

# **NIST 2013 Assessment of PMU Performance**

## **(a work in progress)**

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# 2012/2013 PMU performance testing

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- In support of continuing development of IEEE PMU performance standards, NIST sent requests to all PMU vendors to provide a sample of their PMU to be tested against the new IEEE Std. C37.118.1-2011 requirements.
  - 12 vendors responded by sending either production or prototype (pre-production) PMUs for analysis.
  - Vendors will not be identified here or in the final report.
  - Test data is given to the vendors as it becomes available.

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  - 12 vendors responded by sending either production or prototype (pre-production) PMUs for analysis.
  - Vendors will not be identified here or in the final report.
  - Test data is given to the vendors as it becomes available.
- This project allows for:
  - Understanding the PMU test requirements and limits compared to the performance of actual PMUs.
  - Continued development and refinement of the PMU test equipment at NIST.
  - Continued development and refinement of the PMUs themselves since test results are provided to the individual vendors as it becomes available.

# Early results

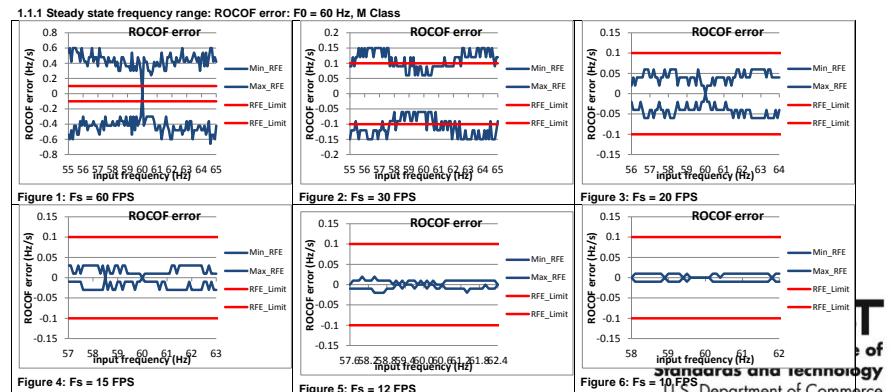
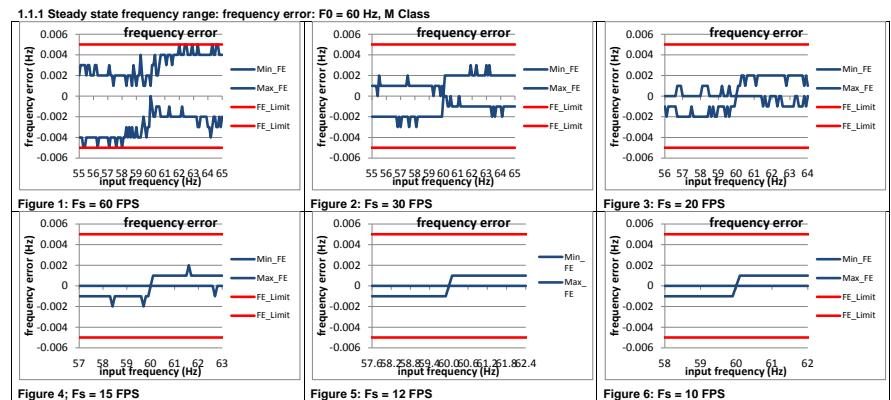
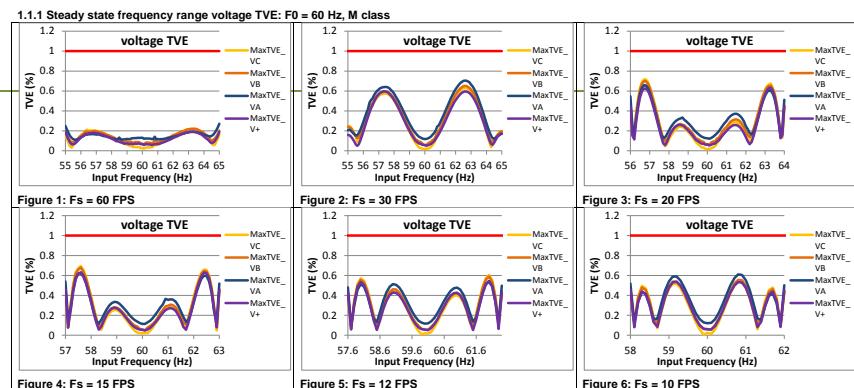
- None of the PMUs tested were able to pass all the test limits of IEEE Std C37.118.1-2011.
- Detailed results (numerical and graphical) was shared with the IEEE PSRC H11 committee members, authors of the PMU performance standard.
  - Helped the committee determine that an amendment was needed.
  - Helped the committee determine some details of the amendments themselves.
- Some vendors provided revised firmware for re-testing.

