

Synchrophasor-Based Monitoring, Analysis, and Control

Roy Moxley
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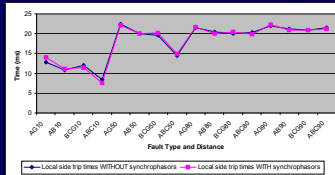
Making Electric Power Safer, More Reliable, and More Economical®

The Power System Is Changing



Photo Courtesy of Shawn
Jacobs, OG&E

SEL Synchrophasor Vision



Synchrophasors in a Relay



Relay
asors in a Meter
Synchrophasors on the Web
IEEE Protocol :
SYN

IEEE Protocol in a Relay



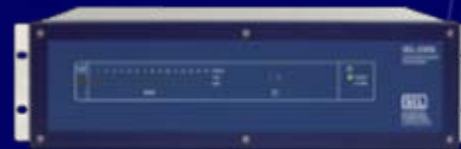
Retrofit S In a Relay

Utility Gradient

Real-Time Control in
a Relay (Mexico)
SCADA

Control in
(Mexico)
SCADA Synchrophasors
Real-Time Processing

Real-Time Vector Processor



Synchrophasors Are Standard

SEL-421 IEEE C37.118

SEL-451

SEL-487E

NEW!

SEL-787

SEL-734 SEL Fast Message

