0.28	1.34	2.14	0.28	0.98	2.81	2.09	0.50	0.31	0.68	2.37	0.64	5.15	1.03
3		0.03	1.23	1.07	2.31	1.00	1.55	27.93	28.24	27.76	12.05	28.08	3.23	28.07	1.12
4		0.35	2.64	2.73	2.13	1.90	3.16	35.59	41.91	33.80	34.07	35.23	2.03	36.46	2.34
5		4.15	3.10	4.44	3.07	4.20	5.21	0.76	8.07	1.38	5.03	0.62	6.48	1.02	4.00
6		0.29	1.56	2.27	0.29	1.10	2.92	3.40	0.55	0.38	0.46	2.59	0.62	6.54	1.15
7		20.49	14.68	24.23	16.28	23.15	30.12	4.06	3.17	2.73	26.27	7.14	37.09	14.11	20.27
8		0.03	0.99	1.02	1.62	0.88	1.45	18.19	18.39	18.07	1.08	18.37	2.58	18.42	0.91
9		1.14	4.82	5.56	0.75	2.69	6.60	20.02	18.78	15.99	16.52	19.47	1.65	21.76	3.30
10		0.24	1.12	1.45	0.22	0.65	1.74	1.95	5.69	0.99	0.45	1.51	0.49	2.15	0.86
11		0.01	0.27	0.29	0.32	0.23	0.88	1.85	5.63	2.25	0.39	0.36	0.49	2.09	0.35
12		0.02	0.62	0.54	0.85	0.51	0.80	12.39	12.43	12.23	0.88	0.84	2.01	12.41	0.51

* Courtesy: Dr. Ryan Quint, NERC



Multi-event Calibration-Preliminary Results

2 orders of magnitude reduction from initial error
1 order of magnitude reduction from initial error
reduction from initial error
Increase from initial error

Obvious solution: run calibration simultaneously on all events of interest strung together but this comes at the cost of computational expense and engineering involved in enabling running a batch of events simultaneously.

Our solution: carry some essential information from the earlier calibrations runs and guide the subsequent calibration run that helps explain the new disturbance without losing earlier calibration matches.

Performance of estimates from the sequential estimation approach for the gas plant case shows the proposed approach effectively reduce the overall error across all events.

Event no.		True set	Def	Sequential, forgetting factor = 1e-2	Sequential without prior weight
1	Perr rms	0.19	2.80	1.02	0.38
2		0.28	1.34	0.32	0.25
3		0.03	1.23	0.58	0.37
4		0.35	2.64	1.00	0.35
5		4.15	3.10	3.81	3.72
6		0.29	1.56	0.35	0.30
7		20.49	14.68	19.39	19.25
8		0.03	0.99	0.47	0.18
9		1.14	4.82	1.17	0.83
10		0.24	1.12	0.27	0.29
11		0.01	0.27	0.10	0.04
12		0.02	0.62	0.29	0.08
1	Qerr rms	0.21	1197.90	2.71	0.91
2		0.04	60.99	0.29	0.03
3		0.22	995.61	3.25	0.69
4		0.46	1370.90	27.41	10.48
5		0.13	215.22	1.24	0.38
6		0.03	41.74	0.54	0.10
7		0.92	1856.30	9.45	0.69
8		0.26	668.64	3.18	0.38
9		0.43	2613.00	304.42	6.79
10		0.07	57.92	5.16	0.81
11		0.05	63.22	0.93	0.15
12		0.12	474.97	0.18	0.08
	delta p 2-norm			12.2178	15.9934
	delta p inf-norm			9.2333	14.402



Implementation & Demonstration



Software Implementation-Generality & Robustness

- **Dynamic simulation engine**

- ✓ GE's PSLF
- ✓ PowerTech's TSAT

- **System Configuration**

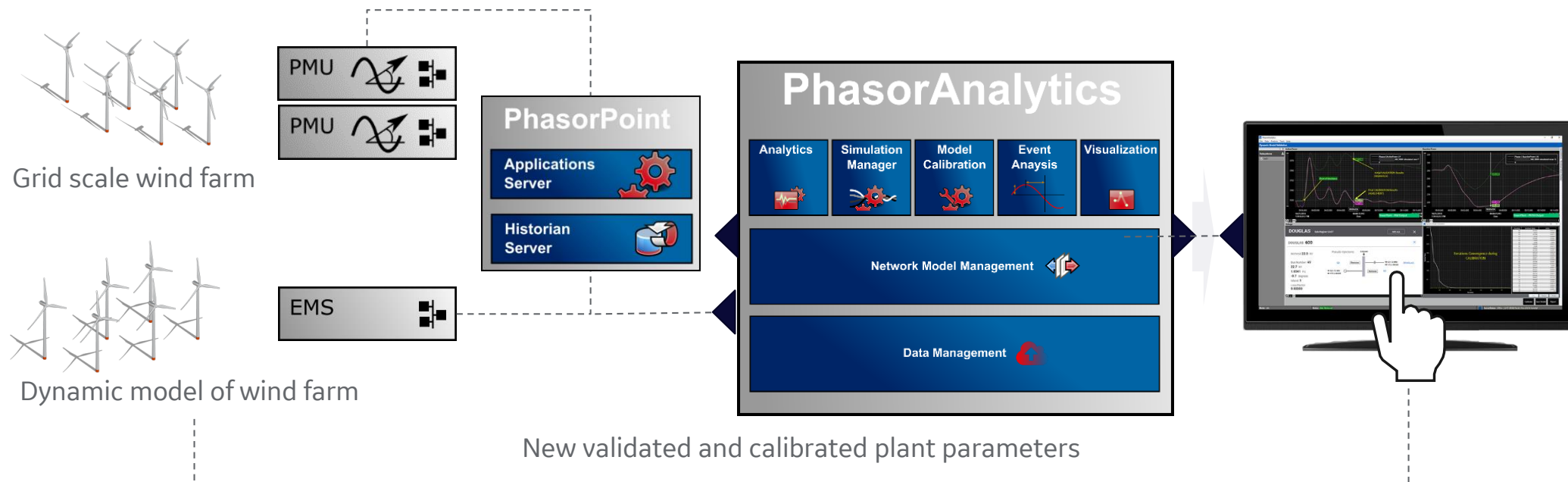
- ✓ PMU at POI
- ✓ PMU at Generator Terminal