Table 1: Steady state frequency range test results

Fs (FPS)	10M			10P			12M			12P			15M			15P			20M			20P			30M			30P			60M			60P		
Test	T	F	R	T	F	R	T	F	R	T	F	R	T	F	R	T	F	R	T	F	R	T	F	R	T	F	R	T	F	R						
	V	E	F	V	E	F	V	E	F	V	E	F	V	E	F	V	E	F	V	E	F	V	E	F	V	E	F	V	E	F						
	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E	E						
C37.118.1 Annex C	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P	P						
PMU A	P	P	F				P	P	F		P	P	F		P	P	F		P	P	F		P	P	F	P	F	P	F	F						
PMU B	P	P	F	P	P	F				P	P	F		P	P	F		P	P	F		P	P	F	P	P	F	P	P	F						
PMU C	P	F	F																							F	F	F		P	F	F				
PMU D	P	P	P	P	P	P	F	P	P		F	P	P		F	P	P	P	F	F	P	P		F	P	P	P	P	P	P						
PMU E	P	P	F							P	P	F		P	P	F		P	P	F		P	P	F	P	P	F	P								
PMU F	P	P	F										P	P	F										P	P	F									
PMU G	P	P	P				P	P	P		P	P	P		I	P	P		F	P	P	P														

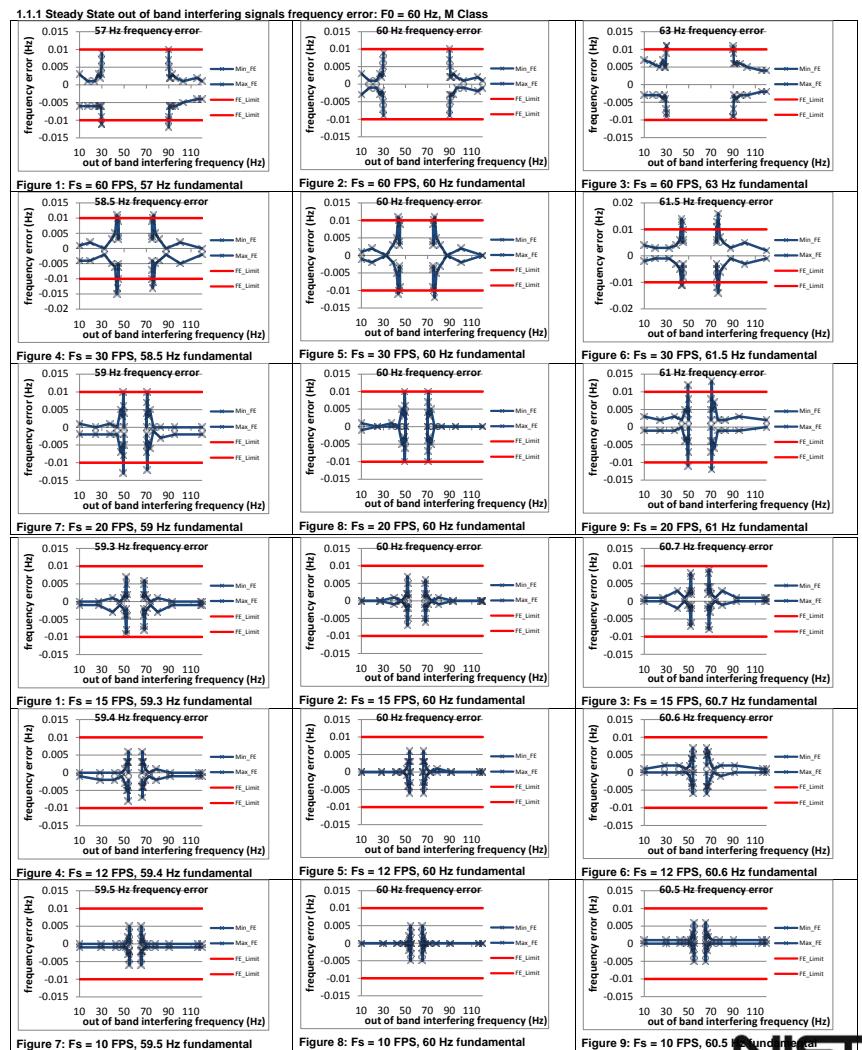
# PC37.118.1a Amendment

- All PMUs are now being re-tested against the draft amendment IEEE draft PC 37.118.1a
  - Some results are improved due to some relaxed requirements
  - Some PMU vendors have revised firmware based on the amendment and are now passing or close to passing the amended standard
  - Most PMU vendors still need to make revisions in order to pass the amended requirements



# The tests and some example results

- This is NOT a presentation of the final results of the survey
  - The survey is still in progress
  - Some tests are still being developed, refined, and calibrated
    - » Calibration is the measurement of the test's uncertainty
- The survey represents the results from over 80,000 individual tests (estimated)