SEL-311A, B, C

SEL-311L

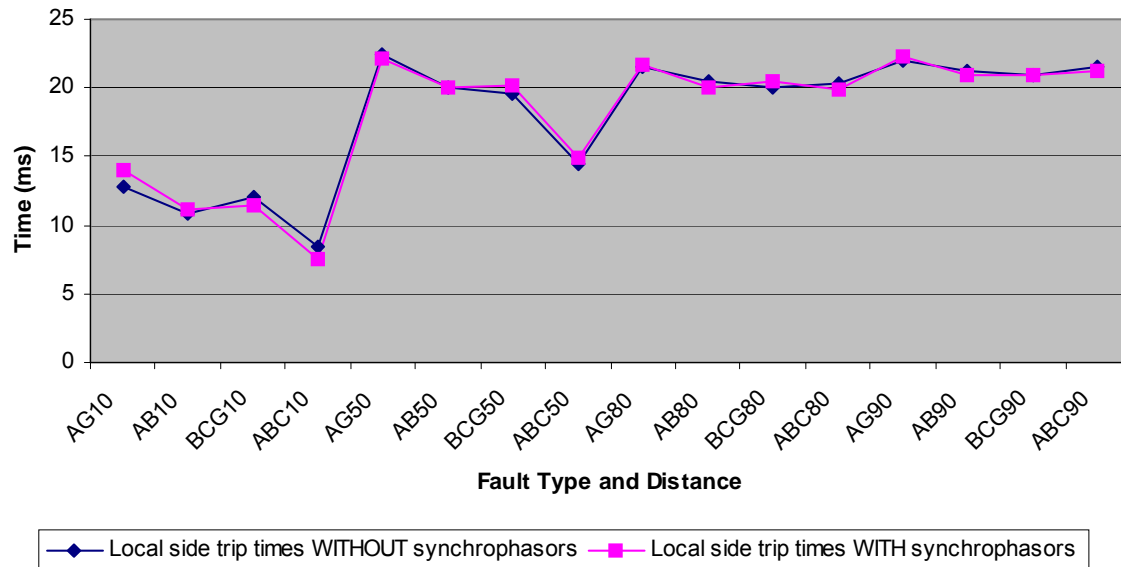
SEL-351

SEL-351S

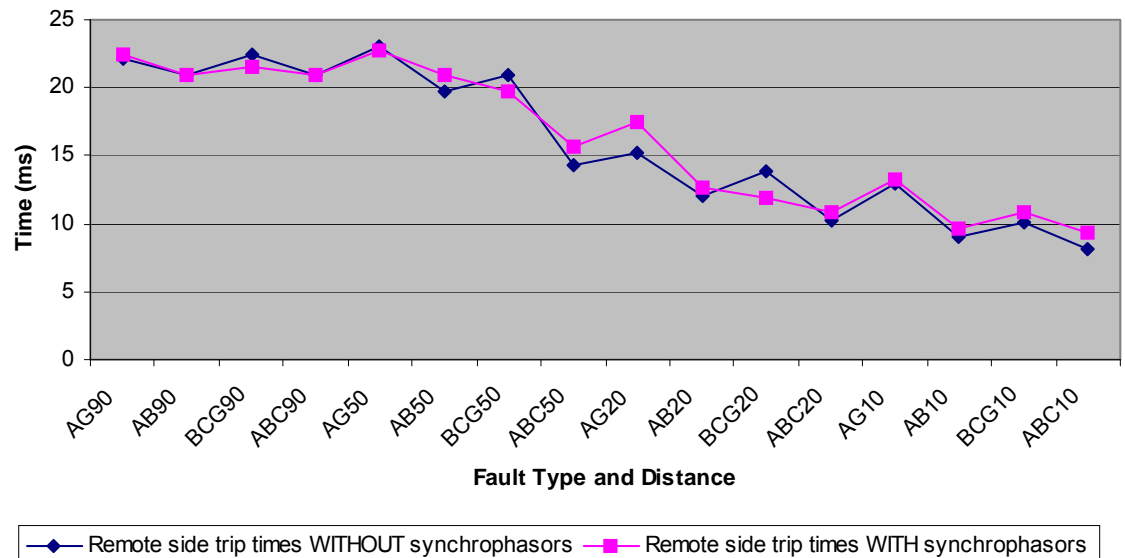
SEL-351A



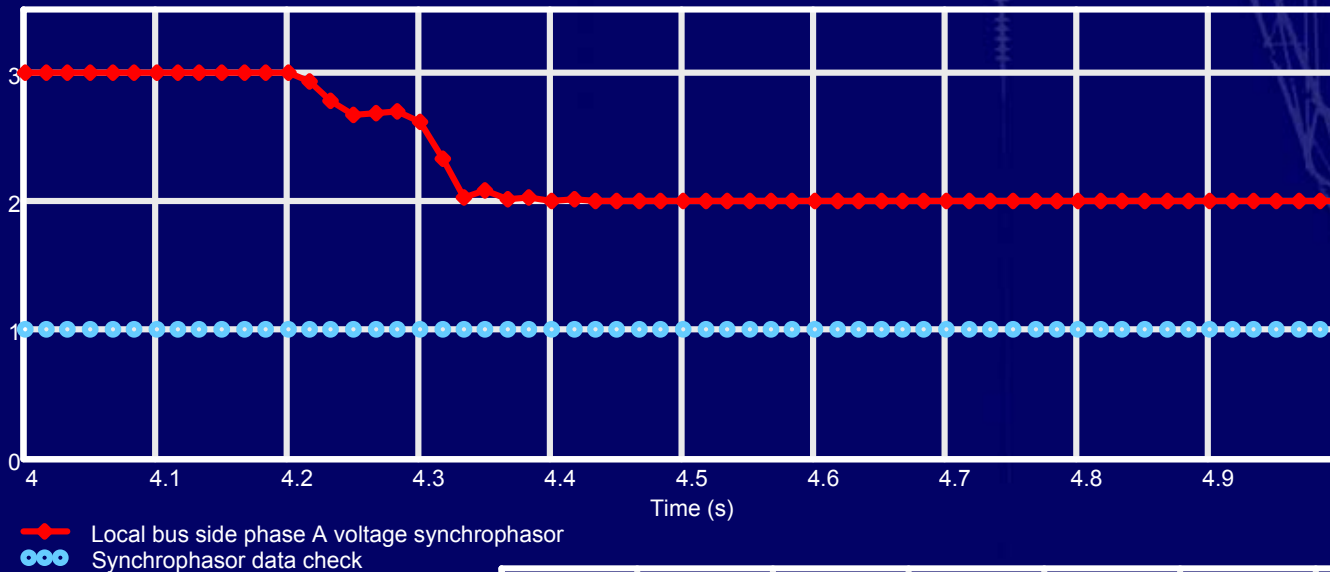
Protection AND Synchrophasors



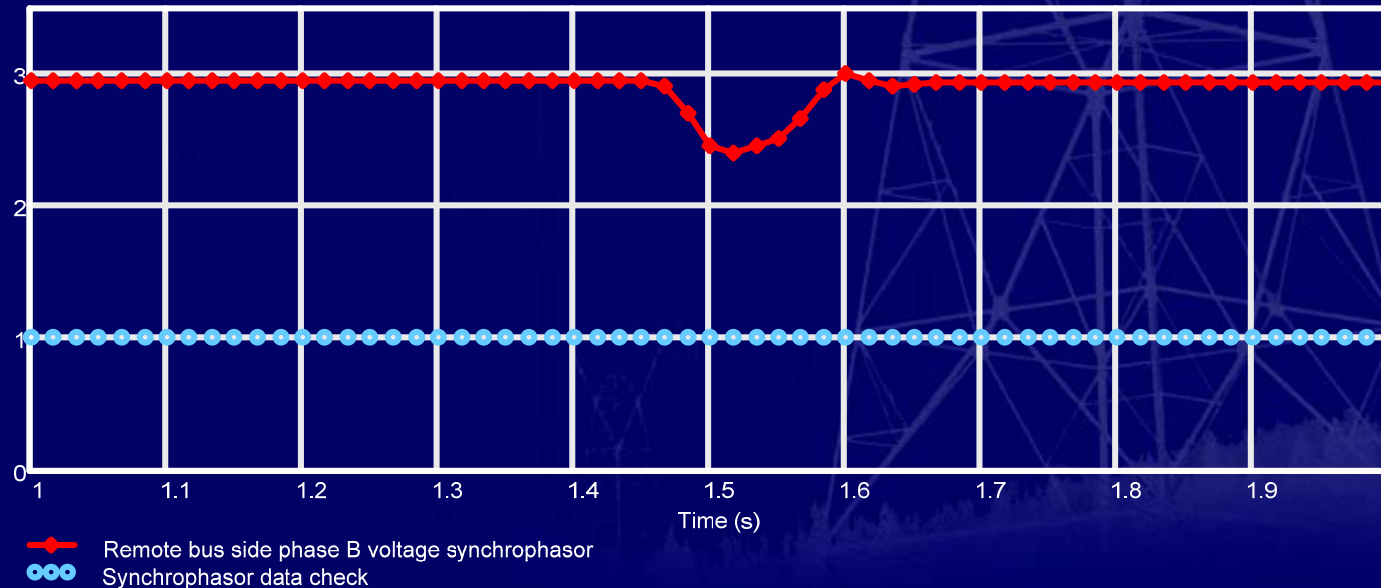
Synchrophasors
do not hurt relay
performance



Relaying Has No Impact on PMCU Function



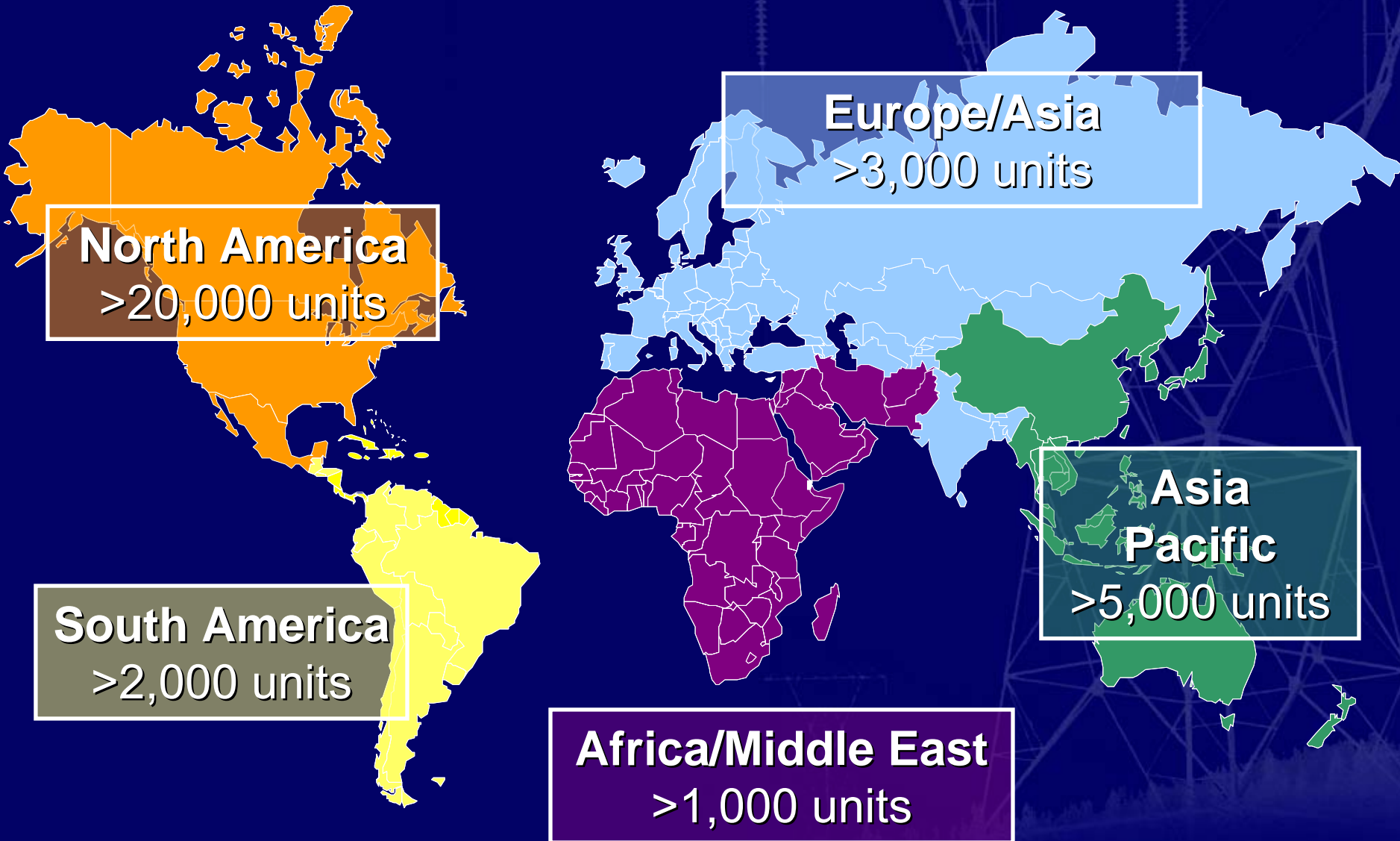
No lost data



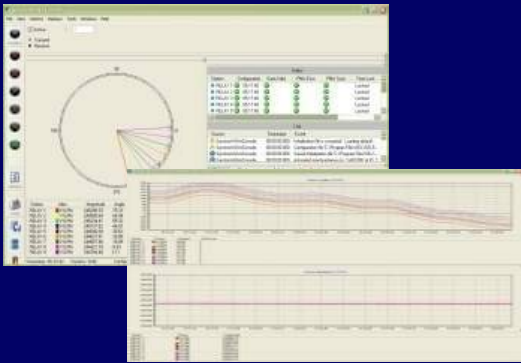
Relays Are Right for Synchrophasors

- Phasor measurement and control unit (PMCU) \geq PMU
- Minimal incremental cost
- Reduced current and voltage connections
- High-accuracy measurements
- High reliability and availability
- Future control applications
- Relays are everywhere

SEL Synchrophasor Equipped Devices Worldwide !



