



Synchrophasor Technology and Systems

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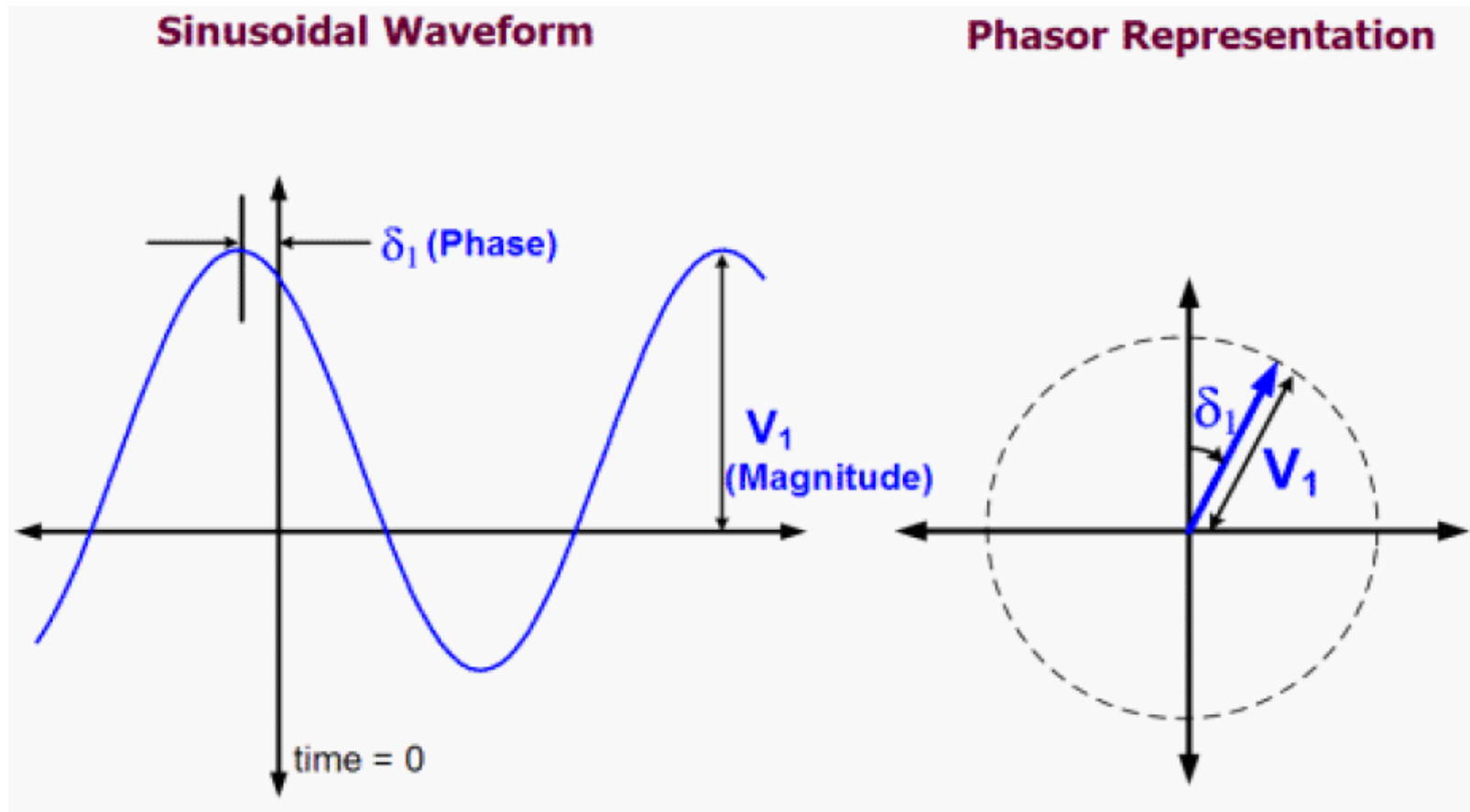
CIGRE-NASPI SYNCHROPHASOR TECHNOLOGY TUTORIAL

Houston, Texas
October 19, 2014

- ▶ Synchronphasor technology and systems (this presentation)
 - Time-synchronized measurements
 - What's a PMU?
 - Data collected by PMUs; PMU v. SCADA
 - PMU data networks -- network, PDC, analytics, gateway
 - PMU deployments across North America
 - Technical standards and protocols
 - Data quality and availability
 - Security and NERC CIP
- ▶ Synchronphasor uses and applications (Dmitry Kosterev)
- ▶ Synchronphasor technology benefits and business case (Matt Gardner)
- ▶ The future of synchronphasor technology (Alison Silverstein)
- ▶ Q&A

What is a “Phasor”?

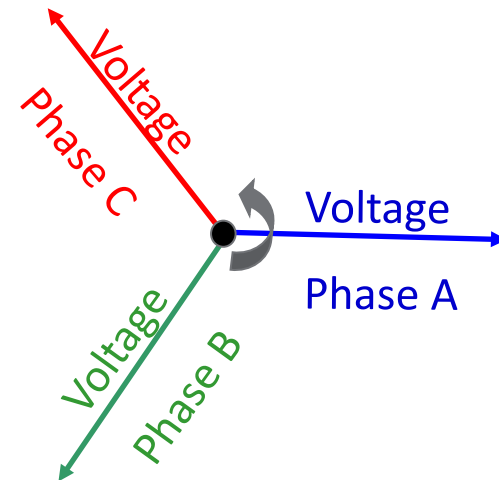
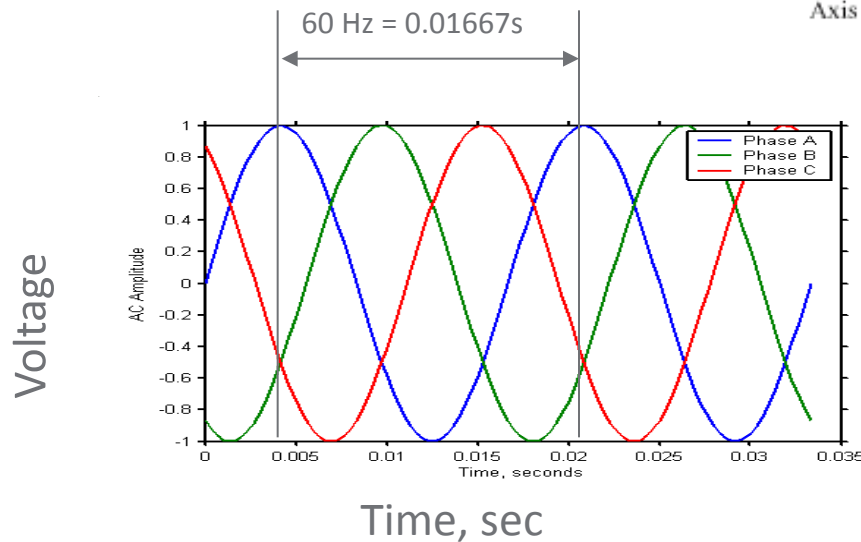
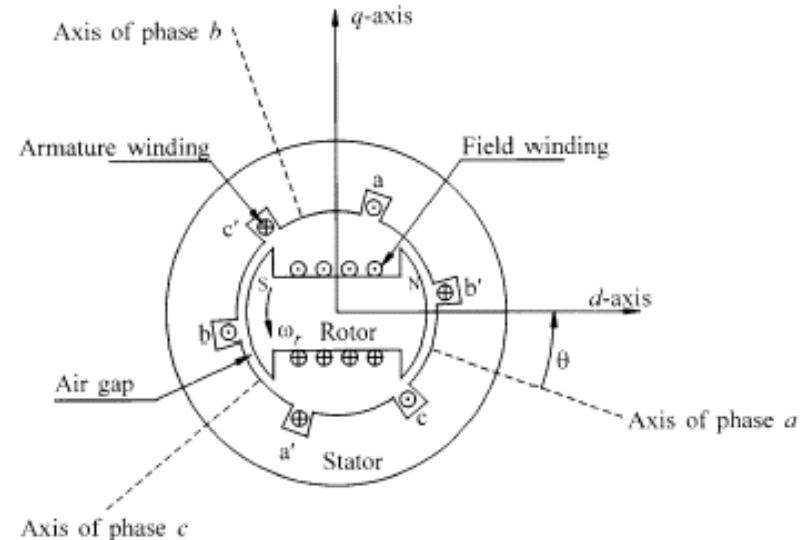
- ▶ Like a vector, a phasor represents both magnitude and relative phase angle



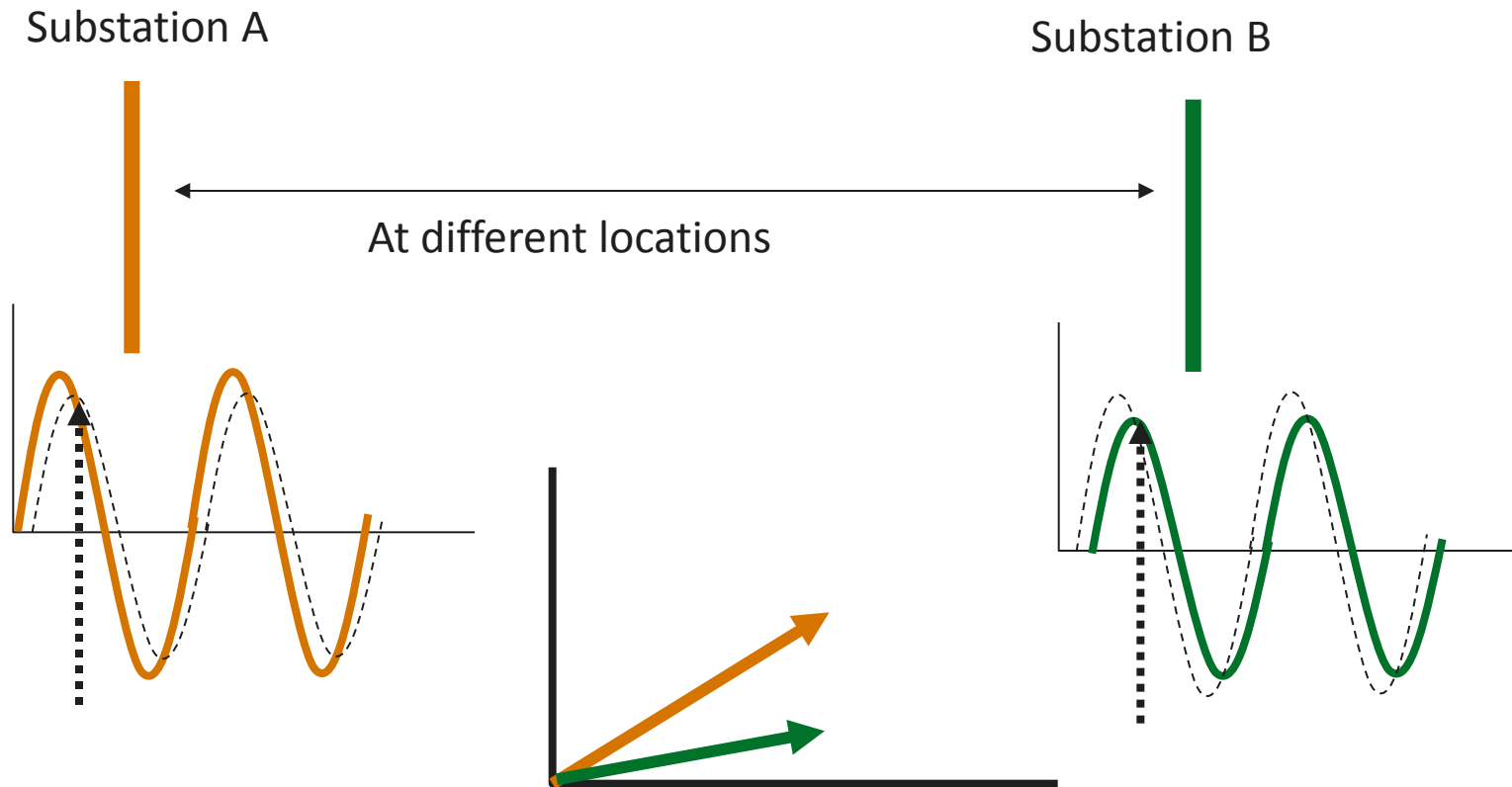
Source: CERTS, Phasor Technology Overview