# Steady State Tests

## Frequency Range

1.1.1 Annex C steady state frequency range voltage TVE: F0 = 60 Hz, M class

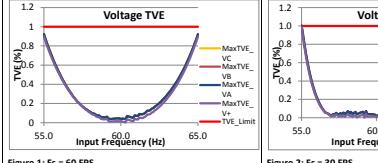


Figure 1: Fs = 60 FPS

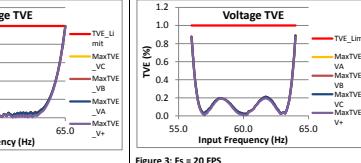


Figure 2: Fs = 30 FPS

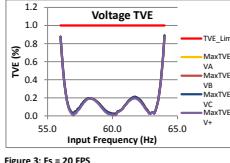


Figure 3: Fs = 20 FPS

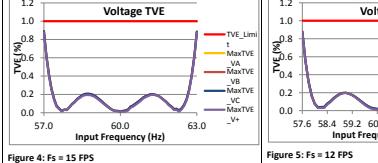


Figure 4: Fs = 15 FPS

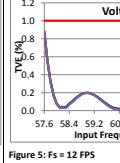


Figure 5: Fs = 12 FPS

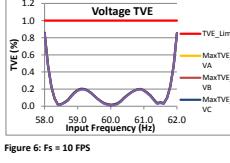


Figure 6: Fs = 10 FPS

1.1.1 PMU A steady state frequency range frequency error: F0 = 60 Hz, M class

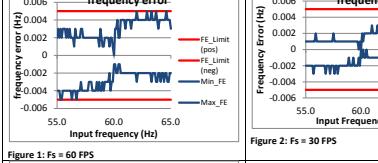


Figure 1: Fs = 60 FPS

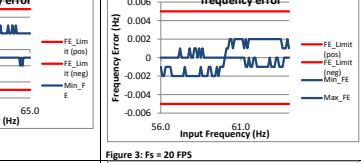


Figure 2: Fs = 30 FPS

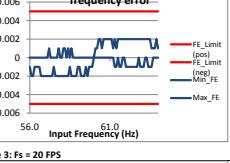


Figure 3: Fs = 20 FPS

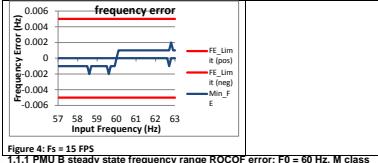


Figure 4: Fs = 15 FPS



Figure 5: Fs = 10 FPS

1.1.1 PMU B steady state frequency range ROCOF error: F0 = 60 Hz, M class

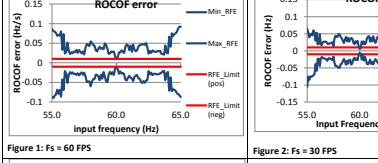


Figure 1: Fs = 60 FPS

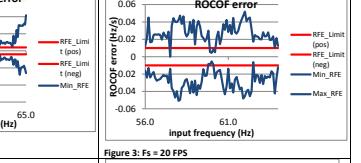


Figure 2: Fs = 30 FPS

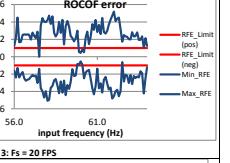


Figure 3: Fs = 20 FPS

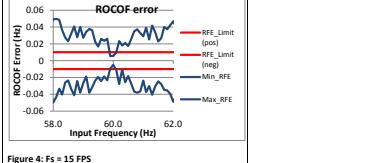


Figure 4: Fs = 15 FPS



Figure 5: Fs = 10 FPS

## Harmonics

1.1.1 Steady state harmonic distortion voltage TVE: F0 = 60 Hz, M class

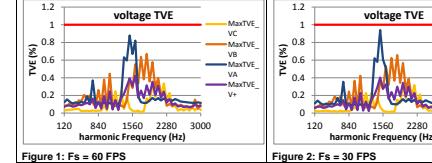


Figure 1: Fs = 60 FPS