Application Options – Not “One Size Fits All”



SEL-5078 Visualization

SEL-3306 Hardware PDC
SEL-5077 Software PDC
SEL-3378 Vector Processor

SEL-5077, SEL-5078 Archiving

[illegible]

System Operator, Reliability Council

PMU's



Protection and Control Time Frame

~1.0 Second

~30 Seconds



Relay Action

Control Action





Human Action



METER PM 13:22

421 Synchrophasor - HyperTerminal

File Edit View Call Transfer Help



=>>met pm 13:22
Synchronized
=>>

Relay 1
SEL-421 Pullm

Time Quality

Synchrophasor







MAG (kV)
ANG (DEG)

MAG (A)
ANG (DEG)

Connected 0:04:54

421 Synchrophasor 2 - HyperTerminal

File Edit View Call Transfer Help



=>>met pm 13:22
Synchronized Phasor Measurement Data Will be Displayed at 13:22:00.000
=>>

Relay 2
SEL-421 Moscow

Time Quality Maximum time synchronization error: 0.000 (ms) TSOK = 1

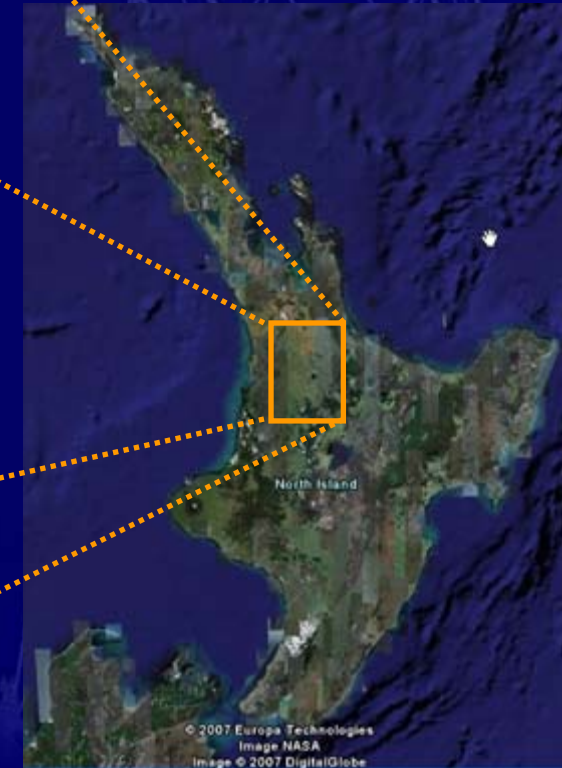
Synchrophasors

	Phase Voltages			Pos. Sequence Voltage
	VA	VB	VC	V1
MAG (kV)	66.975	66.986	66.979	66.980
ANG (DEG)	-55.678	-175.508	64.719	-55.489

	IW Phase Currents			IW Pos. Sequence Current
	IA	IB	IC	I1W
MAG (A)	2004.431	1997.885	1993.773	1998.681
ANG (DEG)	117.671	-1.792	-121.951	117.976

Connected 0:02:22 Auto detect 57600 8-N-1 SCROLL CAPS NUM Capture Print echo

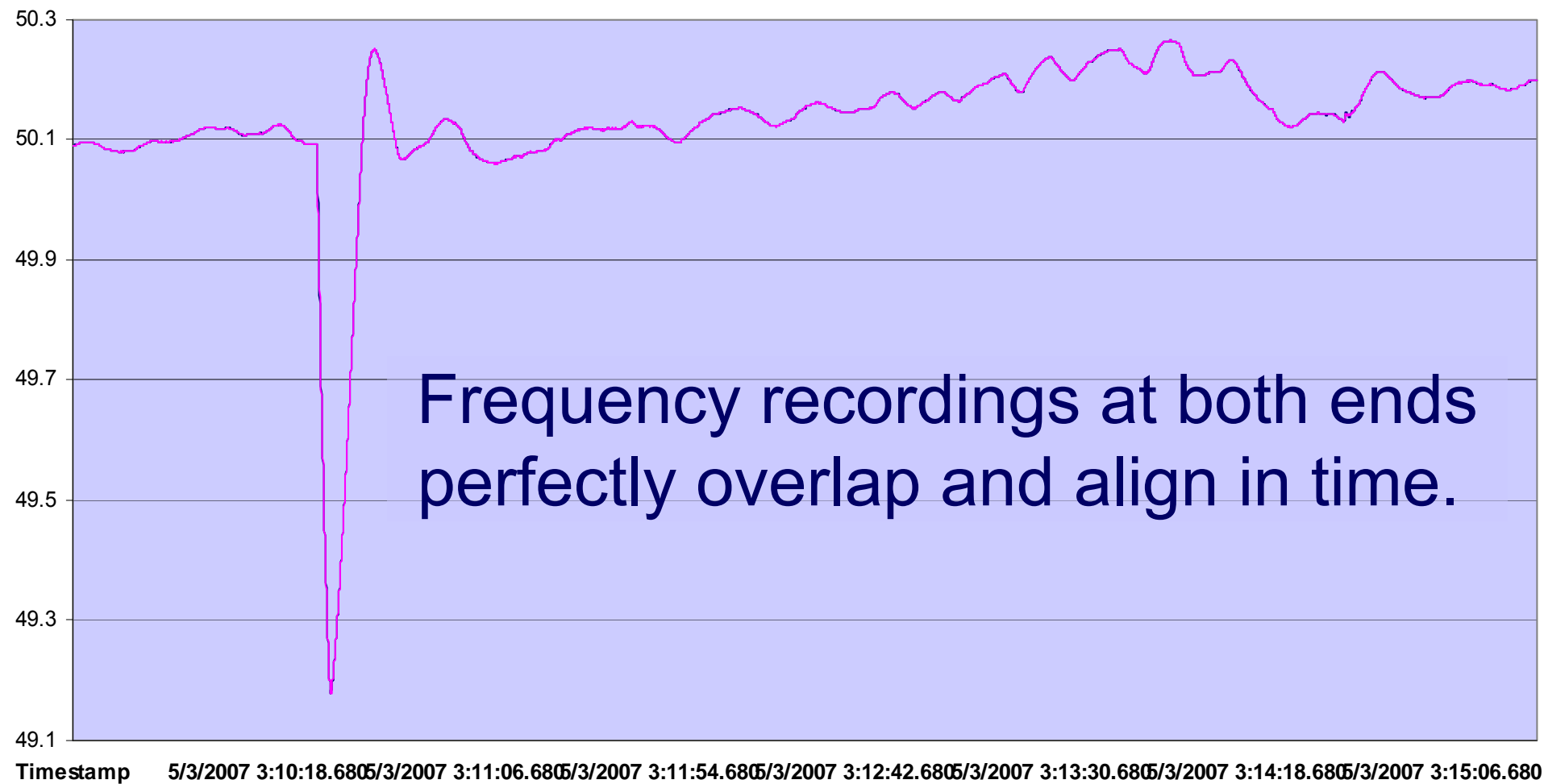
Monitor a Gen Drop Test (New Zealand)



