

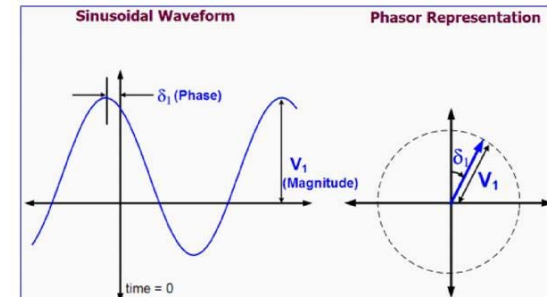
# PMU Emulator and Animation for Synchronphasor Education (SynchroEd)

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# What it is?

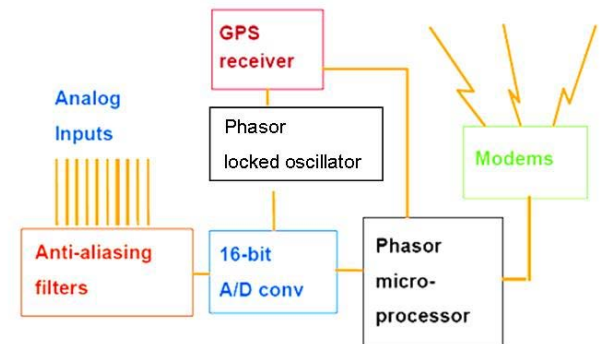
- Educational and training module for basic synchrophasor concepts.
- Detail codes for synchrophasor estimation, filtering embedded in animation
- Developed with support of DOE funding
- Students can learn concept of PMU and fundamental functions; ADC, GPS signal, Phasor estimator
- C++ and MATLAB code



# Why to use?



- Device and system context using animation
- Detail device level information using actual PMU blocks
- Basic synchrophasor concepts and how phasor changes with system dynamic conditions
- How noise, filtering, estimation impact PMU output
- Easy to integrate into existing training or education modules



# Main Window of SynchroEd

Simple two bus system to determine voltage and current phasor  
In the context of the power system

To start PMU animation software, click either PMU1 or PMU2

## Power System



# SynchroEd: PMU architecture

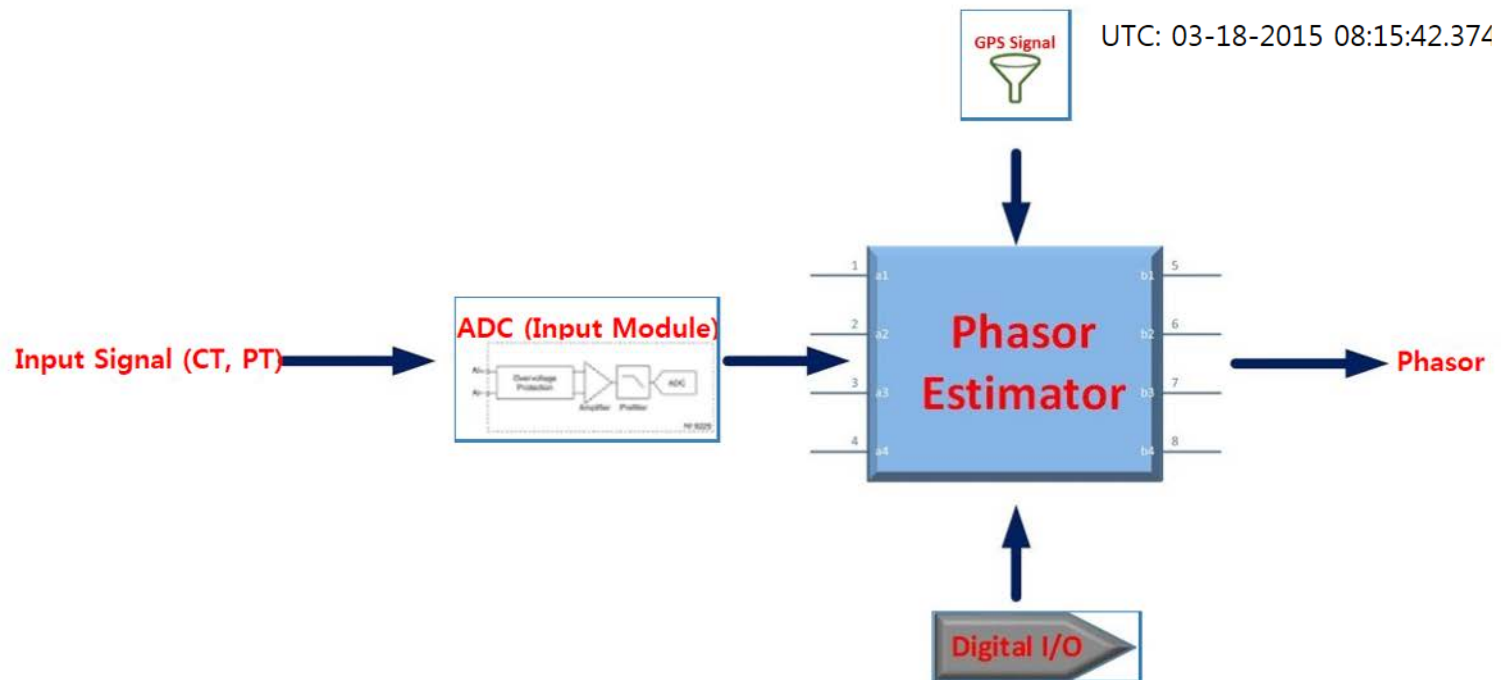
There are four functions;