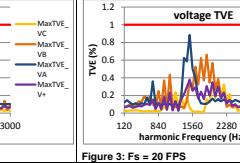


Figure 2: Fs = 30 FPS



Figure 3: Fs = 20 FPS

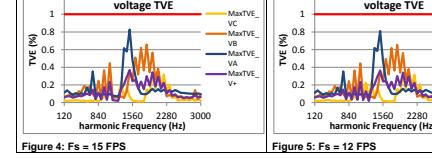


Figure 4: Fs = 15 FPS

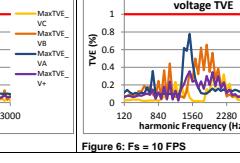


Figure 5: Fs = 12 FPS

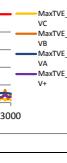


Figure 6: Fs = 10 FPS

1.1.1 Steady state harmonic distortion: frequency error: F0 = 60 Hz, M Class

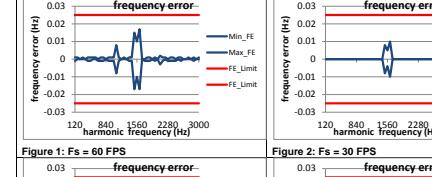


Figure 1: Fs = 60 FPS

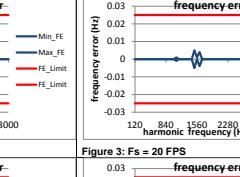


Figure 2: Fs = 30 FPS

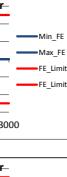


Figure 3: Fs = 20 FPS

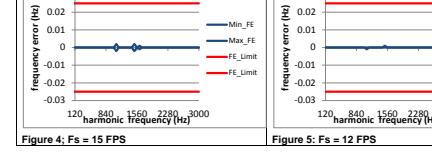


Figure 4: Fs = 15 FPS

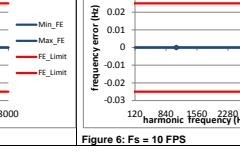


Figure 5: Fs = 12 FPS



Figure 6: Fs = 10 FPS

1.1.1 Steady state harmonic distortion: ROCOF error: F0 = 60 Hz, M Class\*

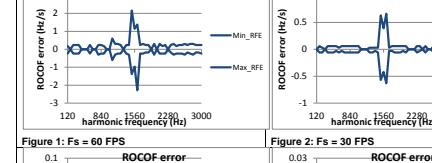


Figure 1: Fs = 60 FPS

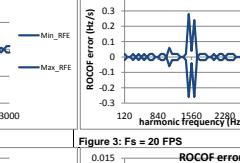


Figure 2: Fs = 30 FPS



Figure 3: Fs = 20 FPS

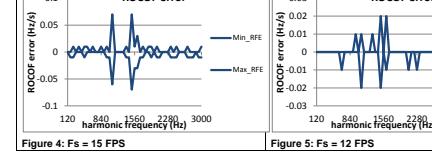


Figure 4: Fs = 15 FPS

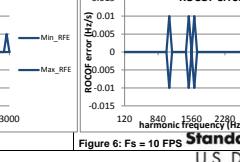


Figure 5: Fs = 12 FPS



Figure 6: Fs = 10 FPS

# Steady State Tests

## Interfering signals

1.1.1 Steady State out of band interfering signals current TVE:  $f_0 = 60$  Hz, M Class

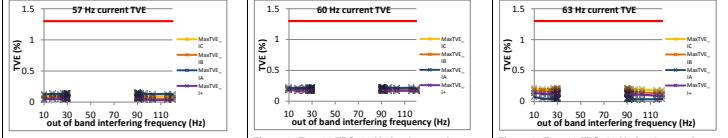


Figure 4:  $f_s = 30$  FPS, 58.5 Hz fundamental

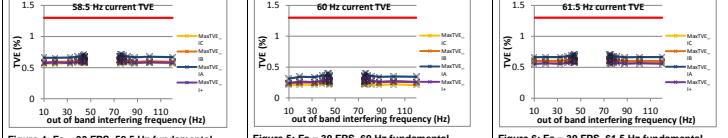


Figure 7:  $f_s = 20$  FPS, 59 Hz fundamental