Test Shows System Remains Stable When 400 MW Dropped

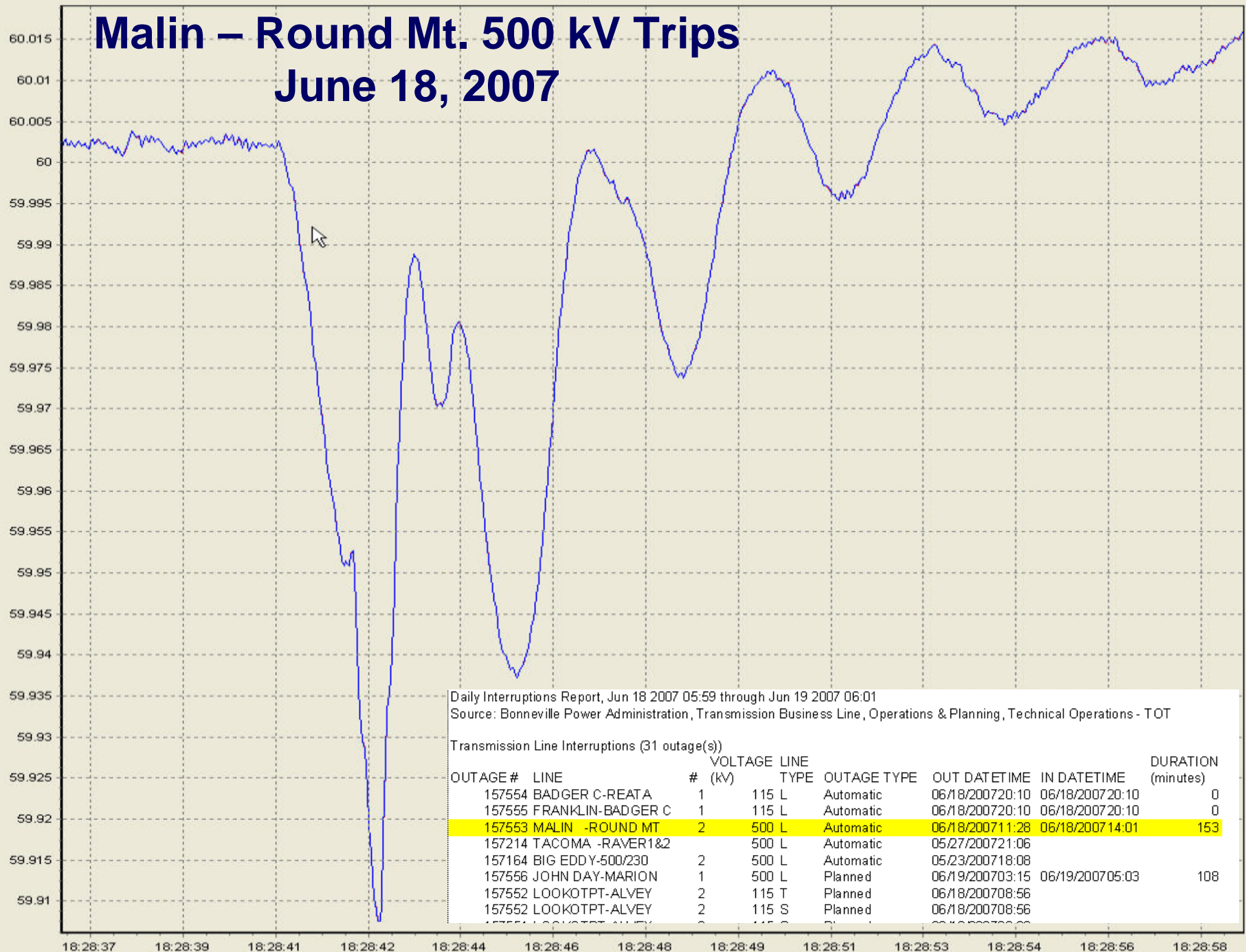
— Whakamaru_Frequency

— Huntly_Frequency

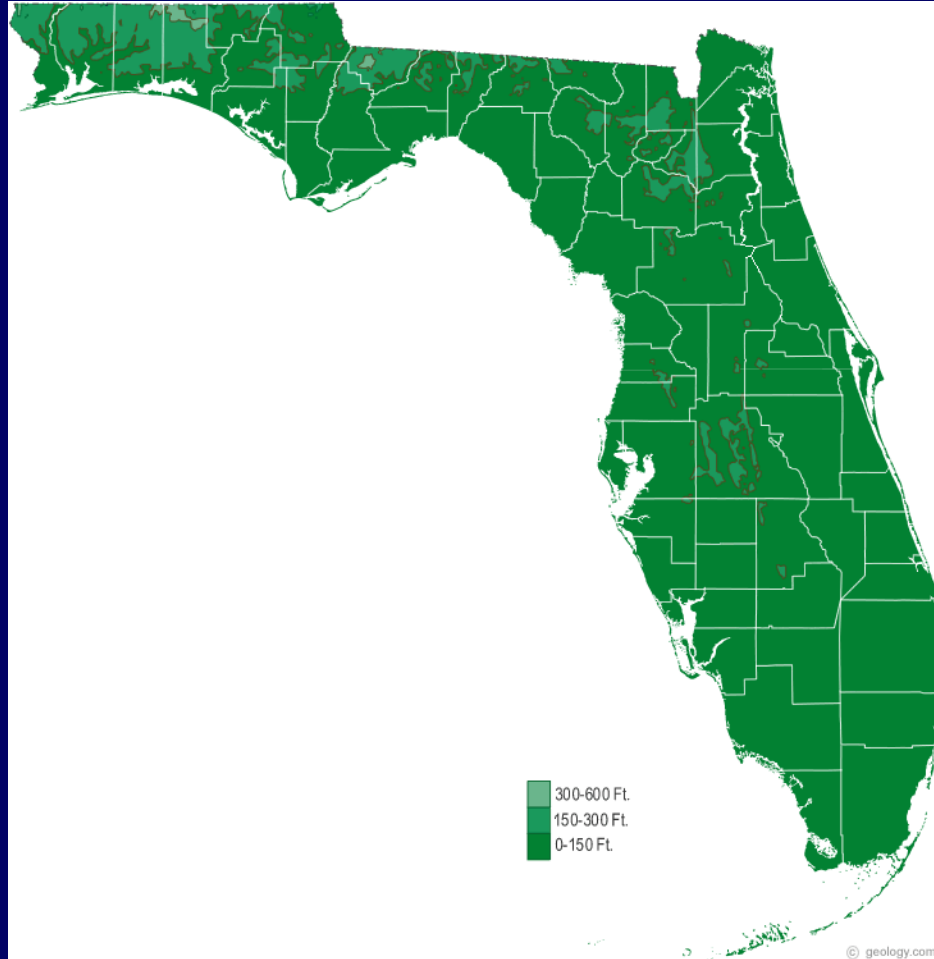


Malin – Round Mt. 500 kV Trips

June 18, 2007



“The MRI of Power Systems”



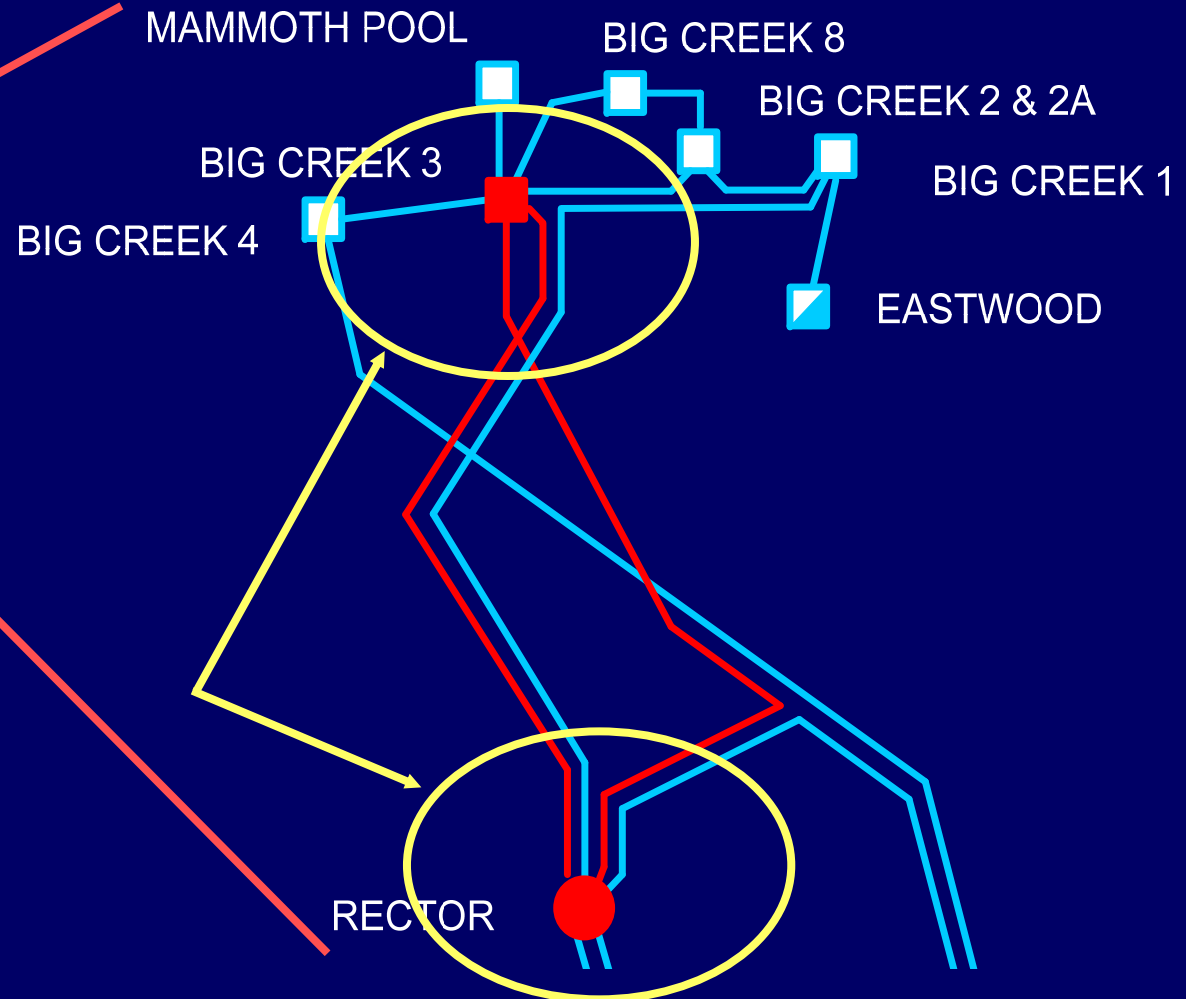
NERC press release
on Florida outage
Feb. 26, 2008:

*Synchrophasors are “Like
the MRI of bulk power
systems”*

Synchrophasor-Based Control – Now a Reality



Big Creek Controls Rector Static VAR Compensator

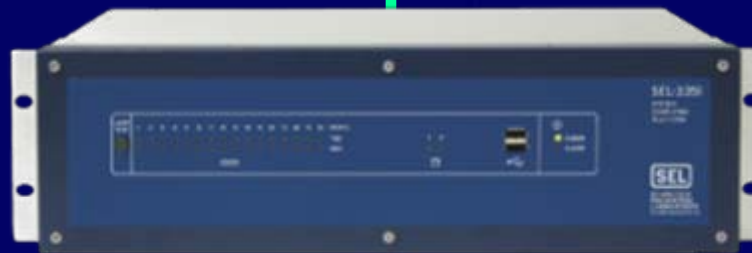


SCE Uses C37.118 From Relays and PMU

SCADA
Master

DNP3

Information
Processor



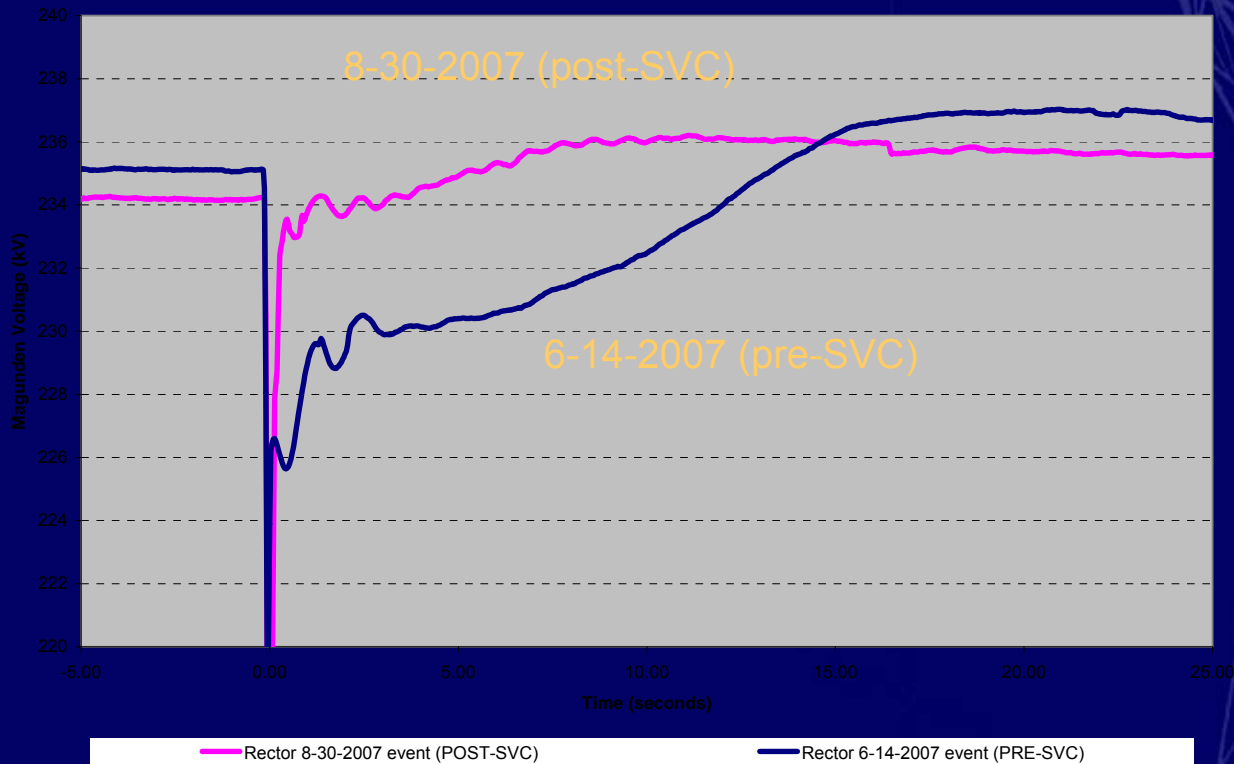
(Harris 5000/6000,
IEC 60870-103,
Modbus, SEL Fast
Message, SES 92,
Telegyr 8979,
Conitel 2020,
GETAC, Recon 1.1,
CoDeSys, OPC, ...)

IEEE C37.118



Impact of the Rector SVC: 6-14-07 (pre-SVC) vs. 8-30-07 (post-SVC)

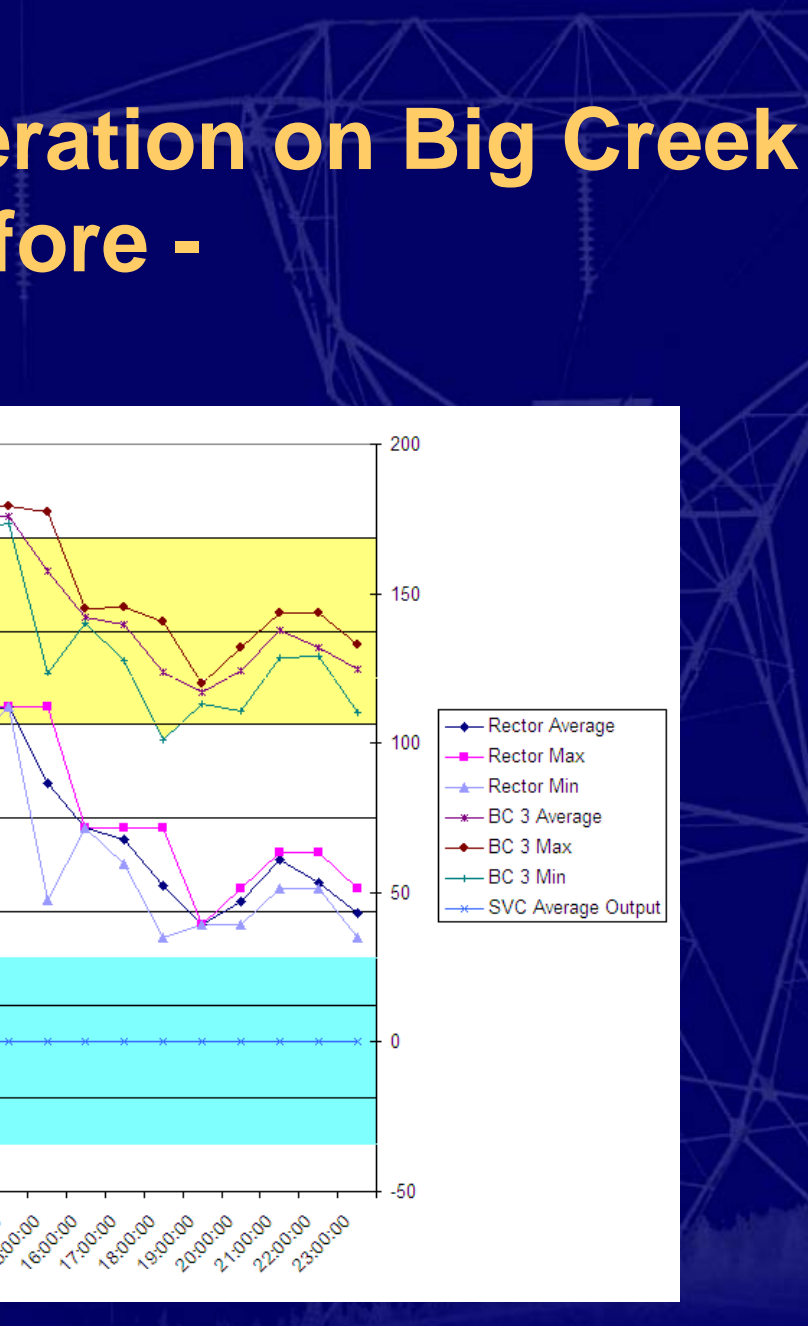
Magunden Substation Voltage Comparison
(Rector Substation Events 6-14-07 and 8-30-07)