- **Steady state & Dynamic model**

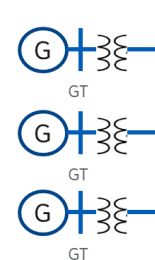
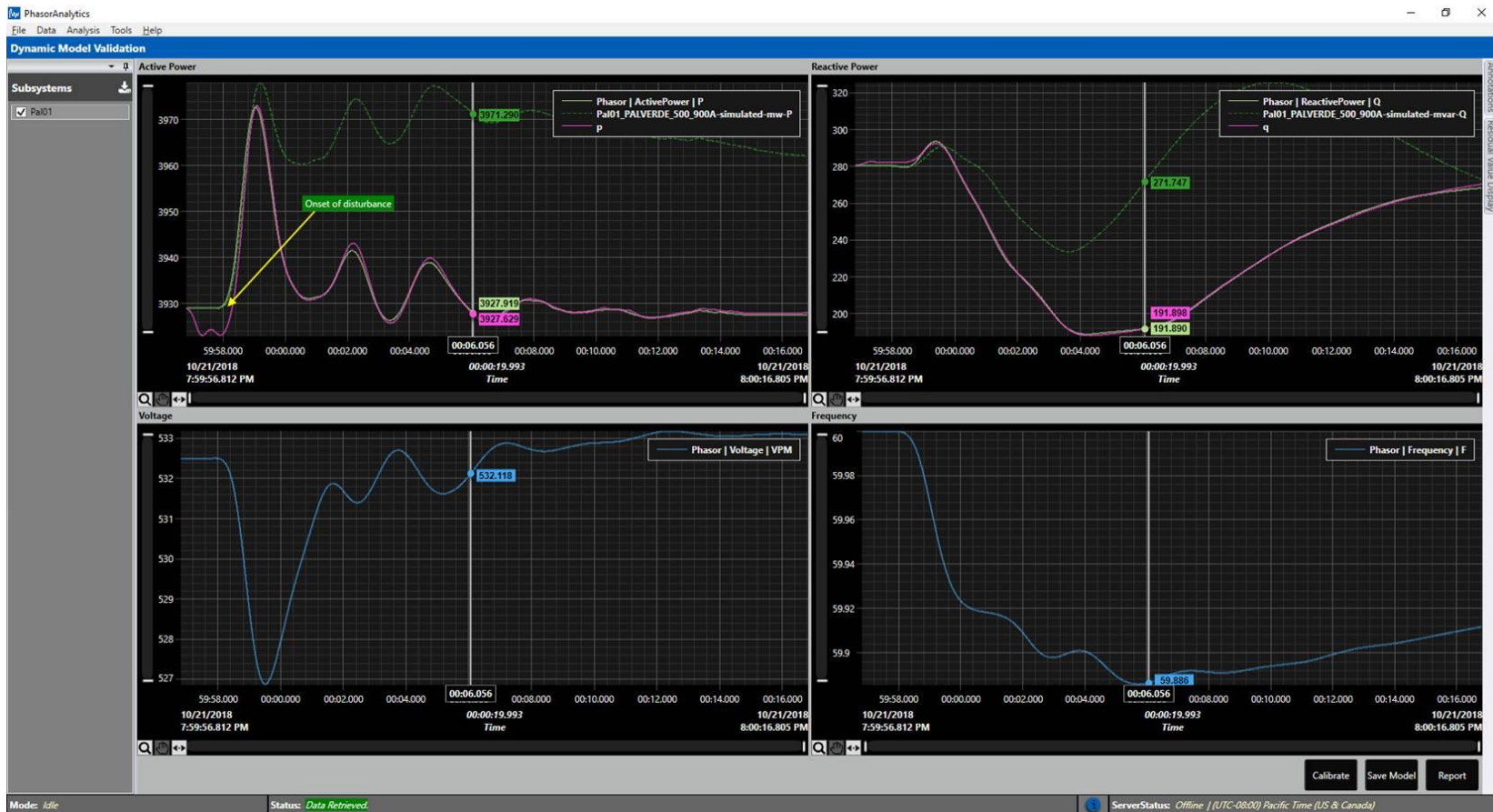
- ✓ EMS-operational model
- ✓ System planning model

- **Phasor Data**

- ✓ e-terraphasorpoint/openPDC/openHistorian
- ✓ JSIS CSV files/COMTRADE files/PI historian