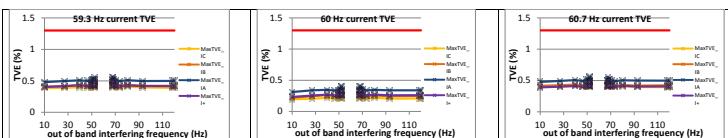
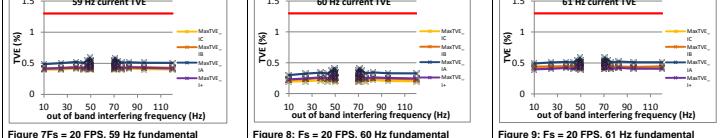


Figure 4:  $f_s = 12$  FPS, 59.4 Hz fundamental

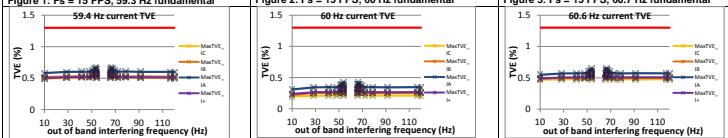
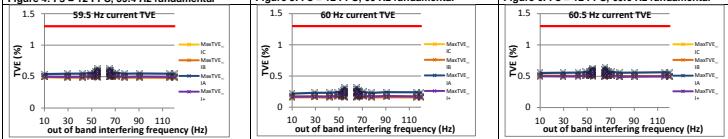


Figure 7:  $f_s = 10$  FPS, 59.5 Hz fundamental



## Magnitude

- All PMUs pass the steady state signal magnitude test
  - No plots were created

(note, there are no frequency error or rate of change of frequency error limits for the steady state magnitude test)

# Dynamic Tests

## Measurement Bandwidth (modulation)

1.1.1 Dynamic phase modulation voltage TVE:  $F_0 = 60$  Hz, M class

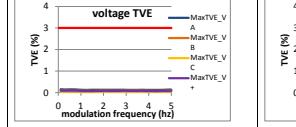


Figure 1:  $F_s = 60$  FPS

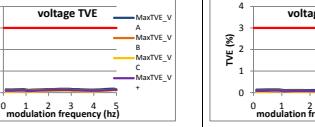


Figure 2:  $F_s = 30$  FPS

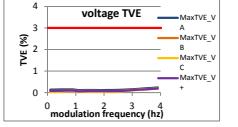


Figure 3:  $F_s = 20$  FPS

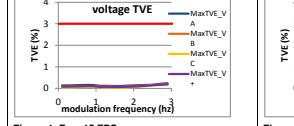


Figure 4:  $F_s = 15$  FPS

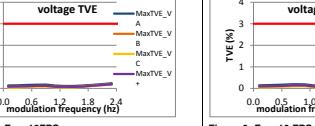


Figure 5:  $F_s = 12$  FPS

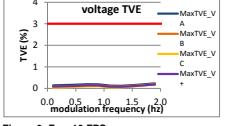


Figure 6:  $F_s = 10$  FPS

1.1.1 Dynamic phase modulation frequency error:  $F_0 = 60$  Hz, M class

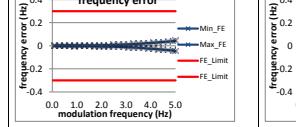


Figure 1:  $F_s = 60$  FPS

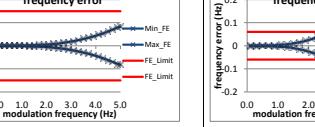


Figure 2:  $F_s = 30$  FPS

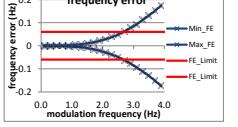


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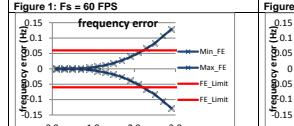