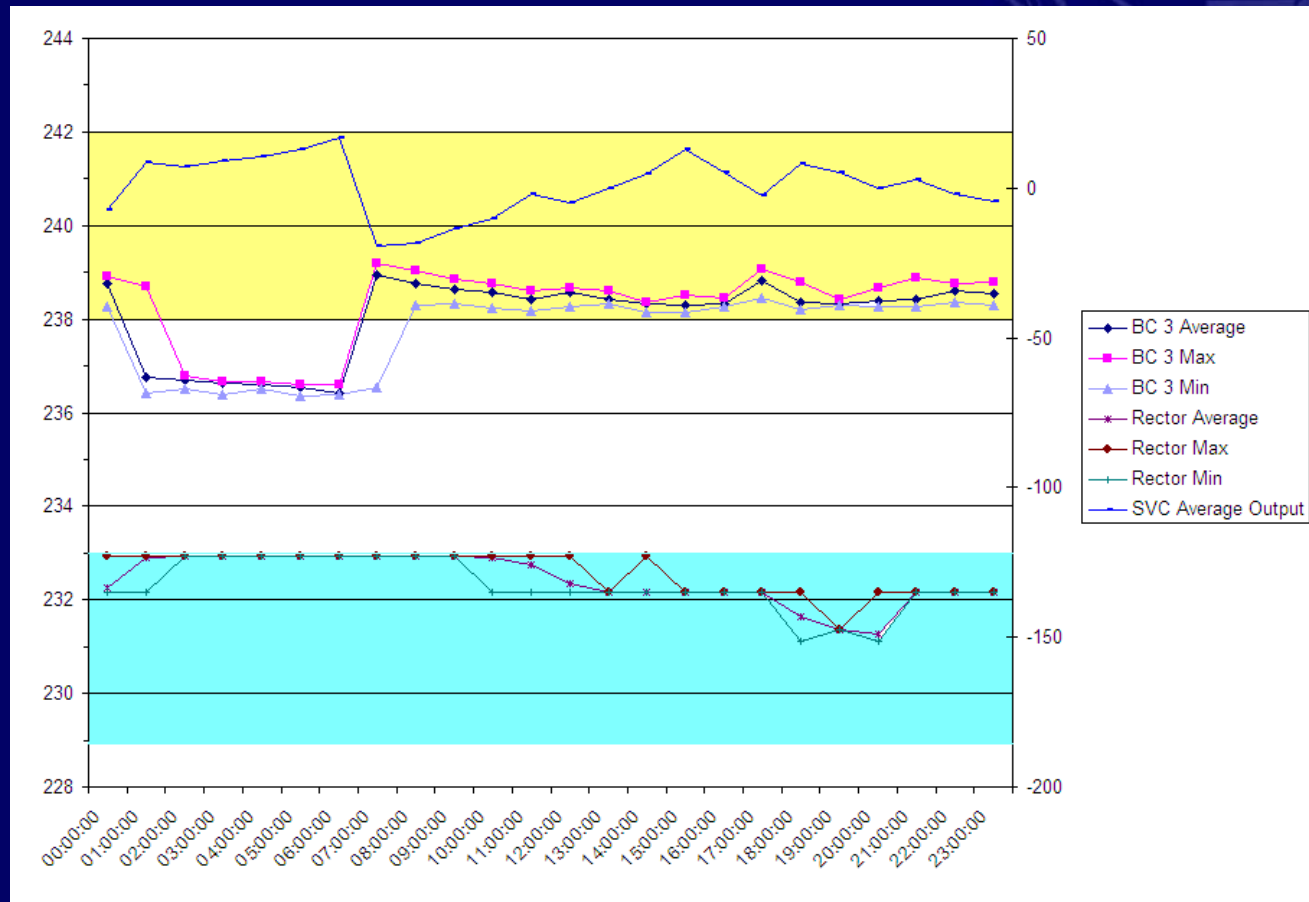
NOTE: Voltages shown were measured ~70 miles south of Rector Substation (actual low voltage event was of greater magnitude at Rector substation itself)

The Rector SVC had the apparent effect of reducing the magnitude & duration of the fault-induced slow voltage recovery...

Operation on Big Creek before -

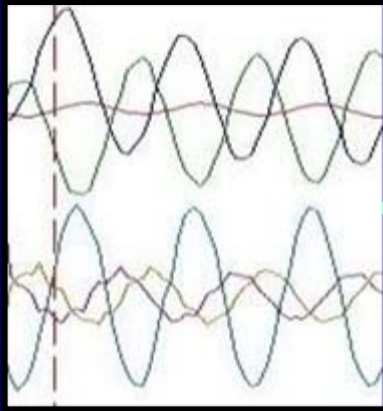


Effect of SVC Operation on Big Creek After -



Synchronous Vector Processing

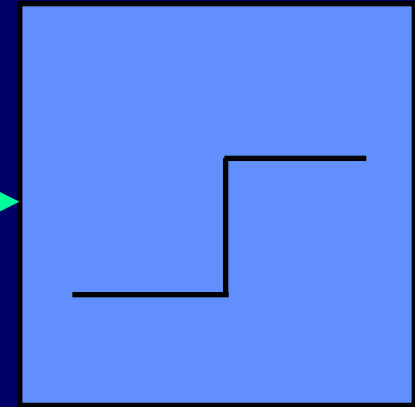
System
Measurement



Function
Calculation



Output
Designation



Send Control to System
(Application)



Apply the **SVAP**

- Collect synchronous phasor measurements
- Collect logical inputs
- Perform vector and scalar math
- Make decisions
- Produce outputs
- Report data

Select Quantities From Each PMU



PMU1

PMU2

PMU3

Analogs

$|V_1|$

$\angle V_1$

$|I_1|$

$\angle I_1$

Freq

PSV42

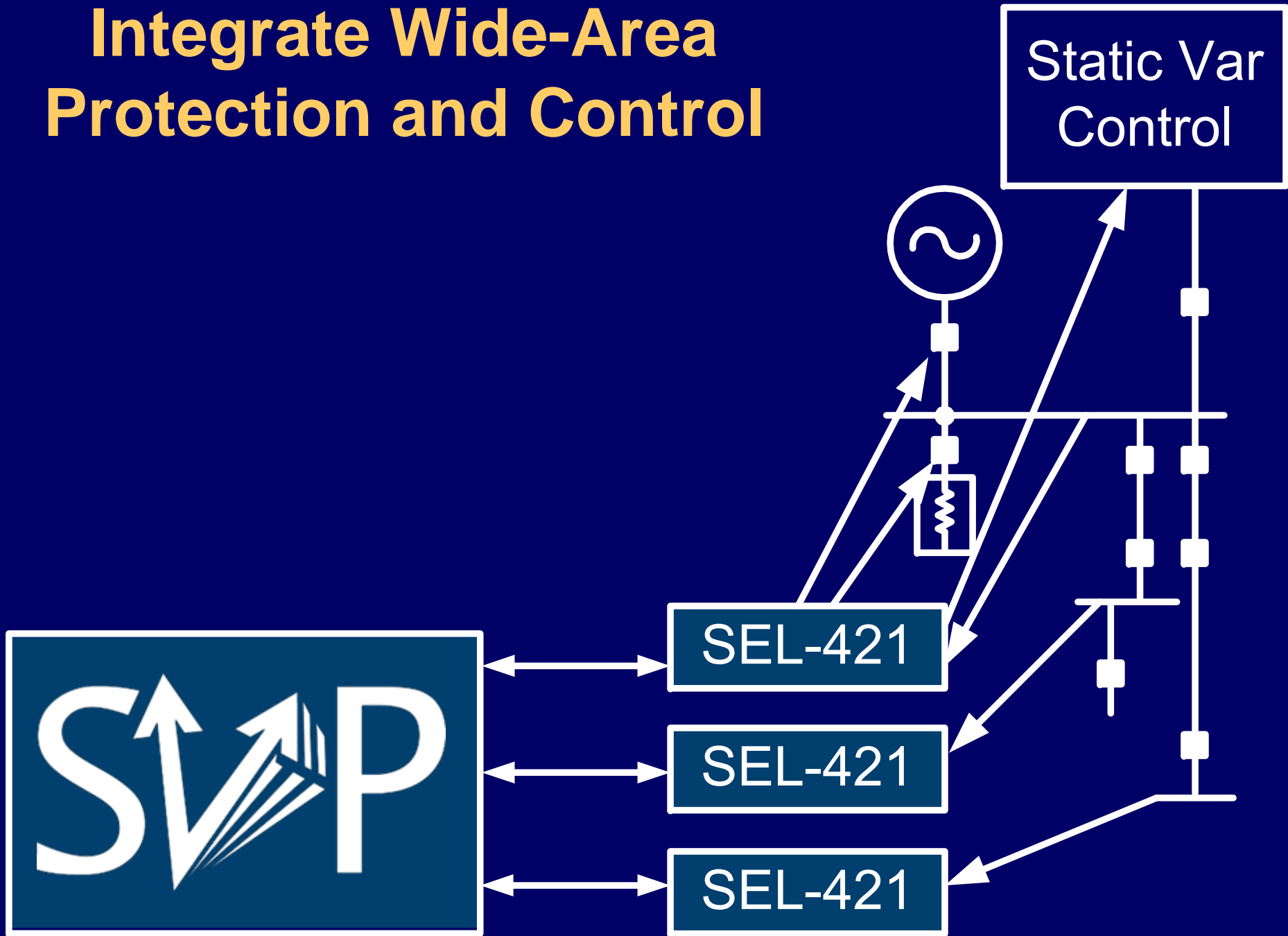
TE (time error)