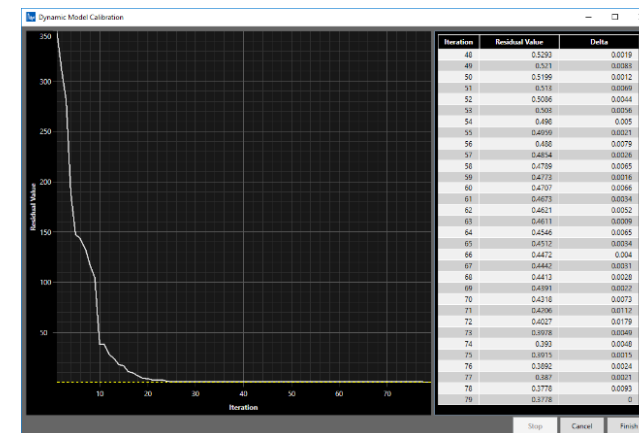


Demonstration Using US WECC Model



Units operational
 1 × 1311 MW
 1 × 1314 MW
 1 × 1312 MW

Units cancelled
 2 × 1270 MW
 Thermal capacity
 3 × 3990 MW_{th}



* Note: Synthesized PMU data using Dynamic Model

Courtesy WECC

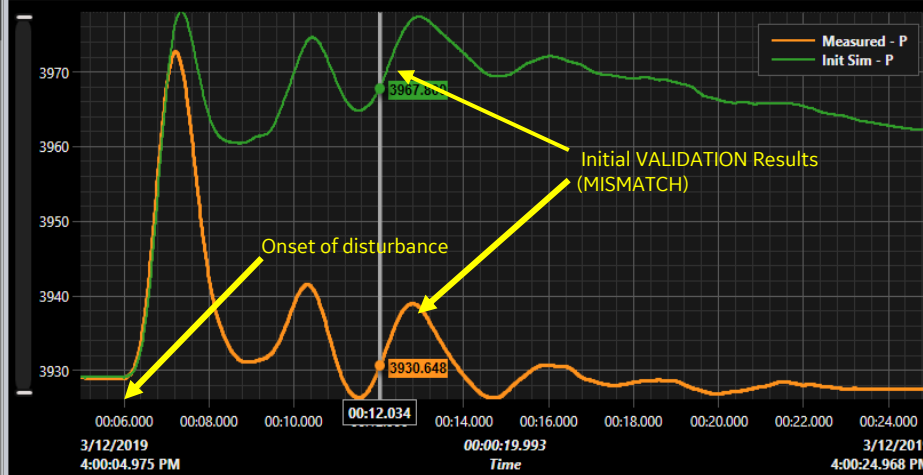


Dynamic Model Validation

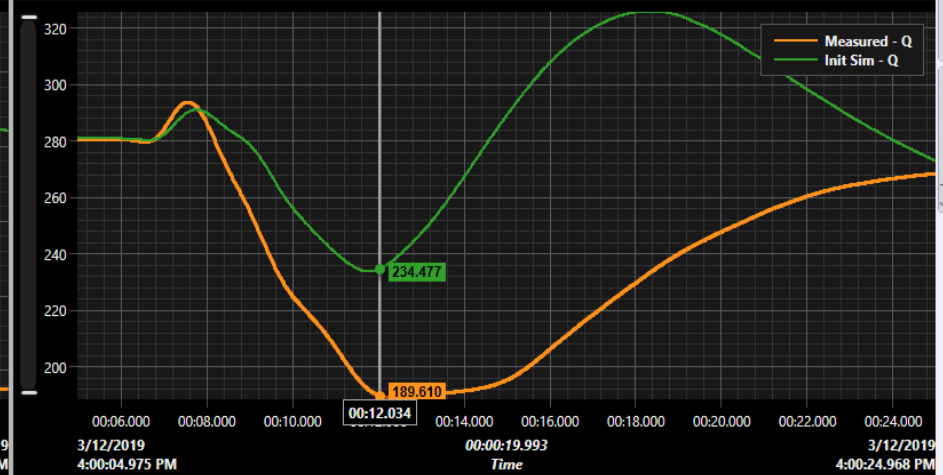
Subsystems

PALOV1

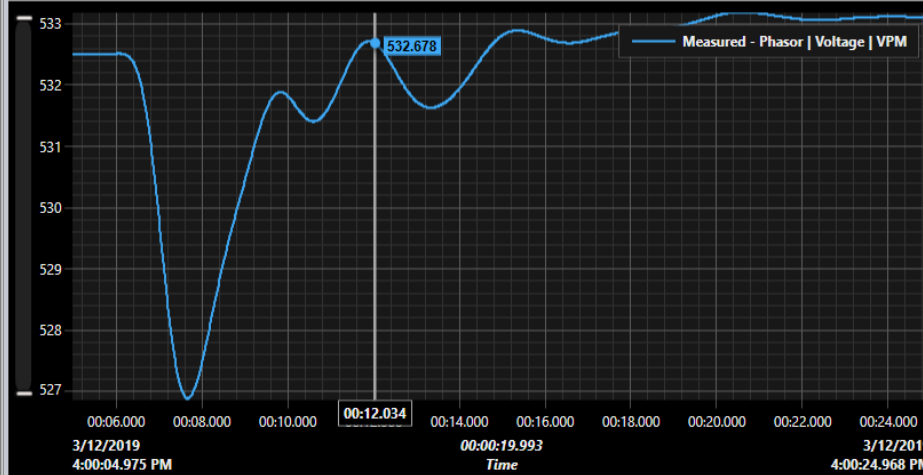
Active Power



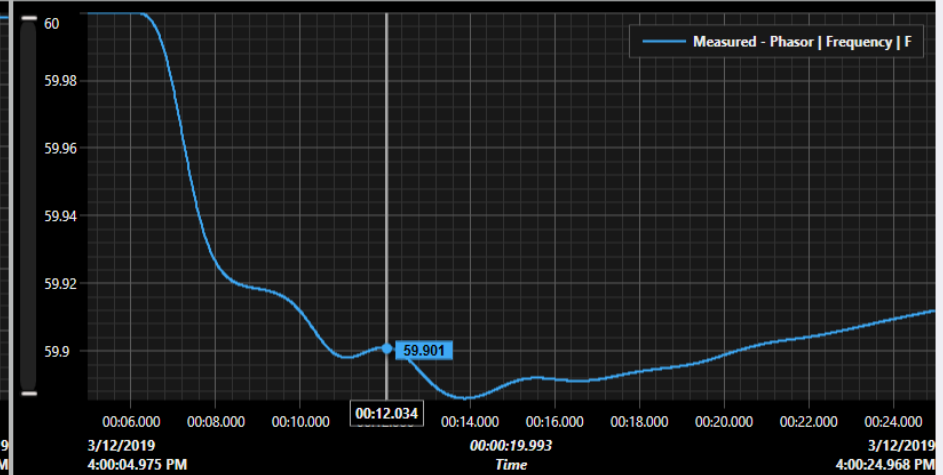
Reactive Power



Voltage



Frequency