Figure 4:  $F_s = 15$  FPS

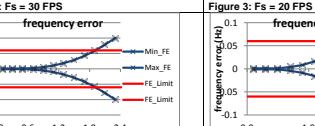


Figure 5:  $F_s = 12$  FPS

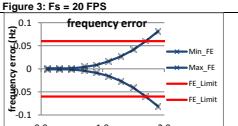


Figure 6:  $F_s = 10$  FPS

1.1.1 Dynamic phase modulation ROCOF error:  $F_0 = 60$  Hz, M class

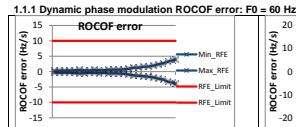


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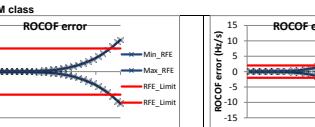


Figure 2:  $F_s = 30$  FPS

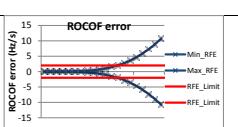


Figure 3:  $F_s = 20$  FPS

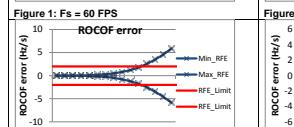


Figure 4:  $F_s = 15$  FPS

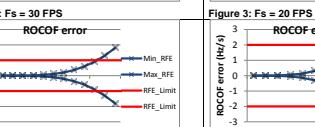


Figure 5:  $F_s = 12$  FPS

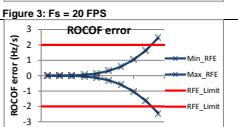


Figure 6:  $F_s = 10$  FPS

## Ramp

1.1.1 Dynamic ramp of system frequency voltage TVE:  $F_0 = 60$  Hz, M Class

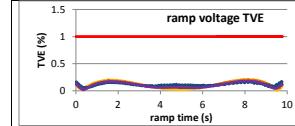


Figure 1:  $F_s = 60$  FPS, ramp from 55 Hz to 65 Hz at +1 Hz/s

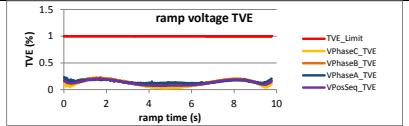


Figure 2:  $F_s = 60$  FPS, ramp from 65 Hz to 55 Hz at -1 Hz/s

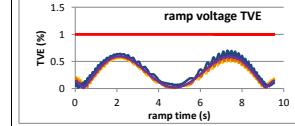


Figure 3:  $F_s = 30$  FPS, ramp from 55 Hz to 65 Hz at +1 Hz/s

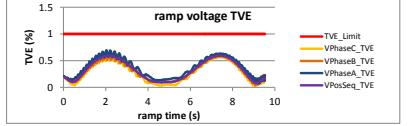


Figure 4:  $F_s = 30$  FPS, ramp from 65 Hz to 55 Hz at -1 Hz/s

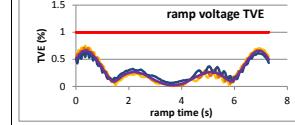


Figure 5:  $F_s = 20$  FPS, ramp from 56 Hz to 64 Hz at +1 Hz/s

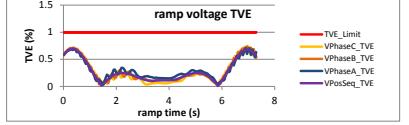


Figure 6:  $F_s = 20$  FPS, ramp from 64 Hz to 56 Hz at -1 Hz/s

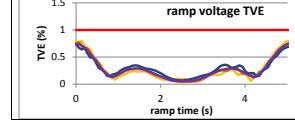


Figure 7:  $F_s = 15$  FPS, ramp from 57 Hz to 63 Hz at +1 Hz/s

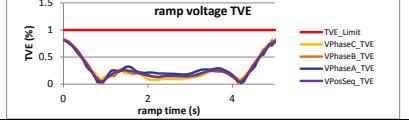


Figure 8:  $F_s = 15$  FPS, ramp from 63 Hz to 57 Hz at -1 Hz/s

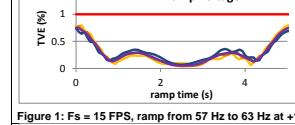