Binary data

Status

Triggers

Integrate Wide-Area Protection and Control



Apply Flexible Function Calculations

IEC 61131 engine

Math

Trig

Differentials

Preprogrammed blocks

Power

Angle difference

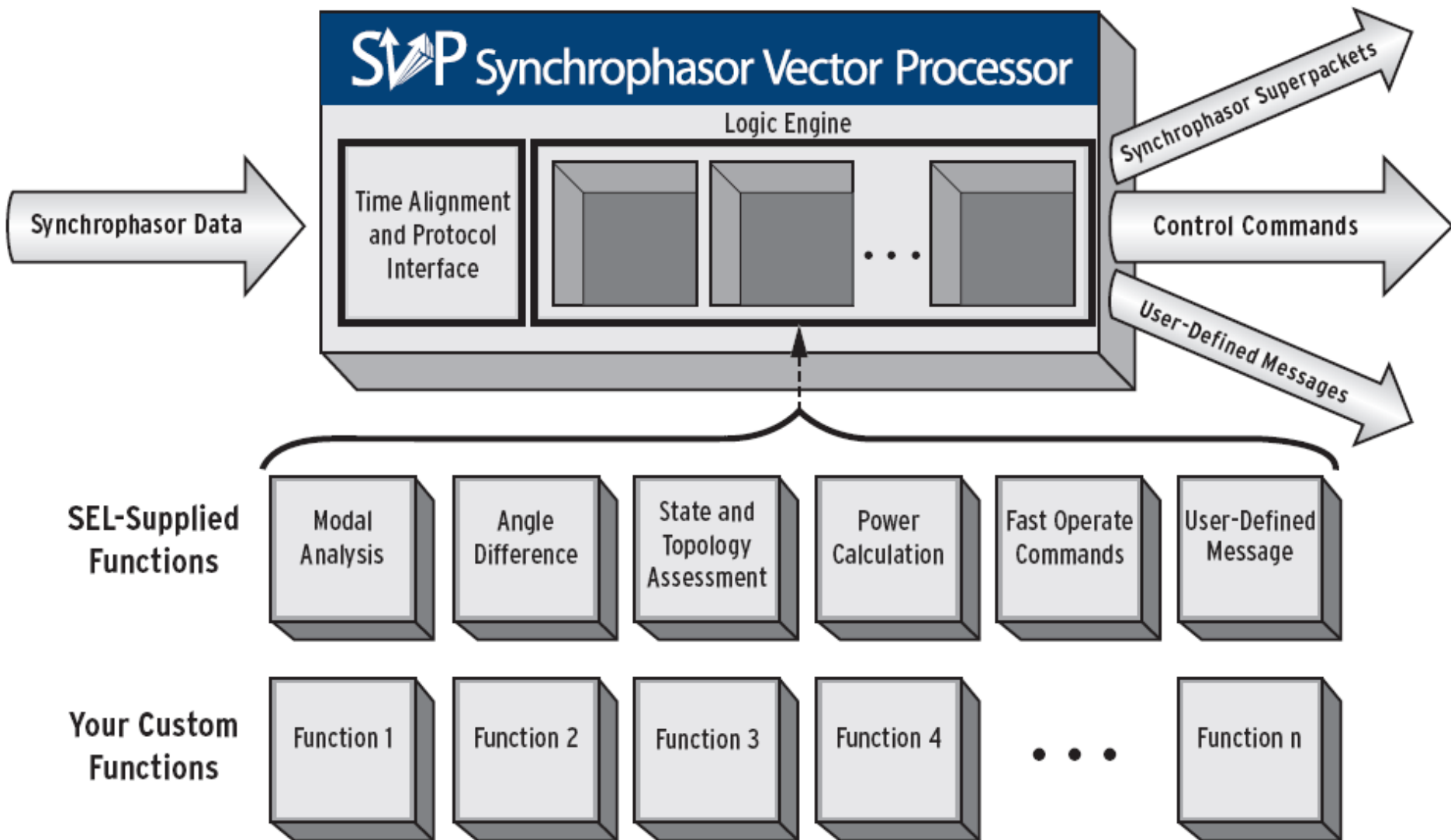
Modal analysis

Station topology check

The image displays a collage of mathematical formulas, likely related to calculus and probability theory. The formulas are written in a stylized, handwritten font on a dark background. The visible formulas include:

- $$\frac{\partial}{\partial \theta} M T(\xi) = \frac{\partial}{\partial \theta} \int_{R_n} T(x) f(x, \theta) dx = \int_{R_n} \frac{\partial}{\partial \theta} T(x) f(x, \theta) dx$$
- $$\frac{\partial}{\partial a} \ln f_{a, \sigma^2}(\xi_1) = \frac{(\xi_1 - a)}{\sigma^2} f_{a, \sigma^2}(\xi_1) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{(\xi_1 - a)^2}{2\sigma^2}\right\}$$
- $$\int_{R_n} T(x) \cdot \frac{\partial}{\partial \theta} f(x, \theta) dx = M\left(T(\xi) \cdot \frac{\partial}{\partial \theta} \ln L(\xi, \theta)\right)$$
- $$\int_{R_n} T(x) \cdot \left(\frac{\partial}{\partial \theta} \ln L(x, \theta)\right) \cdot f(x, \theta) dx = \int_{R_n} T(x) \cdot \left(\frac{\frac{\partial}{\partial \theta} f(x, \theta)}{f(x, \theta)}\right) \cdot f(x, \theta) dx$$
- $$\frac{\partial}{\partial \theta} M T(\xi) = \frac{\partial}{\partial \theta} \int_{R_n} T(x) f(x, \theta) dx = \int_{R_n} \frac{\partial}{\partial \theta} T(x) f(x, \theta) dx$$
- $$1 \cdot \exp\left\{-\frac{(\xi_1 - a)^2}{2\sigma^2}\right\} \cdot \frac{\partial}{\partial a} \ln f_{a, \sigma^2}(\xi_1) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{(\xi_1 - a)^2}{2\sigma^2}\right\} \cdot \frac{(\xi_1 - a)}{\sigma^2}$$