Conceptual Overview

- ▶ Mathematical concept of physical quantities
- ▶ Phasors rotate counterclockwise, each corresponding to a sinusoidal parameter
- ▶ The rotating frame of reference can be modified (e.g., relative phase angle)



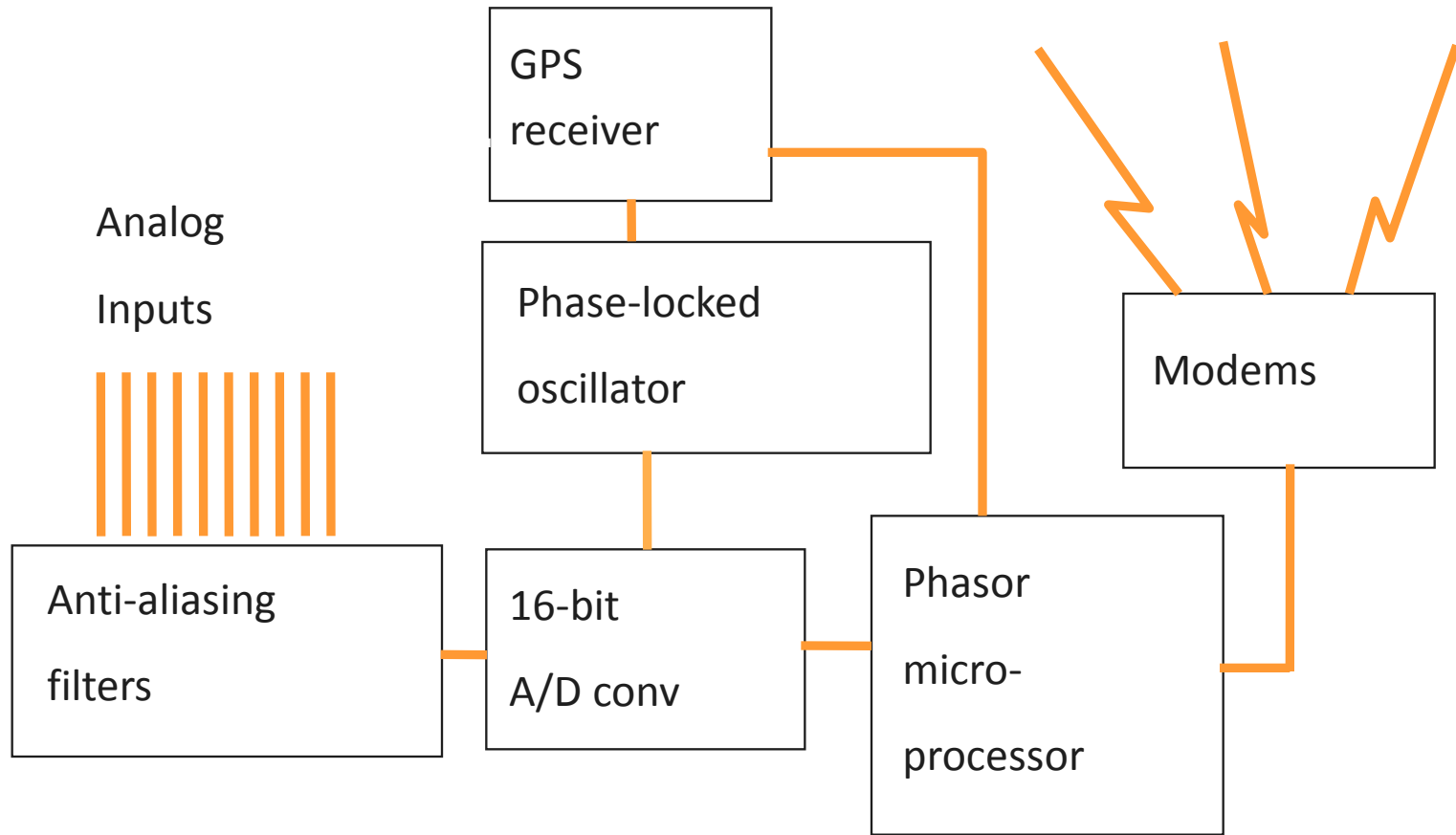
Time Synchronized Measurements



By synchronizing the sampling processes for different signals - which may be hundreds of miles apart, it is possible to put their phasors on the same phasor diagram.

Credit: A.G. Phadke

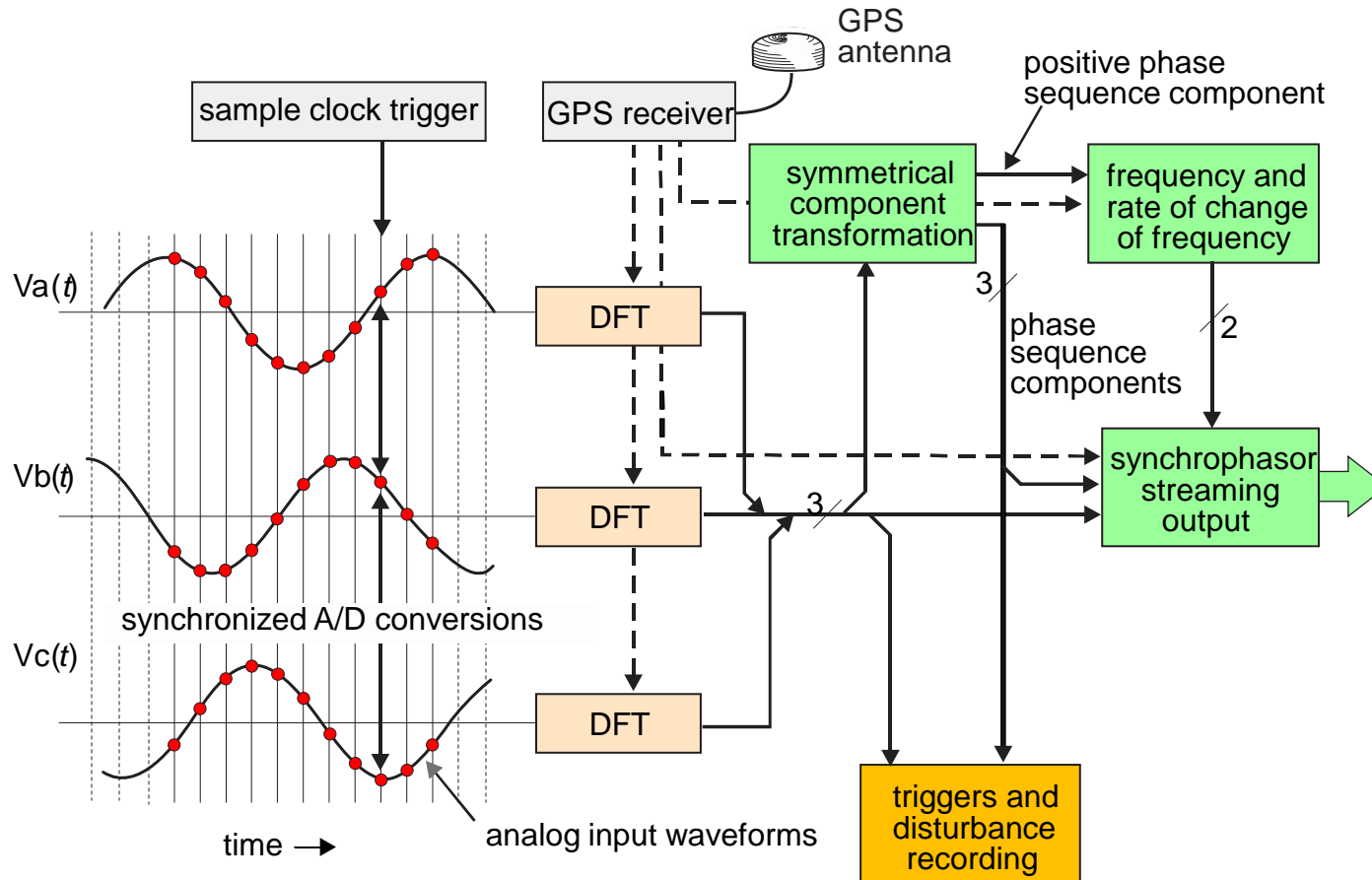
Phasor Measurement Unit



Except for synchronization, the hardware is the same as that of a **digital fault recorder** or a **digital relay**.