- GPS Signal, ADC Module, Digital I/O Module, and Phasor Estimator

UTC or GPS signal has been used for time stamp.

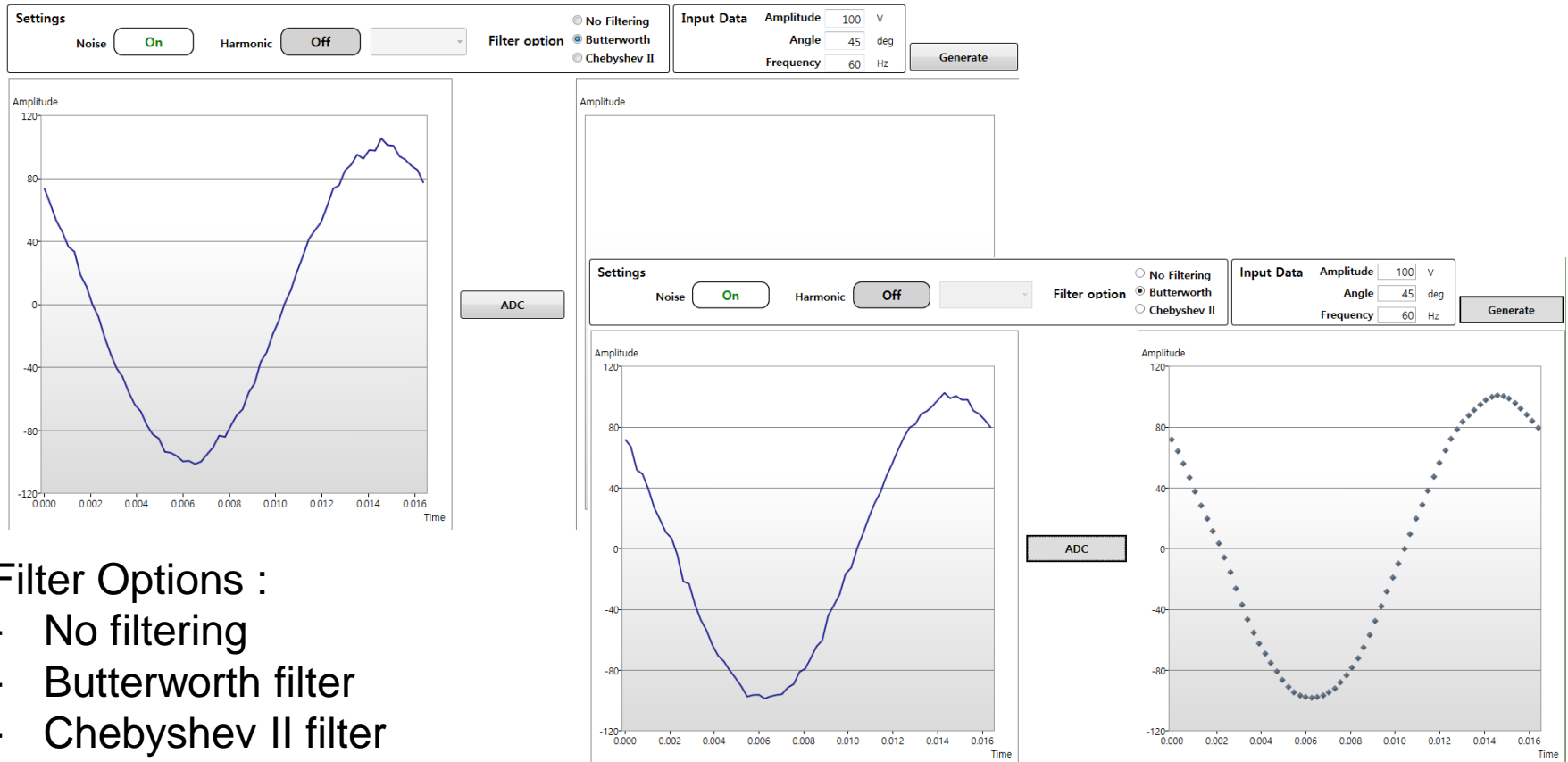
By clicking GPS Signal, UTC time is shown next to GPS Signal function.