Calibrate Save Model Report

Mode: Idle

Status: Data Retrieved.

ServerStatus: Offline | (UTC-08:00) Pacific Time (US & Canada)



Parameter Selection

Select Tunable Parameters

Calibration

Select parameters to calibrate

PALVDGEN_24_UPLGEN3

- genrou (10)
- wscst (7)
- exst3a (7)
- ieeeg1 (3)

PALVDGEN_24_UPLGEN2

- pss2b (12)
- genrou (6)
- ieeeg1 (3)
- exst4b (2)

PALVDGEN_24_UPLGEN1

- pss2b (13)
- genrou (6)
- ieeeg1 (3)
- exst4b (2)

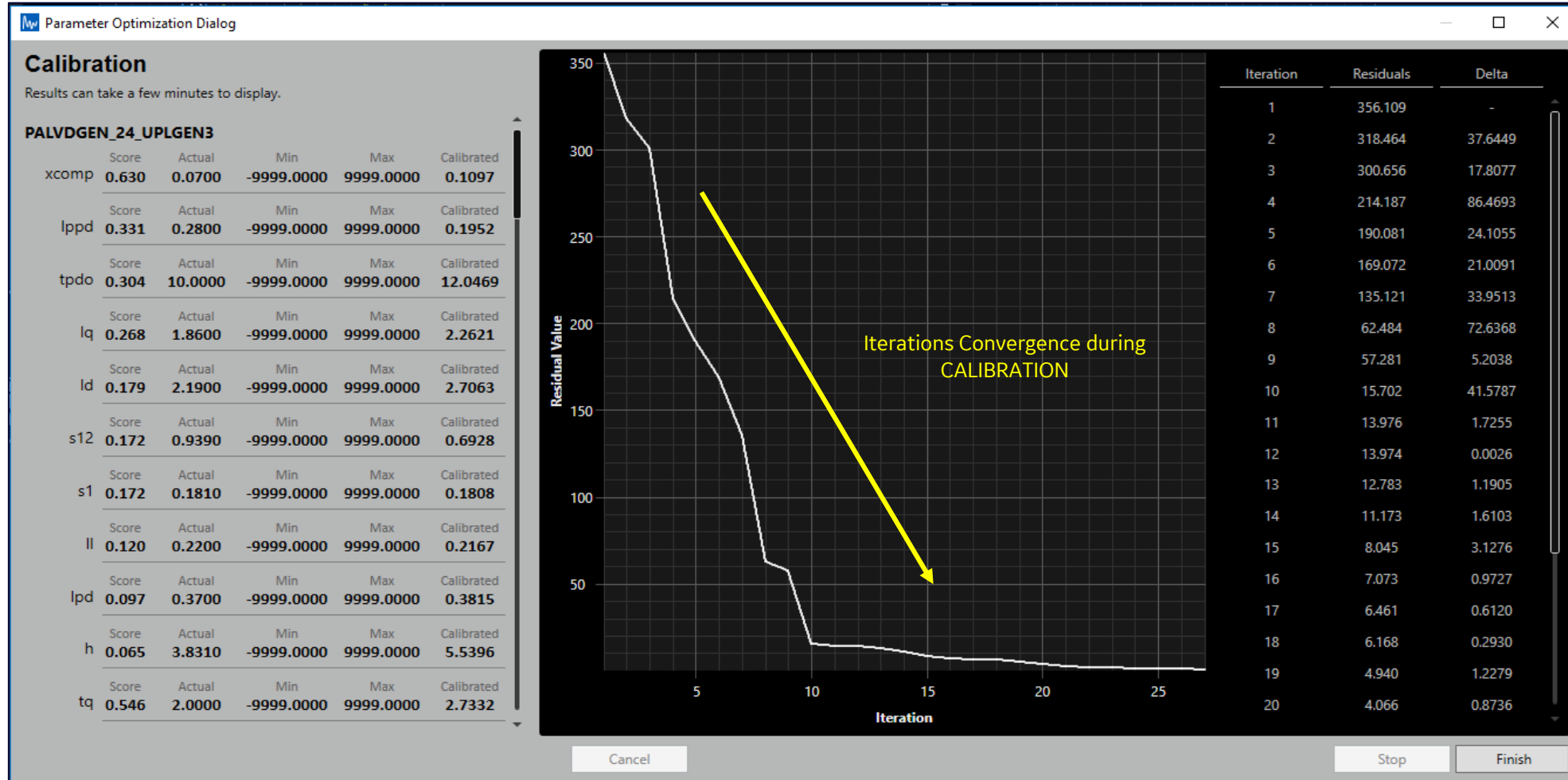
Parameters for : **genrou@PALVDGEN_24_UPLGEN3@7313@3**