Credit: A.G. Phadke

Phasor Measurement Unit



Credit: A.G. Phadke

Wide Area Measurement System Overview



Data Data Data



Phasor Measurement



Global Positioning System

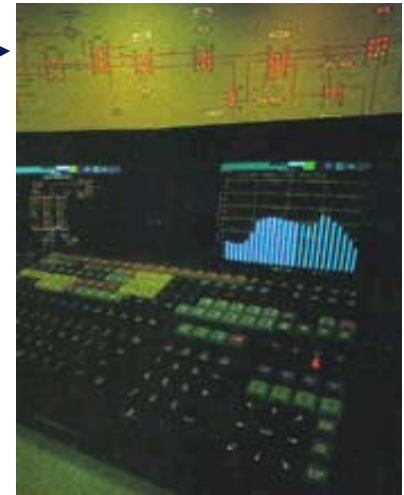
Time-Stamped

Data
Data
Data



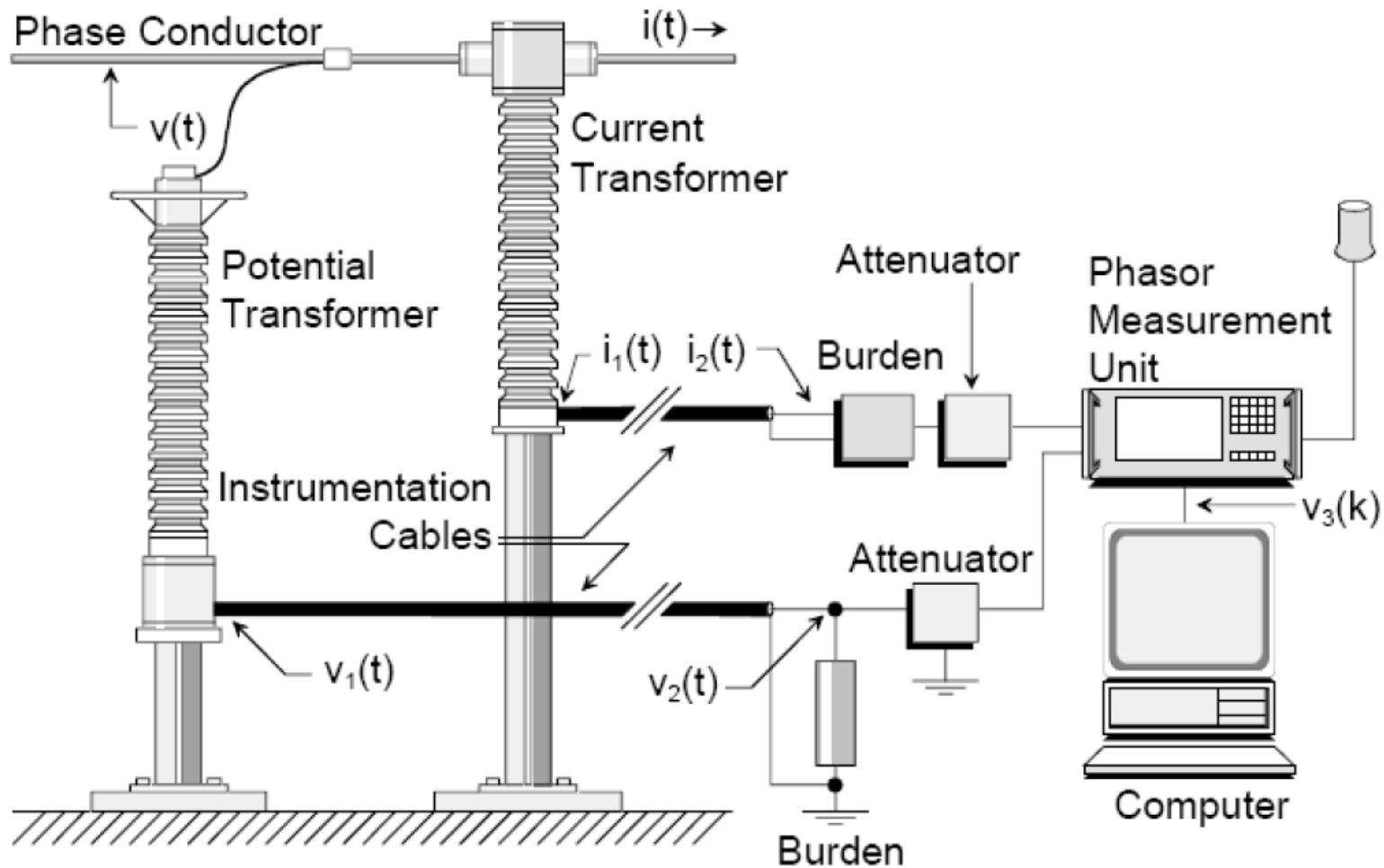
Power System Monitors

Useful Information



Control Center

Substation PMU Installation



Wide Area Measurement System (WAMS)

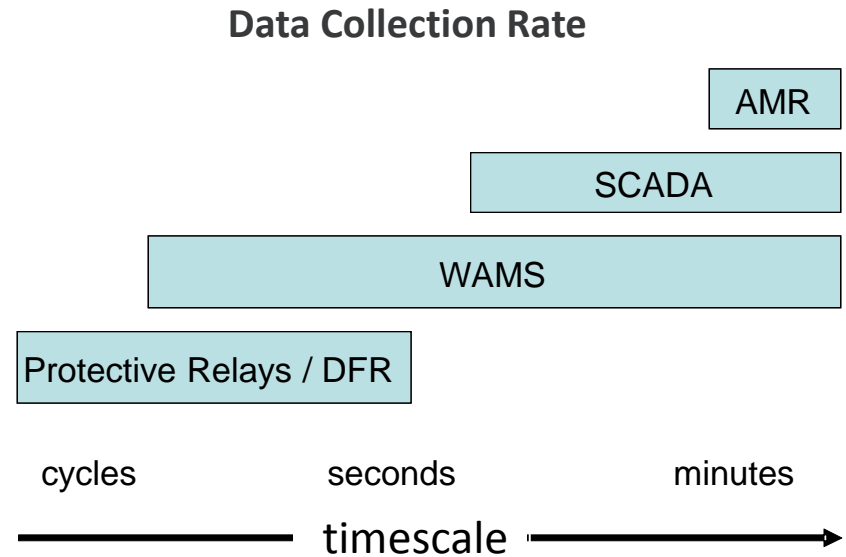
Data acquisition devices (continuously recording and time synchronized)

- ▶ Phasor Measurement Units (PMU)
 - Inputs from potential transformers (PT) and current transformers (CT)
- ▶ Analog signal recorders (with transducer inputs)
- ▶ Point-on-wave (POW) recorders (with PT, CT inputs)
- ▶ Controller monitors (generators, HVDC, FACTS)
 - Inputs from the controller interface or the controlled device
- ▶ Advanced relays and other Intelligent Electronic Devices (IED)
- ▶ Digital fault recorders and other sequence of events recorders

- ▶ What we are covering today is **NOT** supervisory control and data acquisition (SCADA) technology
 - SCADA traditionally relies on a polling style communication architecture
 - Older SCADA protocols do not include time with the data, the time is applied when the data is logged into the energy management system
 - This can sometimes result in significant delay between when the event occurs and when it is time stamped

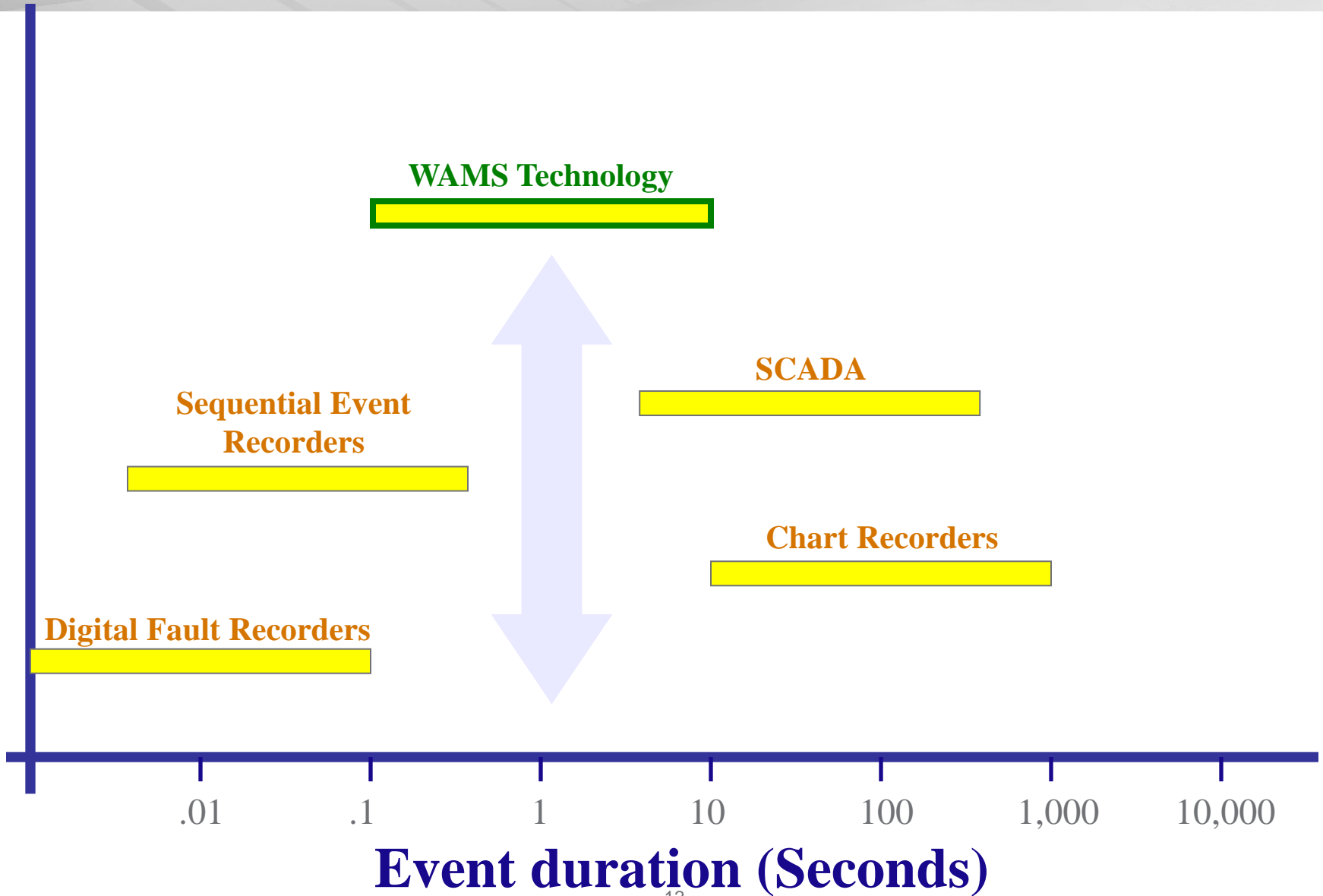
Technology to Meet Emerging Industry Needs

- ▶ WAMS technology is being rapidly deployed by several utilities throughout the world and across North America
- ▶ Both on-line and off-line applications are emerging, particularly those that require faster time synchronized measurements than are available from existing technology
- ▶ The measurement infrastructure is tailored to the requirements of the installation
- ▶ Vendors are providing new solutions including measurement technology, networking, and applications



Time synchronized WAMS data is gathered at sample rates much faster than SCADA systems, and provide the missing link between localized digital fault recorders (DFR) and SCADA systems, which are much slower. However, unlike most SCADA systems, WAMS utilizes Internet protocols to exchange measurement information.