## Phasor Measurement Unit (PMU)



# SynchroEd: ADC Module

ADC with filter can reduce noise and harmonics.



Filter Options :

- No filtering
- Butterworth filter
- Chebyshev II filter

# SynchroEd: Phasor Estimator module

PMU can estimate voltage and current phasor from PT and CT signals  
 First, generating input signal with/without noise, harmonics, and transient condition.  
 Then, PMU can estimate phasor by clicking on start button.

**Phasor Estimator**

**Settings**

Noise  On  Off

Harmonic  Off  On

Normal  
 Fault  
 Transient

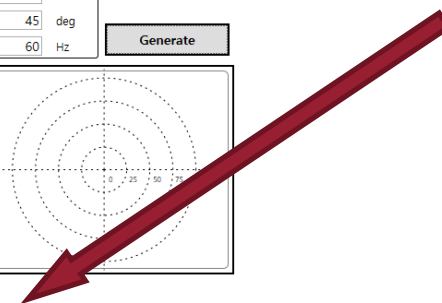
**Input Data**

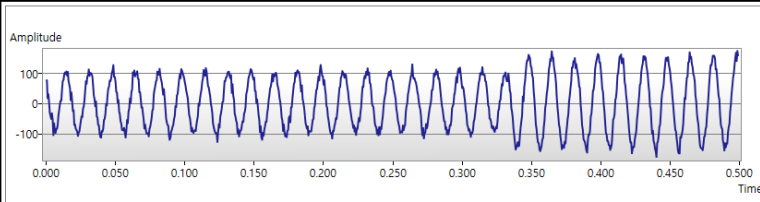
Amplitude: 100 V

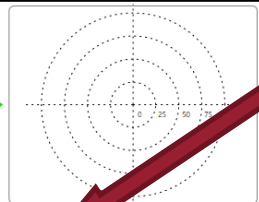
Angle: 45 deg

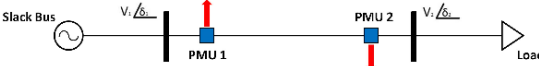
Frequency: 60 Hz

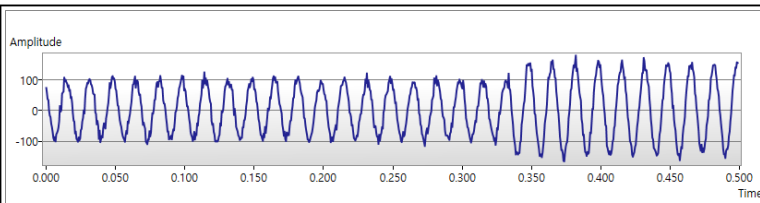
**Click**

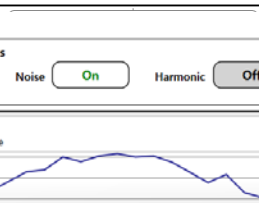












**Phasor Estimator**

Noise  On  Off

Harmonic  Off  On

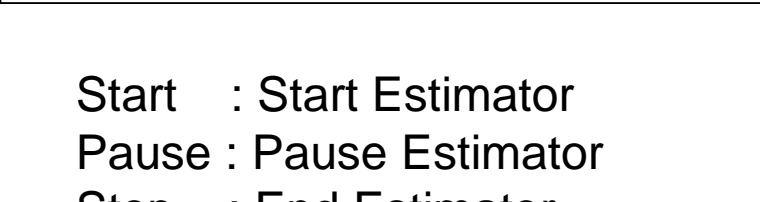
Normal  
 Fault  
 Transient

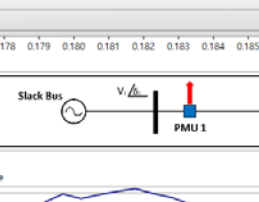
**Input Data**

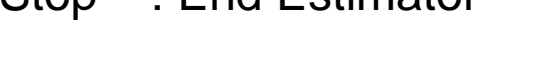
Amplitude: 100 V

Angle: 45 deg

Frequency: 60 Hz







Start : Start Estimator  
 Pause : Pause Estimator  
 Stop : End Estimator







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