User sensitivity score to identify most sensitive parameters. Use min, max values to specify limits

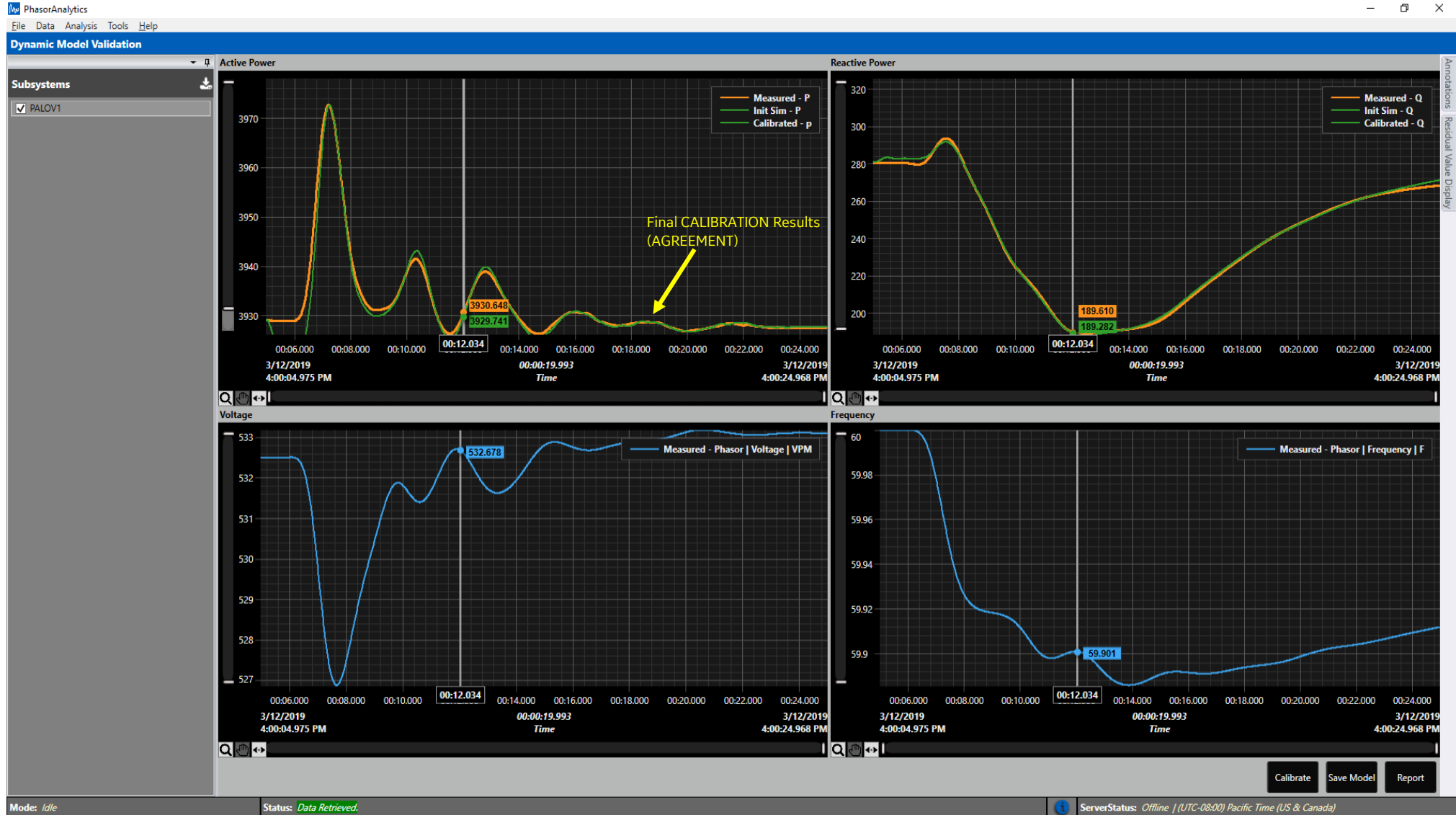
Property Name	Score	Actual Value	Min Value	Max Value
<input checked="" type="checkbox"/> xcomp	0.6297	0.0700	-9999.0000	9999.0000
<input checked="" type="checkbox"/> lppd	0.3308	0.2800	-9999.0000	9999.0000
<input checked="" type="checkbox"/> tpdo	0.3040	10.0000	-9999.0000	9999.0000
<input checked="" type="checkbox"/> lq	0.2679	1.8600	-9999.0000	9999.0000
<input checked="" type="checkbox"/> ld	0.1787	2.1900	-9999.0000	9999.0000
<input checked="" type="checkbox"/> s12	0.1725	0.9390	-9999.0000	9999.0000
<input checked="" type="checkbox"/> s1	0.1717	0.1810	-9999.0000	9999.0000
<input checked="" type="checkbox"/> ll	0.1205	0.2200	-9999.0000	9999.0000
<input checked="" type="checkbox"/> lpd	0.0967	0.3700	-9999.0000	9999.0000
<input checked="" type="checkbox"/> h	0.0648	3.8310	-9999.0000	9999.0000
<input type="checkbox"/> lpq	0.0283	0.5640		
<input type="checkbox"/> tppdo	0.0277	0.0330		
<input type="checkbox"/> tpqo	0.0276	0.4800		
<input type="checkbox"/> tppqo	0.0095	0.0550		
<input type="checkbox"/> ra	0.0042	0.0036		
<input type="checkbox"/> lppq	0.0000	0.2800		