Filling a Measurement Gap

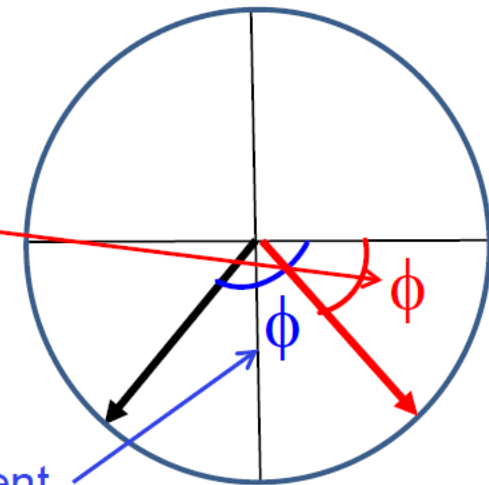
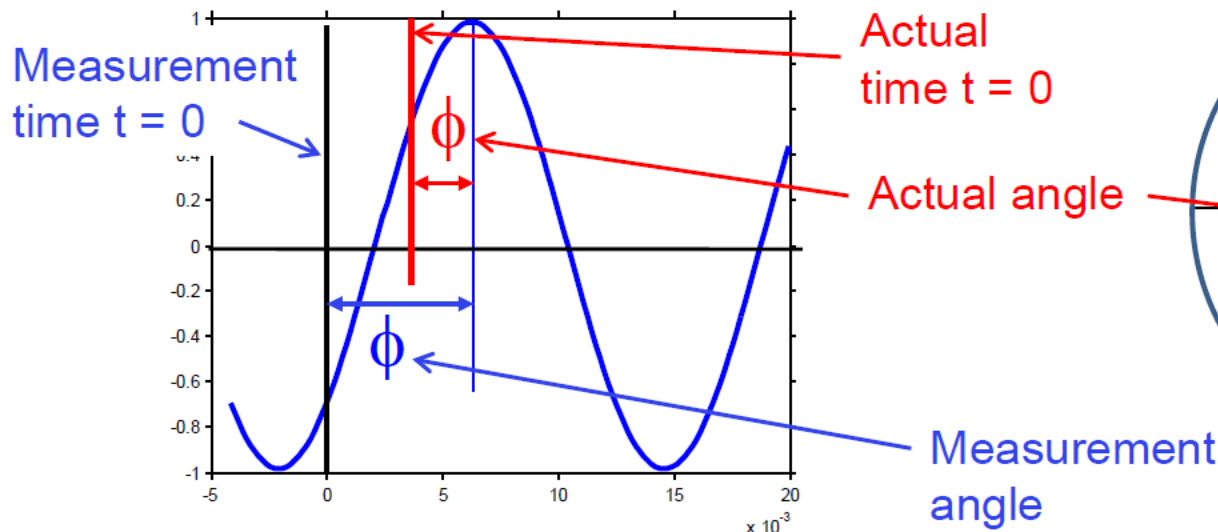


How accurate does your time need to be?

- The phase angle is determined by the time reference
- If $t = 0$ is displaced by x seconds, the phase angle will be rotated by $x/46 \times 10^{-06}$ degrees ($1^\circ \sim 46 \mu\text{s}$ at $f_0 = 60 \text{ Hz}$)
- Note the error ONLY effects phase angle – magnitude ok

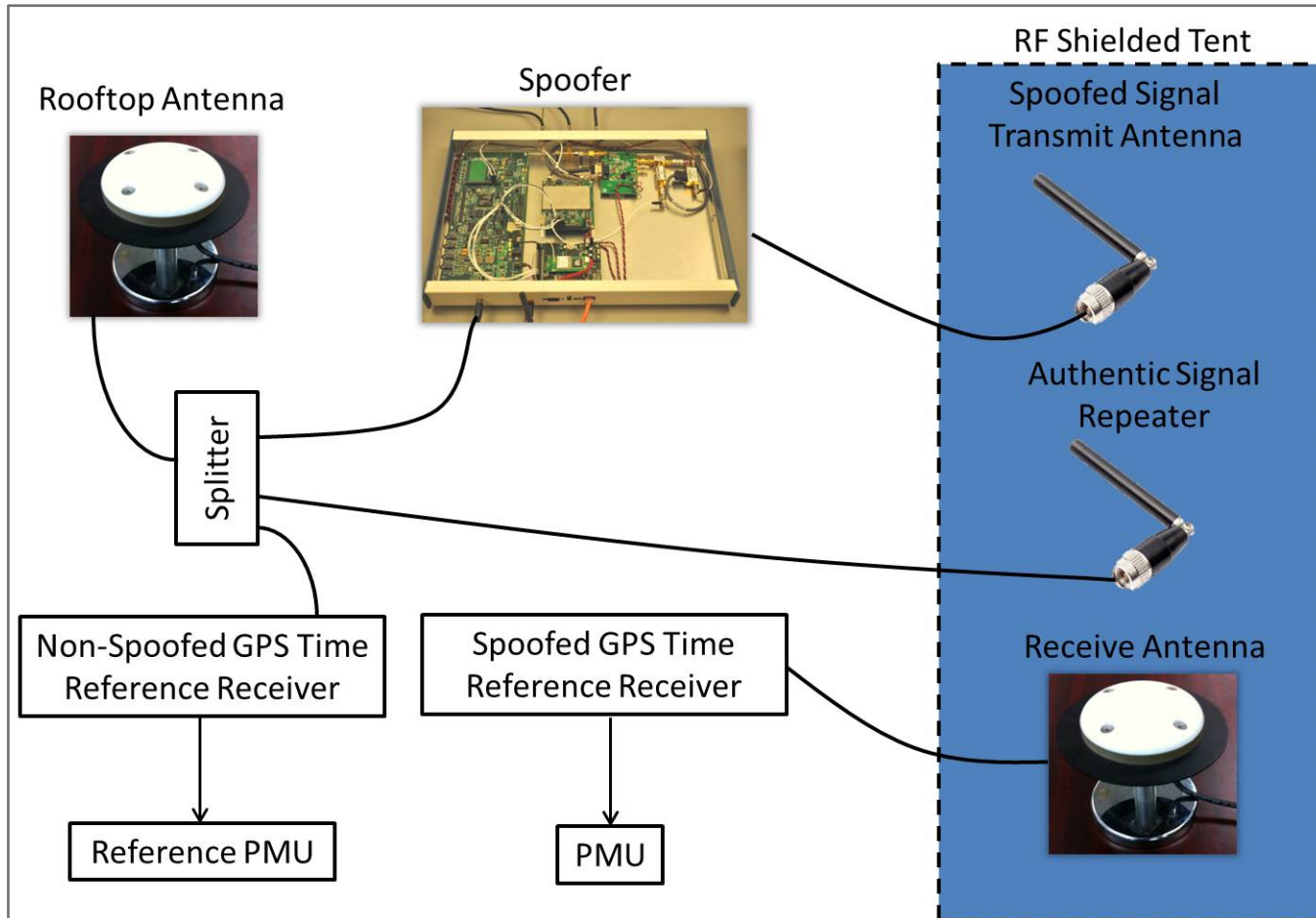
$$v(t) = \sqrt{2} A \cos (2 \pi \omega_0 t + \phi)$$

$$V = A e^{j\phi}$$

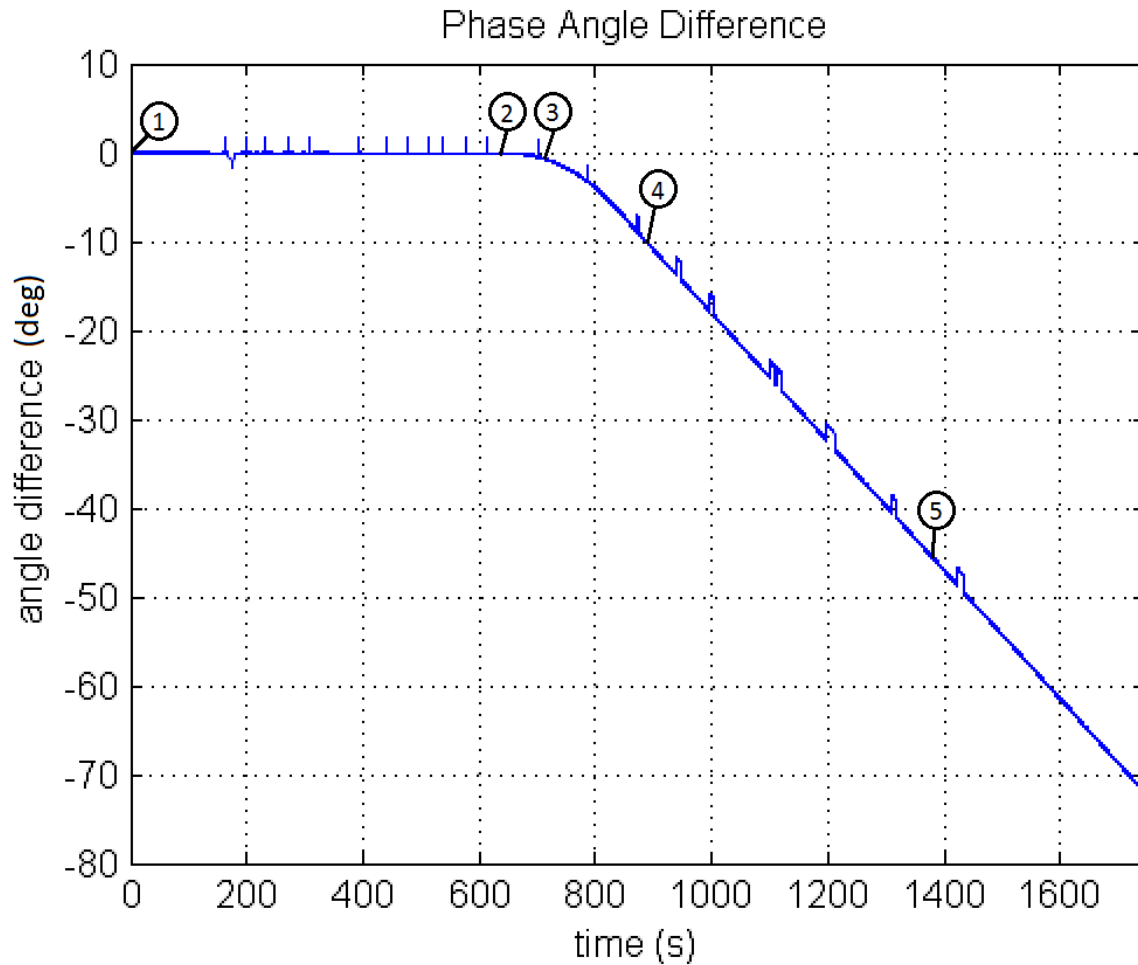


Credit: K. Martin

Testing the Susceptibility of Satellite Clocks to Spoofing (Deliberate Error)