Figure 9:  $F_s = 10$  FPS, ramp from 58.6 Hz to 62.4 Hz at +1 Hz/s

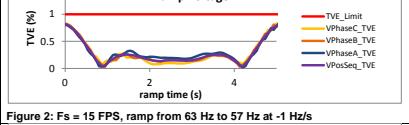


Figure 10:  $F_s = 10$  FPS, ramp from 62.4 Hz to 58.6 Hz at -1 Hz/s

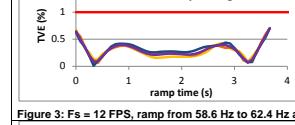


Figure 11:  $F_s = 12$  FPS, ramp from 58 Hz to 62 Hz at +1 Hz/s

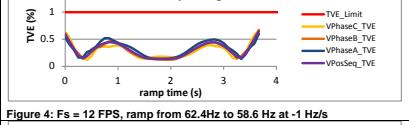


Figure 12:  $F_s = 12$  FPS, ramp from 62 Hz to 58 Hz at -1 Hz/s

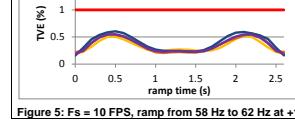


Figure 13:  $F_s = 10$  FPS, ramp from 62 Hz to 58 Hz at -1 Hz/s

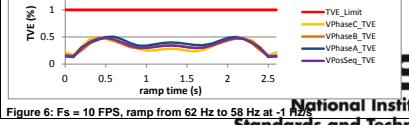


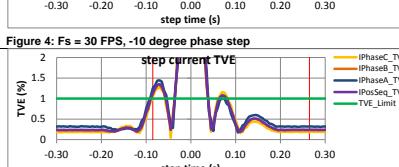
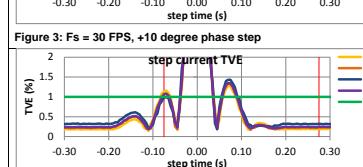
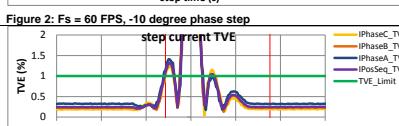
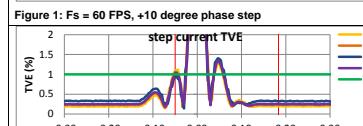
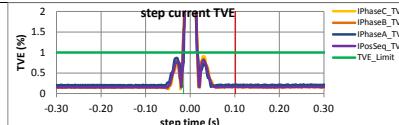
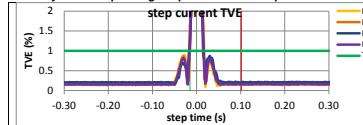
Figure 14:  $F_s = 10$  FPS, ramp from 62 Hz to 58 Hz at -1 Hz/s



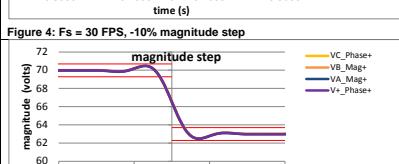
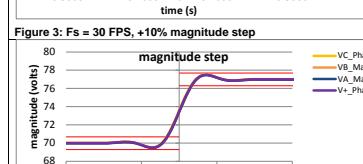
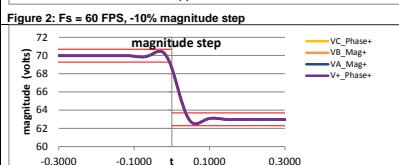
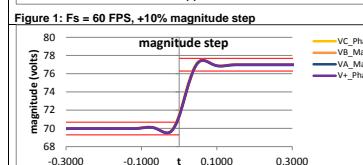
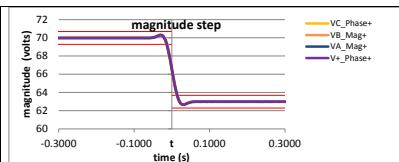
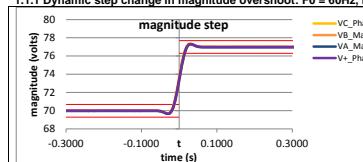
# Dynamic Tests

## Step

### 1.1.1 Dynamic step change in phase current response time: F0 = 60 Hz, P Class



### 1.1.1 Dynamic step change in magnitude overshoot: F0 = 60Hz, M class



## Measurement Latency

Test is under development

# Thank you

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## Schedule:

- Expected completion of testing:  
January 2014 (+ 3 weeks)
- Expected publication of results as a NIST Interagency Report:  
June 2014
  - NIST IRs are available to the public.

## Questions?

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