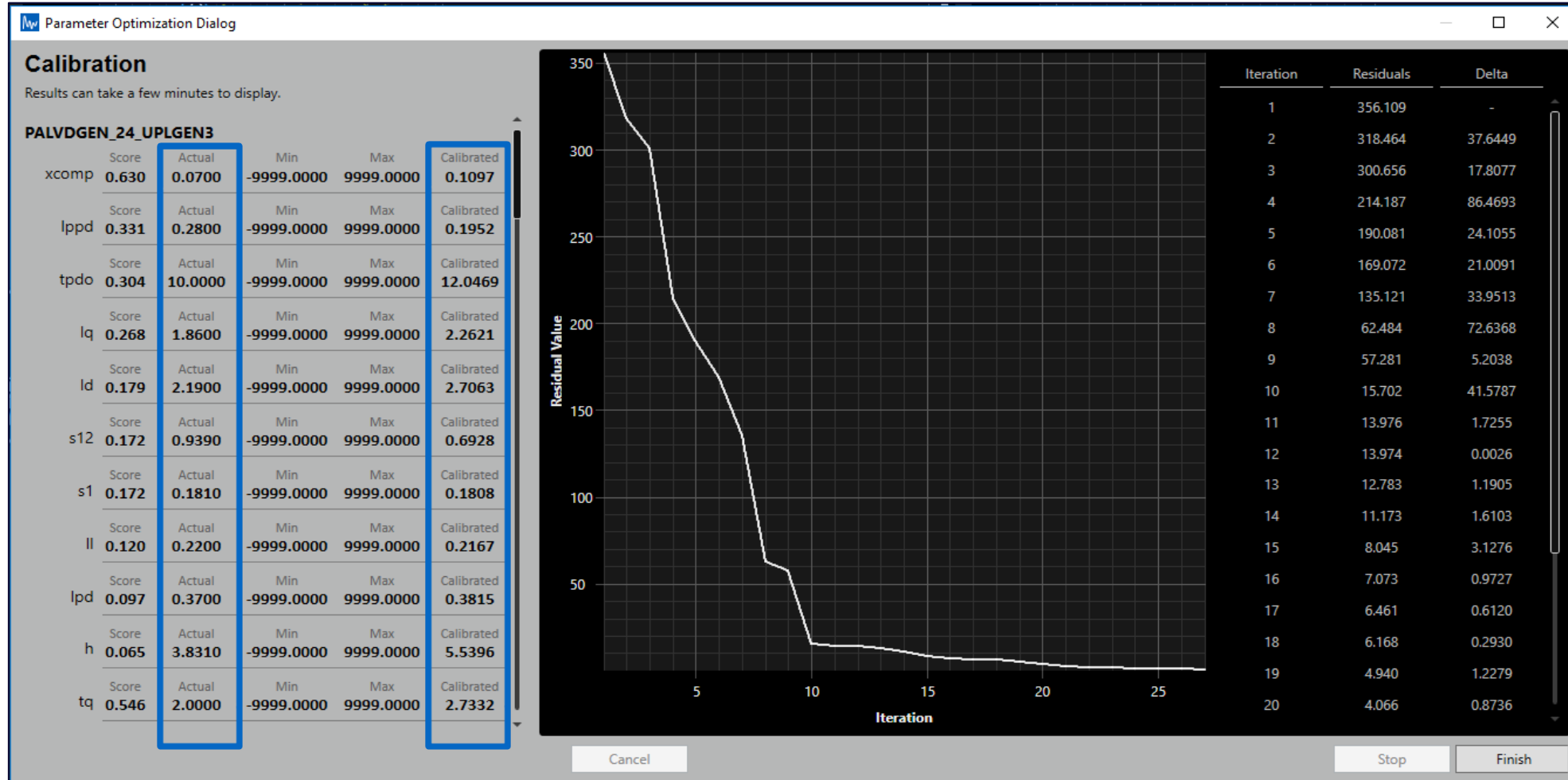
Calibration - Progress



Calibration - Results



Calibrated Parameters

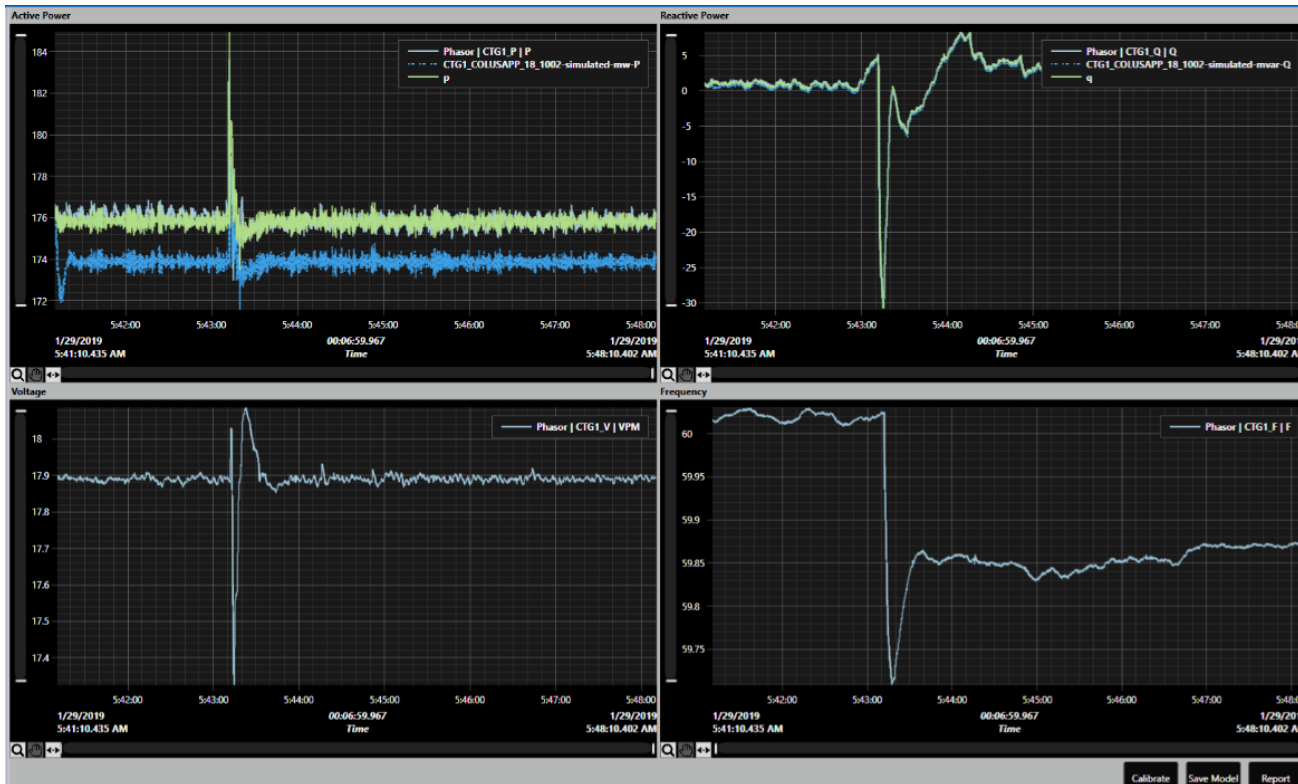


Original **Actual**
Parameters

Final **Calibrated**
Parameters



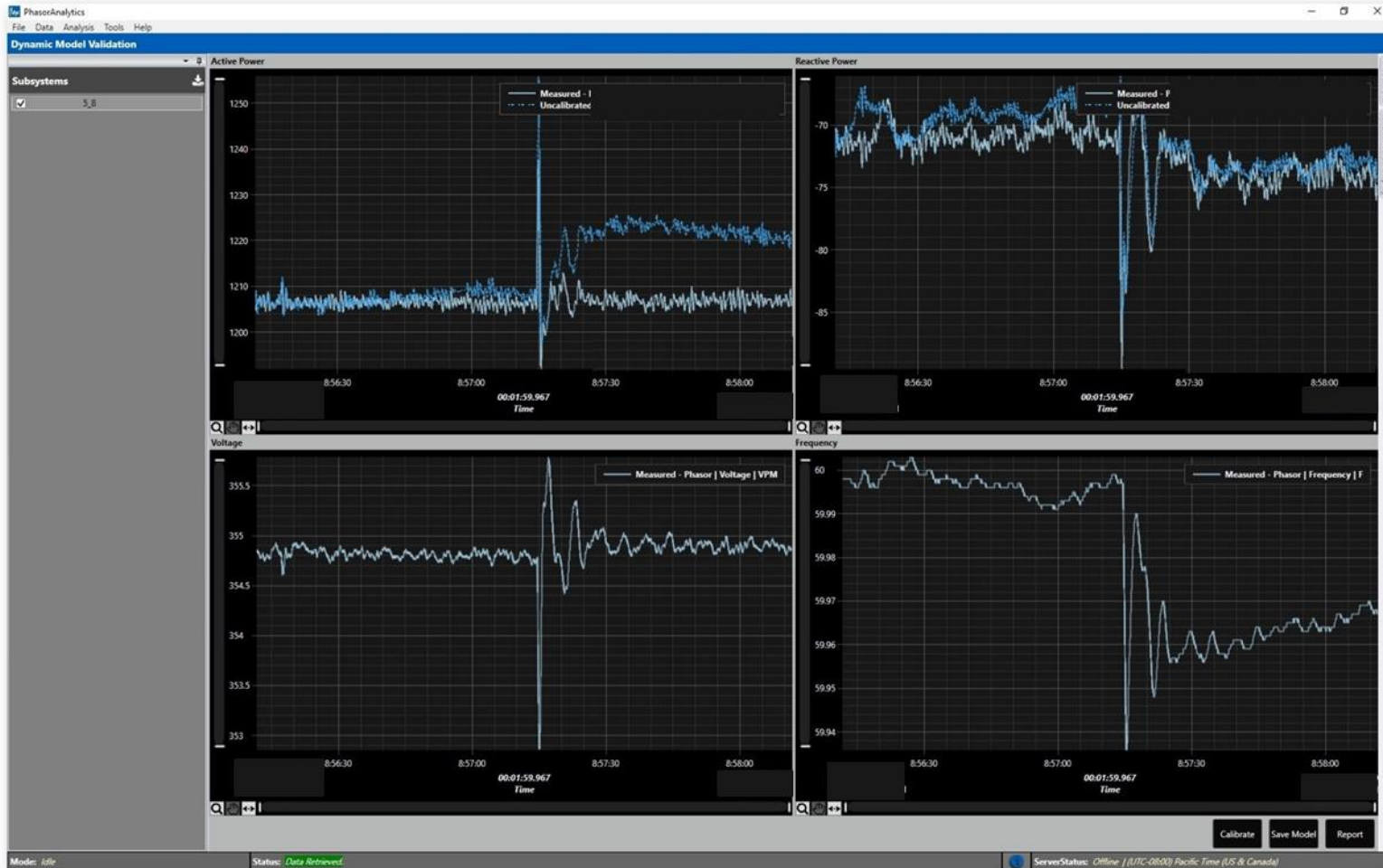
PG&E test case



- 1040 Pacific DC Intertie rate of change activated . Plant info: GE's 2 GT and 1 ST, GE's Generators and GE's Excitation system EX2100. Siemens' three step-up Xfmrs.
- Both PSLF and TSAT has to add an impedance to handle PMU located at generator terminal.
- Identified need to define the high/low bounds of parameter before calibration.



ISO-NE test case



- MV&C using TSAT engine is being verified using a Power plant under ISO-NE foot print
- Dynamics observed is because of another generator trip nearby
- Mismatch observed is mainly in the active power
- Makes a case for tuning governor control



Conclusion

- **Lesson learned and new feature for production grade MVC software**
- **A sequential estimation approach designed and verified using multiple event data**
- **Model Validation and Calibration software tested using field data from PG&E and ISO-NE**

Next Step

- Validate multi-event calibration approach against real test data
- Model Calibration field tests at PG&E and ISO-NE, June
- DOE Peer Review, June 12-13, Washington DC