Satellite Clock Spoofing Test Results



Satellite Clock Spoofing Conclusions

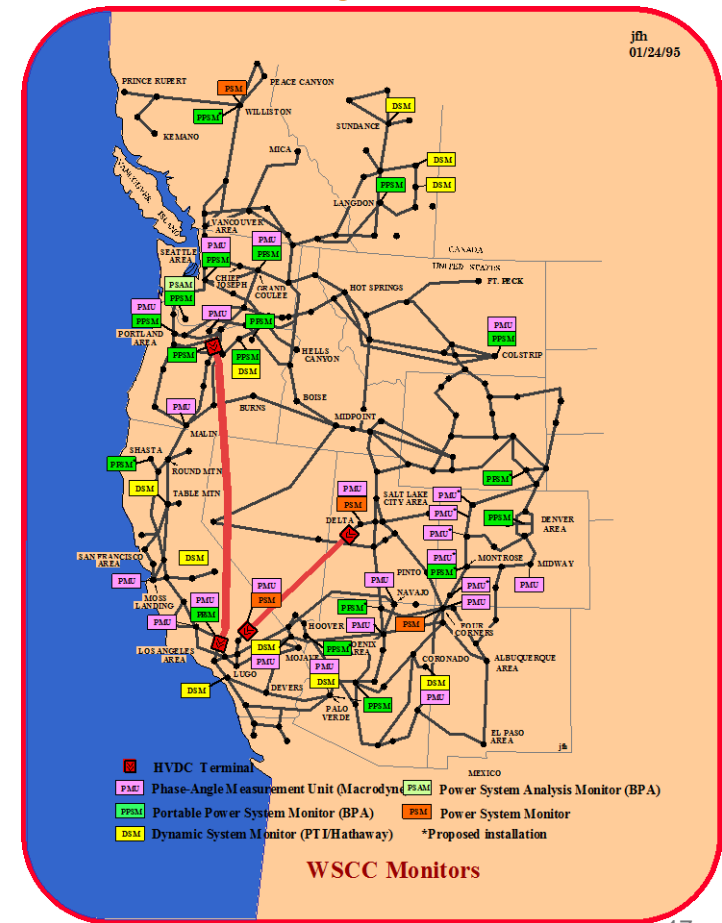
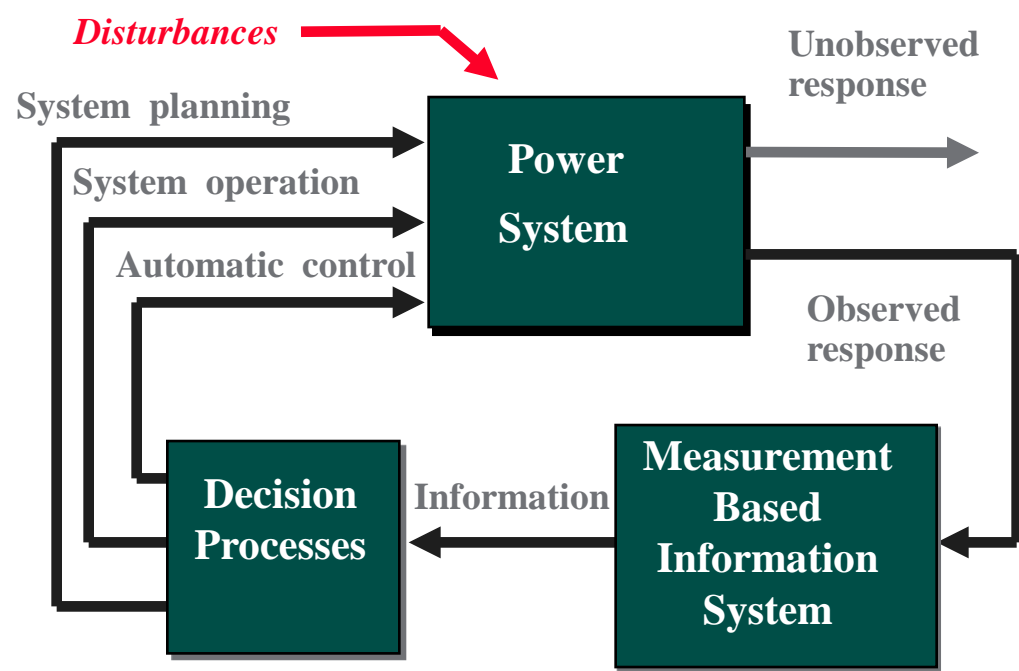
- ▶ All three satellite clocks that we tested were susceptible to time errors being introduced
 - Some differences in the rate of change that could be implemented (defeating the internal error checking algorithms)
 - Some differences in how the clocks responded when the spoofing signal was turned off
- ▶ Need to find alternative methods for ensuring critical applications cannot be undermined
 - Currently investigating various alternatives including the IEEE 1588 Precision Time Protocol Standard



WAMS Deployment in the Western Interconnection

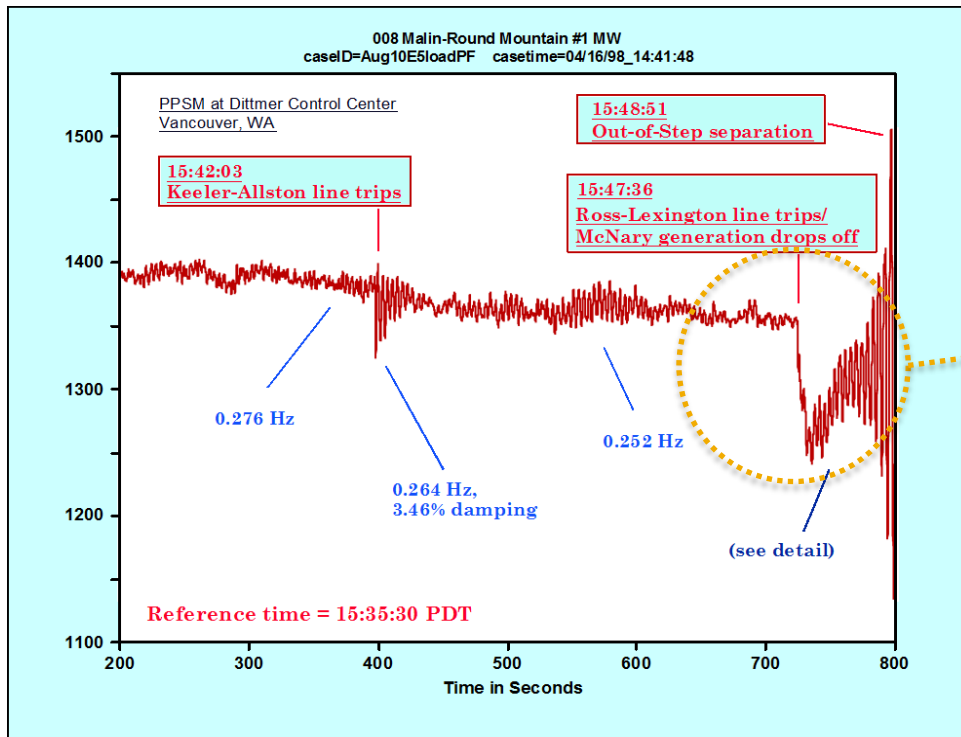
Dynamic monitor network that supports advanced situational awareness and analysis

“Better information supports better - and faster - decisions.”