Presentations/Publications

1. IEEE PES Innovative Smart Grid Technologies (ISGT) Conference, February 2018 – **Presented paper** on model parameter identifiability analysis titled, “Synchrophasor based dynamic model validation leveraging multiple events”
2. i-PCGRID Workshop, March 2018 – **Presentation** on synchrophasor applications being developed on this project
3. NASPI Work Group Meeting, April 2018 – **Presentation** on Fast Voltage Stability Assessment algorithm
4. GE Grid Solutions User Group Meeting, June 2018 – **Presentation** on synchrophasor applications being developed on this project
5. IEEE PES General Meeting, August 2018 – **Presented paper** on the developed model validation/calibration algorithm titled, “Towards a commercial-grade tool for disturbance-based model validation and calibration.”
6. NASPI Work Group Meeting, October 2018 – **Presentation** on model validation/calibration algorithm integration into the PhasorAnalytics with a live demonstration.



Thanks the team!



Carol Painter: DOE Project Officer
Phil Overholt: DOE program mgr.
Jeff Dagle: Technical advisor from PNNL



Honggang Wang: PI
Alex Santos: Contract manager
Na Jing: Financial Analyst

Developers

Utility Partners



Lead FAT and field demos, Develop model cal., AGM and operator guidance software tools; Model val./cal. platform integration of PSLF & TSAT with WAMS product

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Russ Frizzell-Carlton
Vijay Sukhavasi



Development of model calibration techniques, angle-based grid management, factory acceptance testing

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Jovan Bebic
Chaitanya Baone
Anup Menon
Naresh Acharya
Yan Pan



Model validation/ calibration platform integration of PSLF with WAMS product

Haris Ribic
Juan Sanchez-Gasca
Brian Thomas
 Develop APIs to enable Communication between WAMS product and PSLF



Model validation/ calibration platform integration of TSAT with WAMS product, assist with AGM

George Zhang
 Develop APIs to enable Communication between WAMS product and PSLF



Provide cost share, test data and models, assist/host applications in QA environment, Field tests

Keith Mitchell
 Field demo for AGM and operator guidance.



Provide cost share, test data and models, assist/host applications in QA environment, Field tests

Sherman Chen
 Field demo for Model Validation/ Calibration tool.



Provide feedback on developed Applications

Xiaochuan Luo
Frankie Zhang
 Field demo for Model Validation/ Calibration tool.



Provide feedback on developed Applications

Hongming Zhang
Alex Ning
 Technical advisor