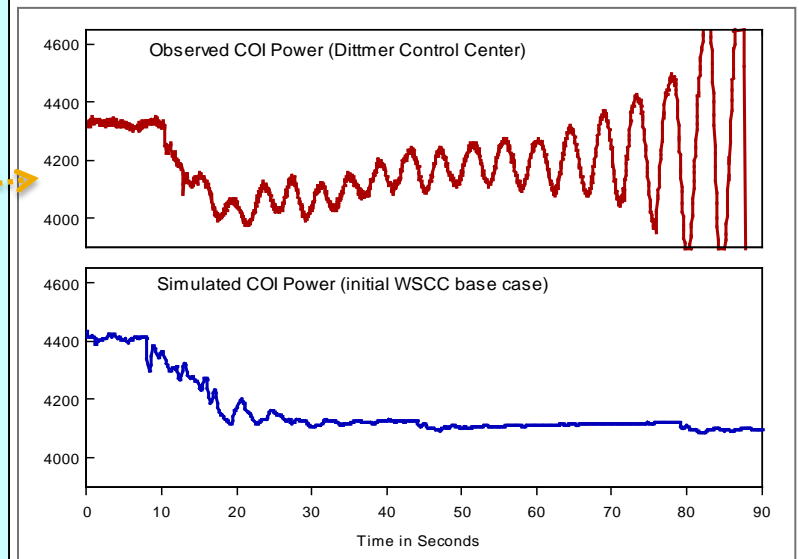


WAMS Background – Disturbance Analysis

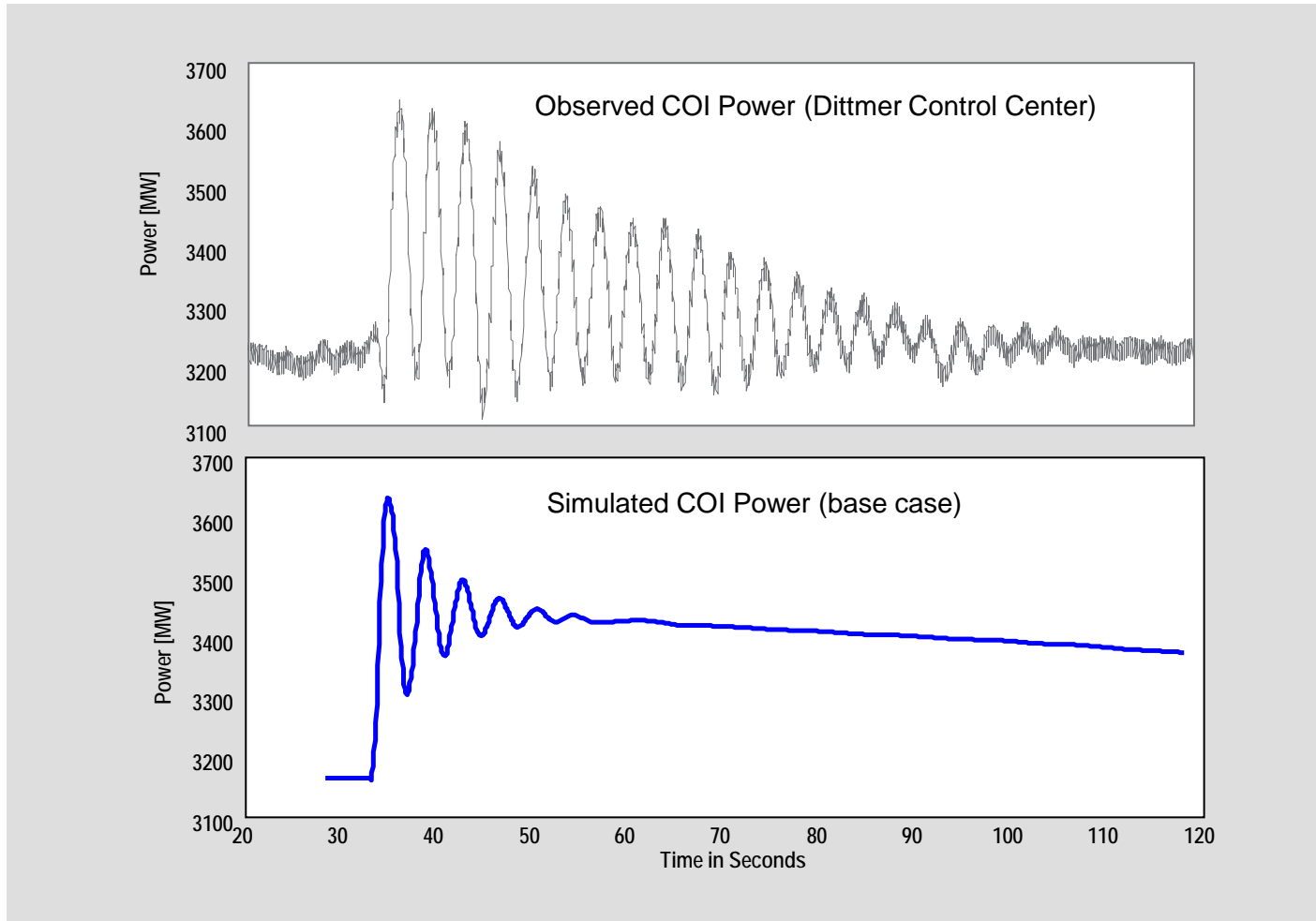
August 10, 1996 Post-Disturbance Analysis



Better Models Were Needed!



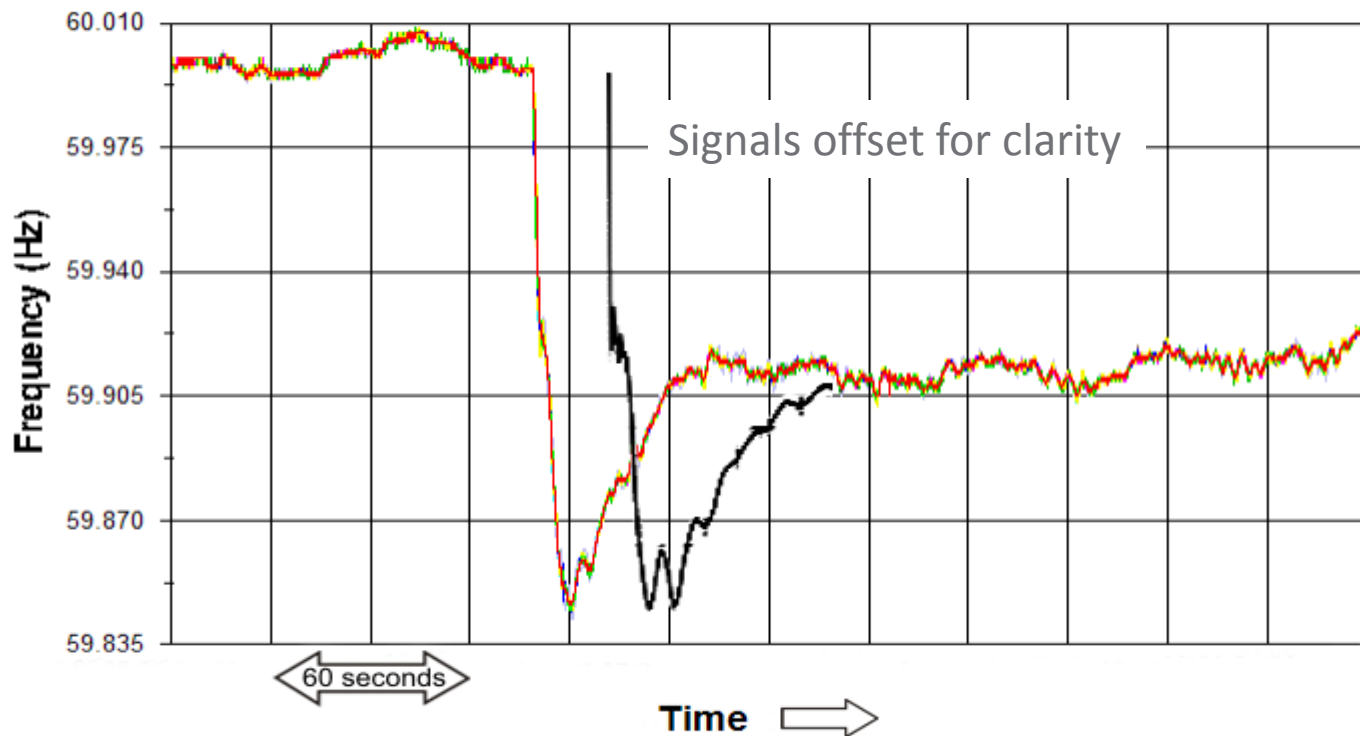
System Disturbance August 4, 2000



Graphics by D. N. Kosterev, Bonneville Power Administration

A More Recent Example --- The Models Have Been Improved Significantly!

Loss of major generator in WECC, actual and modeled



North American SynchroPhasor Initiative



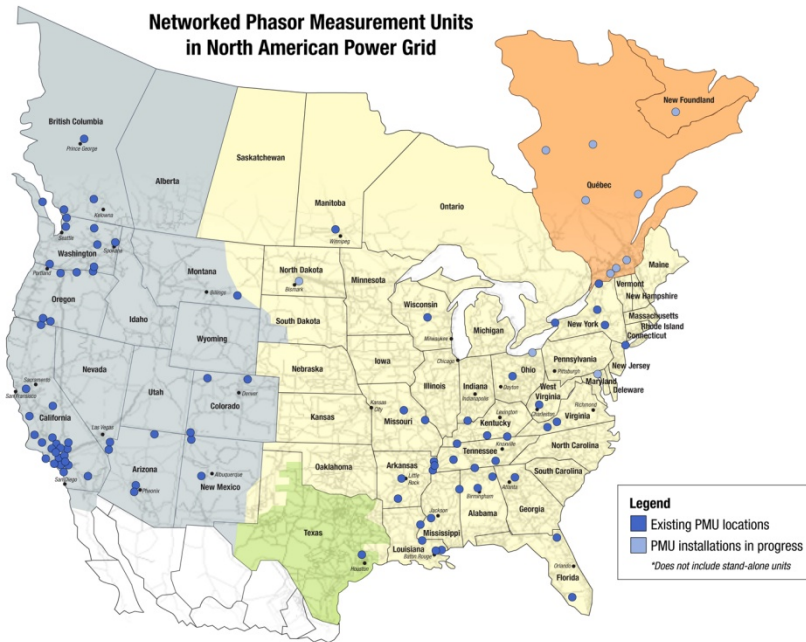
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The U.S. Department of Energy (DOE) and EPRI are working together closely with industry to enable wide area time-synchronized measurements that will enhance the reliability of the electric power grid through improved situational awareness and other applications

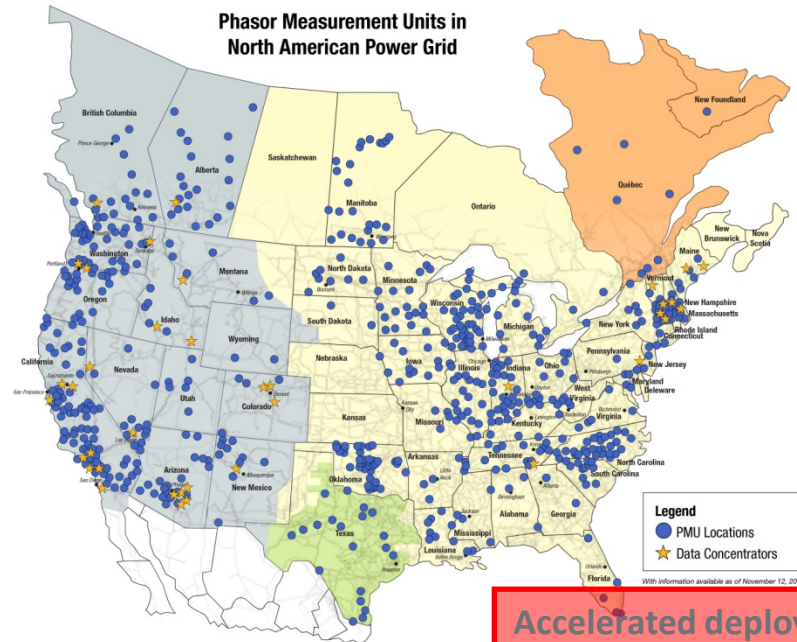
April 2007

Networked Phasor Measurement Units
in North American Power Grid



November 2012

Phasor Measurement Units in
North American Power Grid



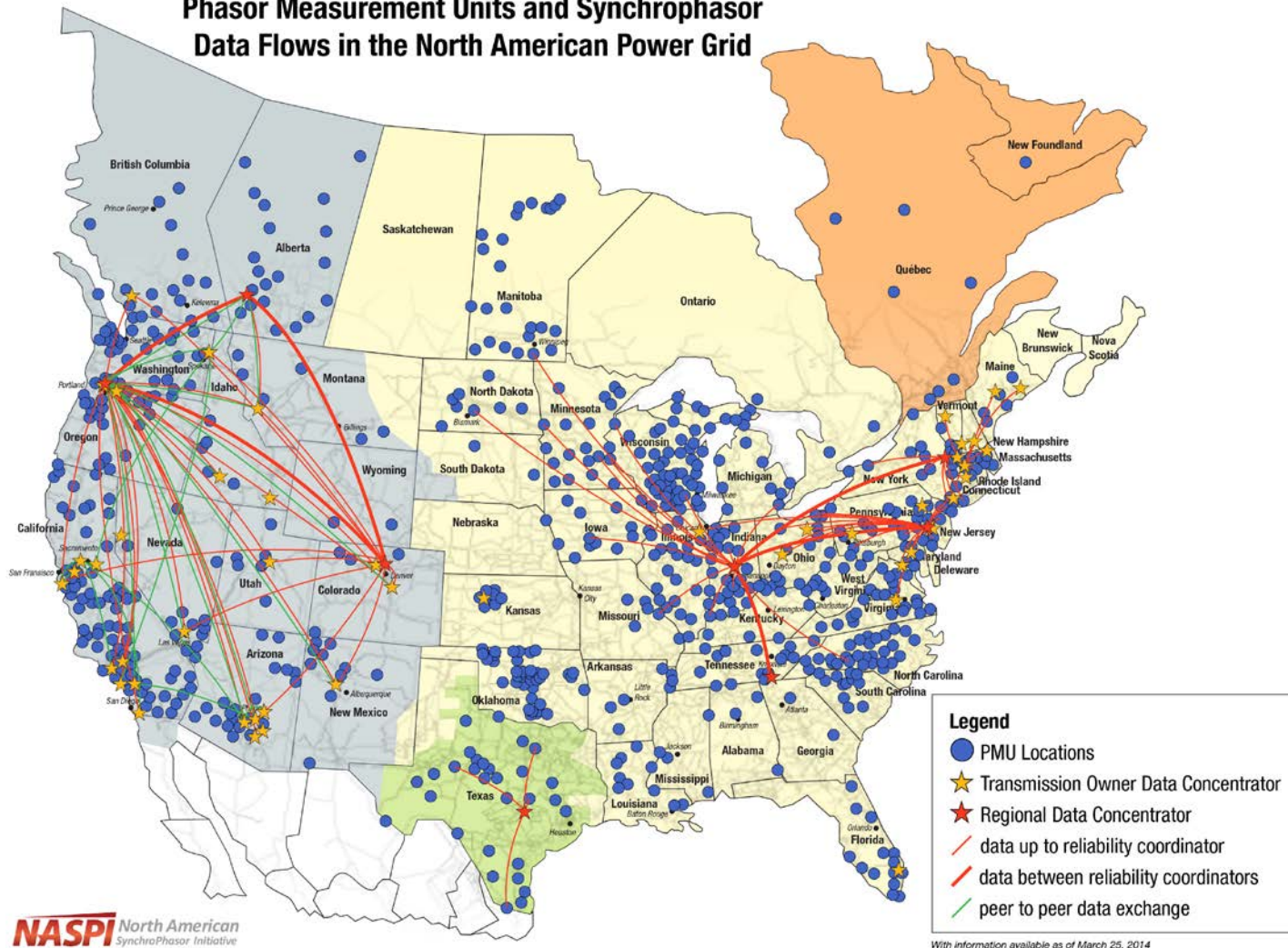
Accelerated deployment
facilitated by ARRA funding

“Better information supports better - and faster - decisions.”

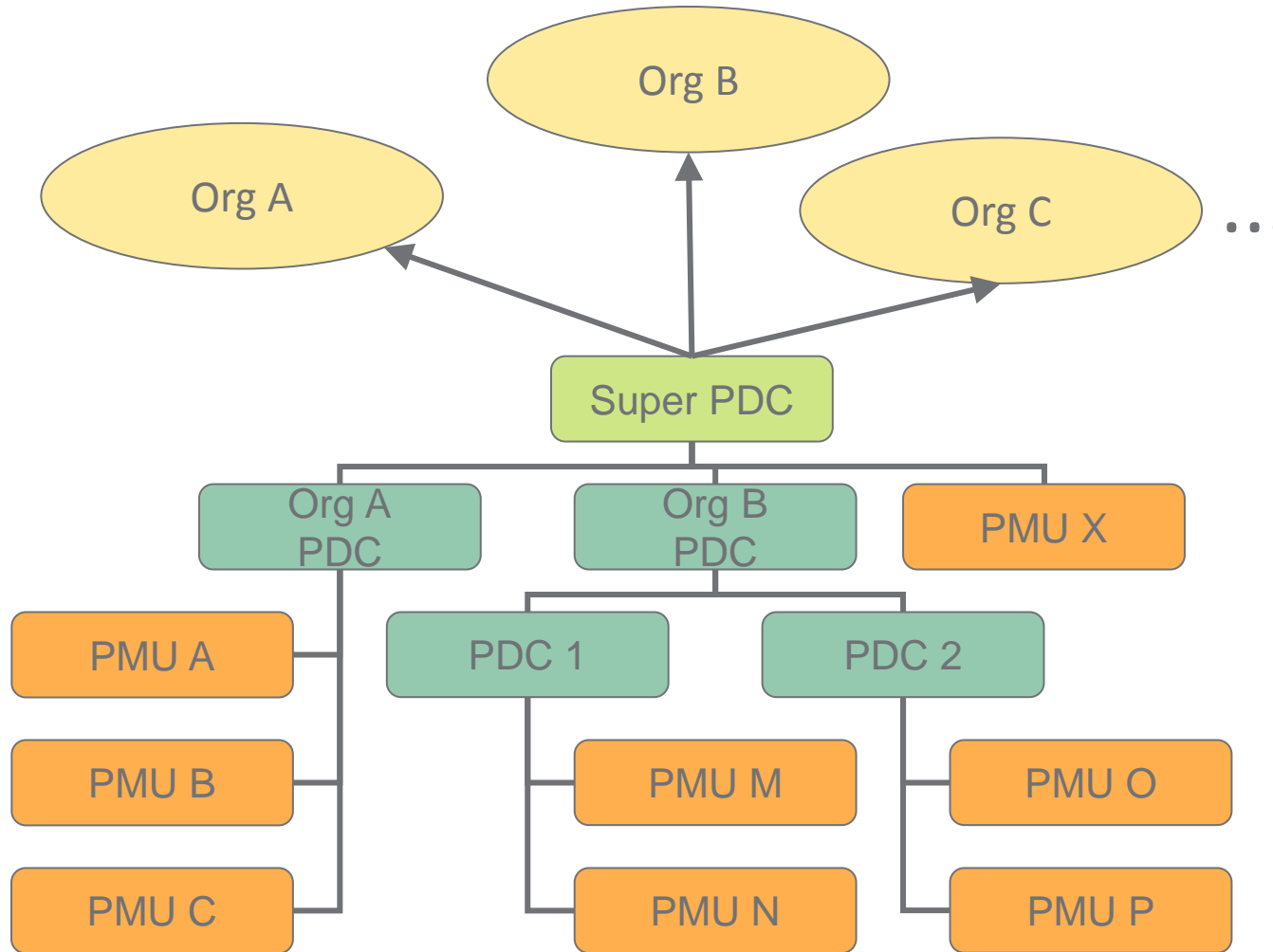


Networking and Data Sharing are Key Elements of the Technology

Phasor Measurement Units and Synchrophasor Data Flows in the North American Power Grid



Logical Measurement Data Network



Phasor Data Concentrator (PDC)

- ▶ A PDC gathers data from a number of devices and forwards it as a single stream
- ▶ PDC as defined in IEEE C37.244:
 - A **function** that collects phasor data, and discrete event data from PMUs and possibly from other PDCs, and transmits data to other applications
- ▶ PDC as defined in IEEE C37.118.1/2
 - A **device** used in phasor measurement systems that combined data from several sources

Security requirements are a function of the “box”

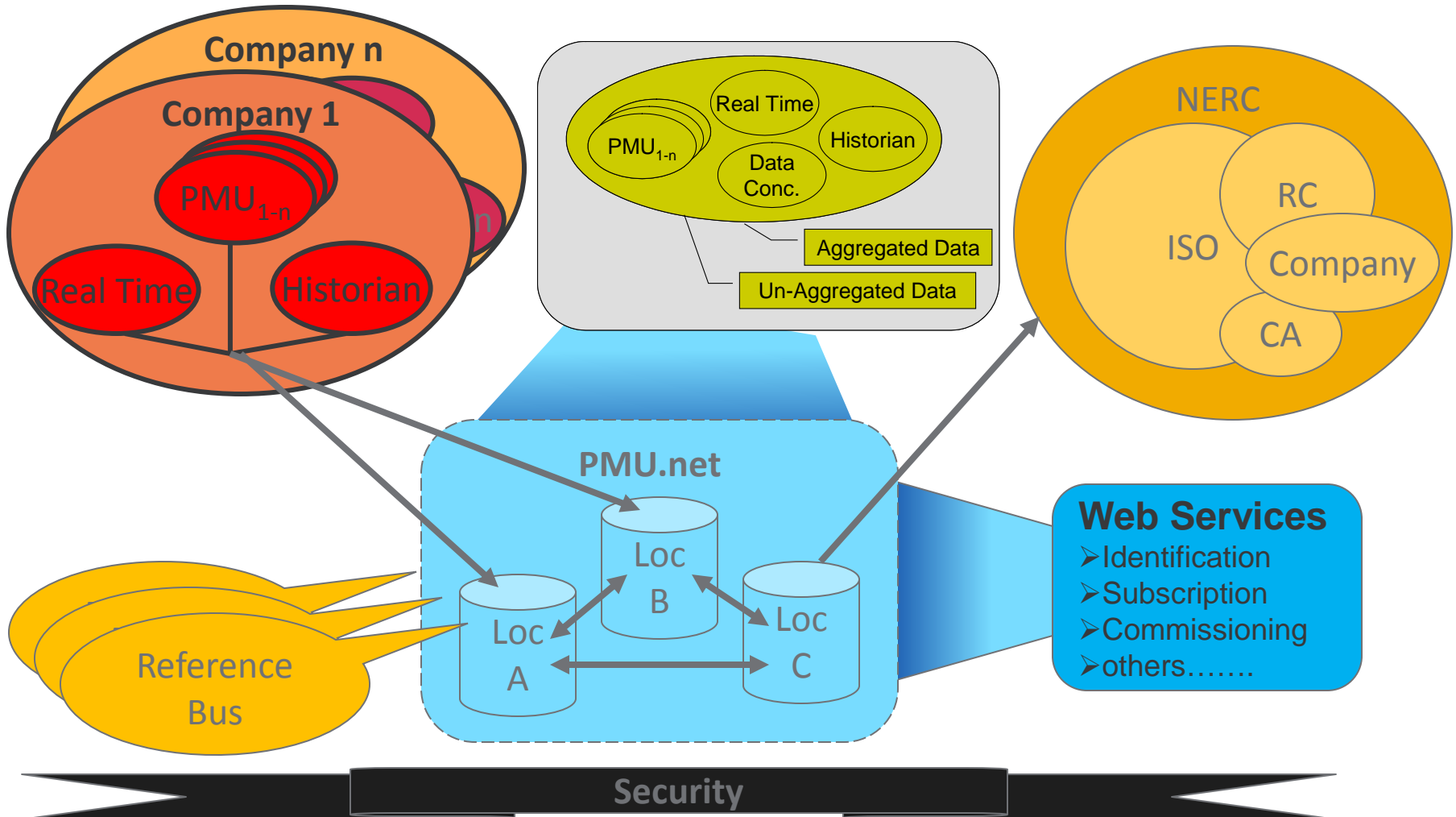
- ▶ Definitions basically equivalent, but the semantic difference is debated
- ▶ IEEE PDC Guide C37.244-2013
 - Covers definitions, functions, performance, and testing

Basic PDC Functions

- ▶ Input data from PMUs
 - Decode, error check, and manage communications
- ▶ Combine input data, generally by timetag
- ▶ Output data to applications
 - Construct message and manage communications
- ▶ Manage measurement system
 - Create record of outages, errors
 - Provide real-time monitor of operation
- ▶ Phasors must be matched by timetag to compare phase angles across system

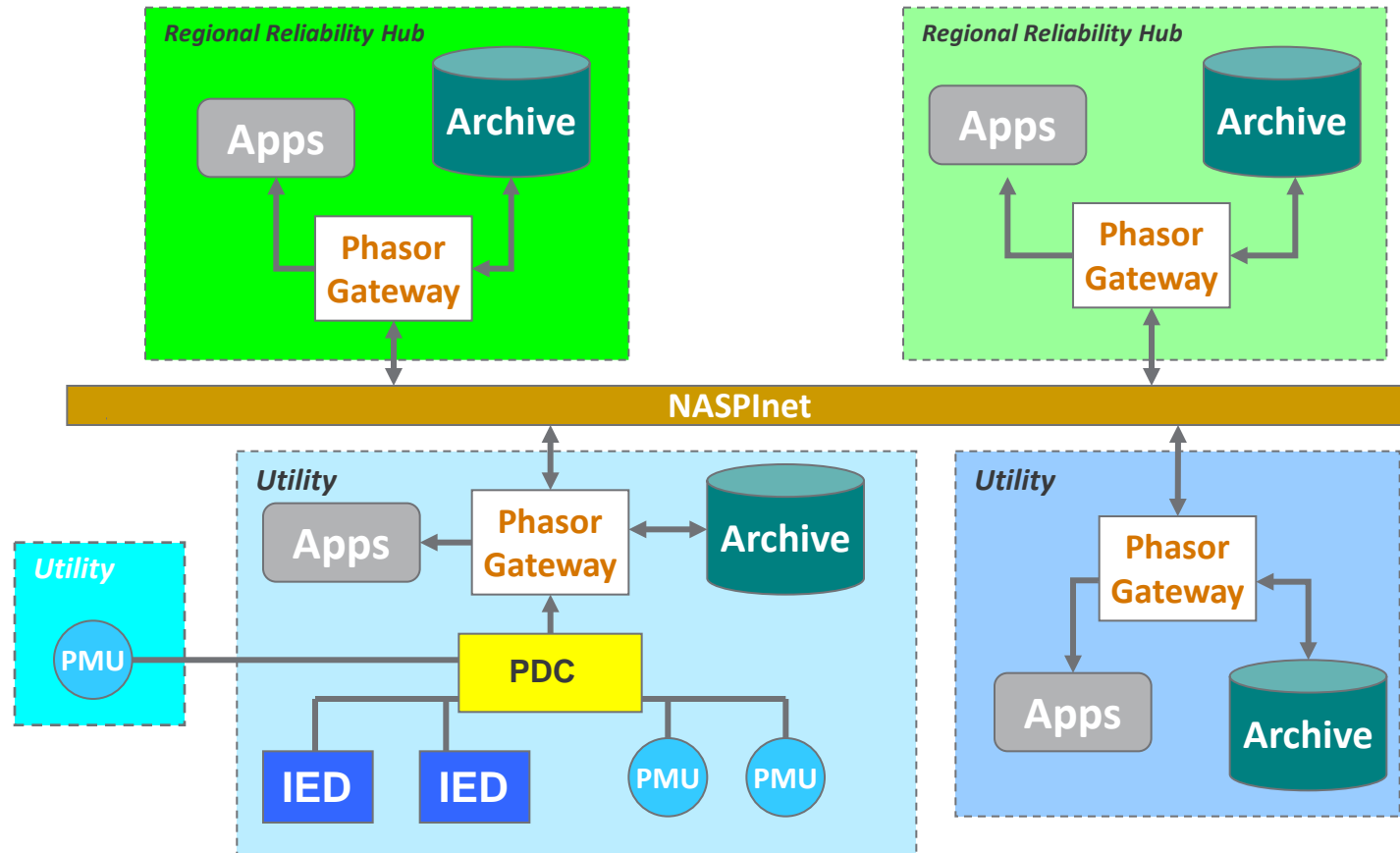
Credit: K. Martin

Future Network Architecture Concept



Credit to Paul Myrda, former Data Mgmt Task Team Lead

The NASPInet Vision – A Distributed Network for Data Exchange and Sharing



NASPI Application Classification

<i>Class</i>	<i>Basic Description</i>	<i>Sampling/ Data Rate</i>	<i>Required Latency</i>
A	Feedback Control	Fast	Fast
B	Open Loop Control	Medium	Medium
C	Visualization	Medium	Medium
D	Event Analysis	Fast	Slow
E	Research/Experimental	N/A	N/A

Data Quality Requirements

- ▶ Measurement accuracy
- ▶ Data availability
- ▶ Data delivery speed
 - Includes cumulative latency throughout the entire measurement, communications, and processing system infrastructure

Highly dependent on the application requirements!

- Some examples of data quality issues:
 - PMU device
 - Including configuration settings, hardware or software failure
 - PDC device
 - Same as above
 - Instrument transformers, including substation cabling
 - Communications infrastructure including routers, firewalls, etc.
 - Applications, including servers, data historians, software compatibility

Data Availability Example

Dates:		8/25/2014 -8/31/2014	
Entity	Percent Availability	PMU Count	
	94.09%	17	
	94.99%	17	
	81.76%	11	
	99.86%	55	
	83.13%	20	
	99.58%	15	
	69.14%	6	
	62.91%	3	
	73.19%	4	
	0.00%	2	
	75.86%	6	
	38.07%	7	
	99.86%	4	
	99.89%	1	
	100.00%	2	
	98.45%	2	
	99.81%	5	
Overall:	90.13%	177	

- ▶ IEEE C37.118
 - Part 1 - This standard defines synchrophasors, frequency, and rate of change of frequency (ROCOF) measurement under all operating conditions.
 - Part 2 - This standard specifies messaging that can be used with any suitable communication protocol for real-time communication between phasor measurement units (PMU), phasor data concentrators (PDC), and other applications.
- ▶ IEC 61850.90-5.1 and 90-5.2
 - 90-5 is the synchrophasor profile for IEC 61850, substation automation
- ▶ IEEE 1588 – time synchronization

Security of Synchrophasors

- ▶ Synchrophasors are becoming part of the bulk electric system and will require physical and cyber security
 - ***But these systems shouldn't be treated any differently than other forms of measurement and control telemetry***
- ▶ Synchrophasor systems will coexist with other bulk electricity system (BES) cyber infrastructure and will have similar dependencies on common communications and network elements
- ▶ System designers and owners are aware of emerging cyber-security standards and technologies
- ▶ Currently available phasor applications require further data analysis, software refinement and operational validation to be fully effective; many are in advanced development and testing and are not in full operational use
 - Therefore, many of these systems are not currently considered critical cyber assets
- ▶ Due to nature of continuous, high-volume data flows, new technology will likely be required for measurement, communications, and applications
 - Technology anticipated to undergo rapid change and refinement over the next several years

Different Types of PMUs

- ▶ P class (protection)
 - Minimal filtering
 - Possible aliasing of higher frequency components
 - Less delay in estimation
 - Important for real-time controls requiring minimum delay
- ▶ M class (measurement)
 - Some anti-alias protection
 - Wider frequency response, lower noise
 - Latency longer (depends on reporting rate)
 - Important for situations with higher frequencies present
- ▶ Both classes
 - Essentially the same measurement in all other respects

Credit: K. Martin

Phasor Applications Taxonomy

RESEARCHERS

- Automatic alarming of remedial action schemes
- Out of step protection
- Short/long-term stability control
- Feedback control

RELIABILITY COORDINATORS

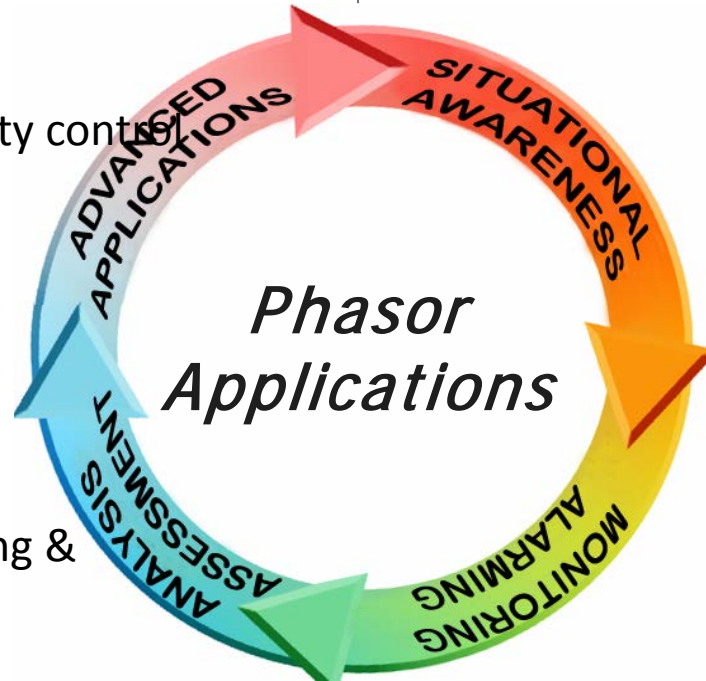
- Situational awareness dashboard
- Real time compliance monitoring
- Frequency Instability Detection/Islanding

PLANNERS

- Post-mortem analysis
- Model validation
- Phasor network performance monitoring & data quality
- Email notifications
- Test new real-time applications

OPERATORS

- Real time performance monitoring
- Real time alerts and alarms
- Event detection, disturbance location
- Suggest preventive action
- Interconnection state estimation
- Dynamic ratings



Credit to Terry Bilke (MISO),
Former leader of the Operations Implementation Task Team



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