Combine Pre-Configured with Custom Functions





Provides Function Blocks

PMCU_IN

EN: BOOL

OK: BOOL

IDCODE: UINT

SOC: UDINT

FOS_USEC: UDINT

TQ: USINT

NUM_PI: UINT

NUM_AI: UINT

NUM_DWI: UINT

DATA_RATE: INT

STATUS: PMCU_STATUS

PI: ARRAY [1..12] OF PMCU_PHASOR

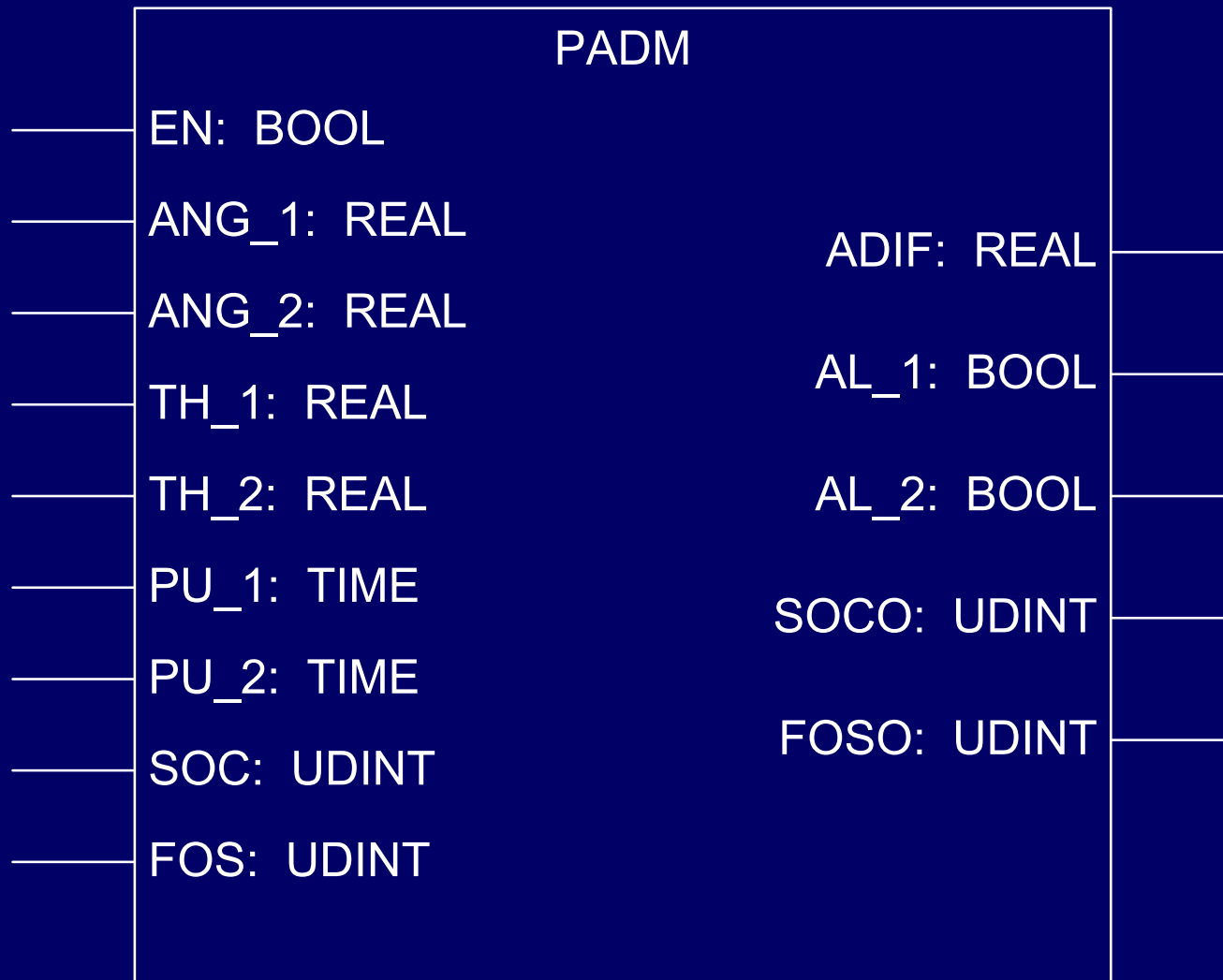
AI: ARRAY [1..8] OF REAL

DWI: ARRAY [1..2] OF PMCU_DIGITAL

FREQ: REAL

DFDT: REAL

Map PMU Quantities to Phase Angle Difference Monitor



Phase Angle Difference Monitor



V1M:291337.3 V

V1A:-94.9 deg

Freq:60.00 Hz

V1M:291337.3 V

V1A:-94.9 deg

Freq:60.00 Hz

Phase Angle Difference Monitor



angdiff:-23.910

Threshold1:20

Threshold2:30

TIMER1:T#16ms

TIMER2:T#8ms

PADMOK

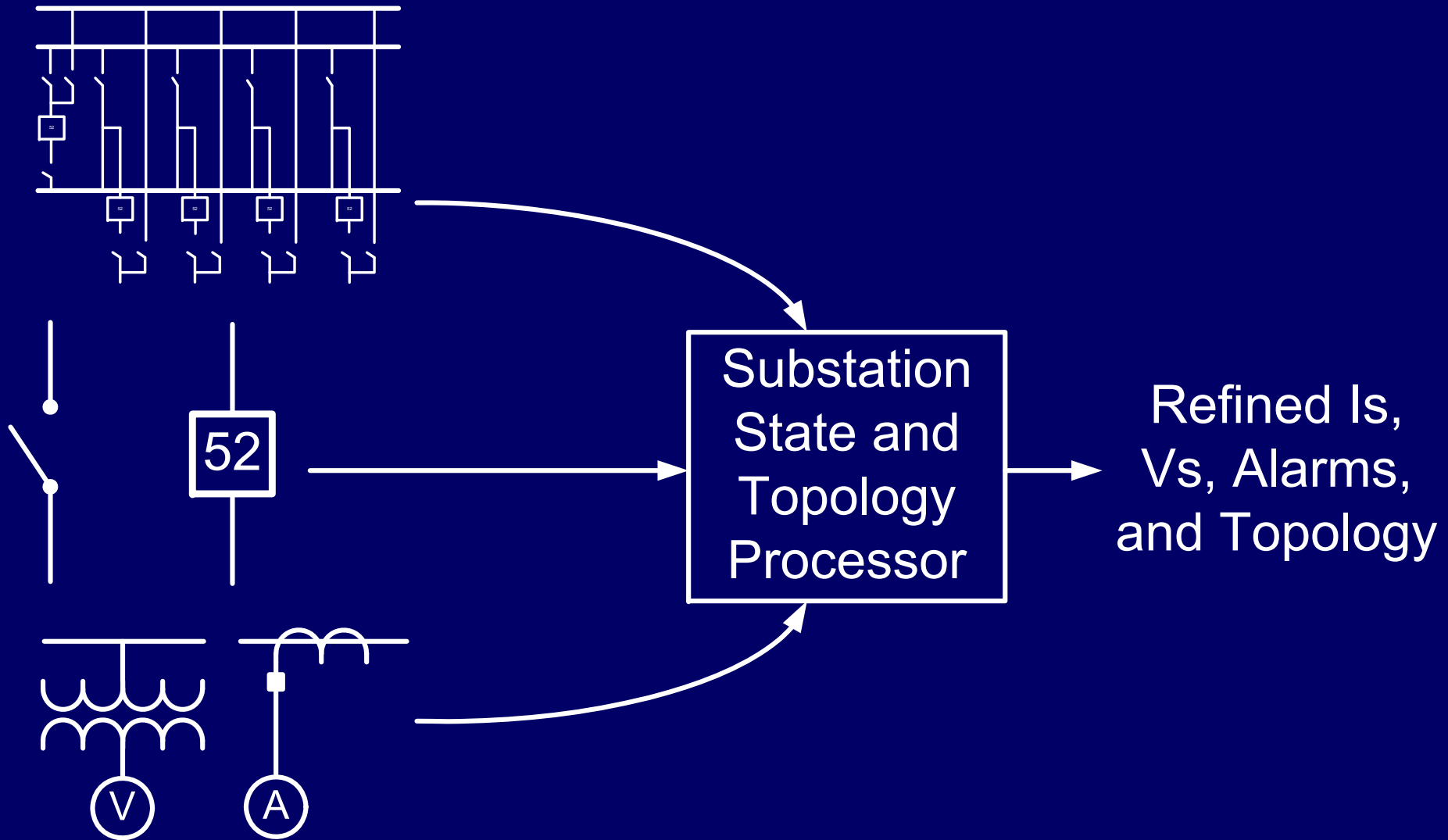
LEVEL 1

LEVEL 2

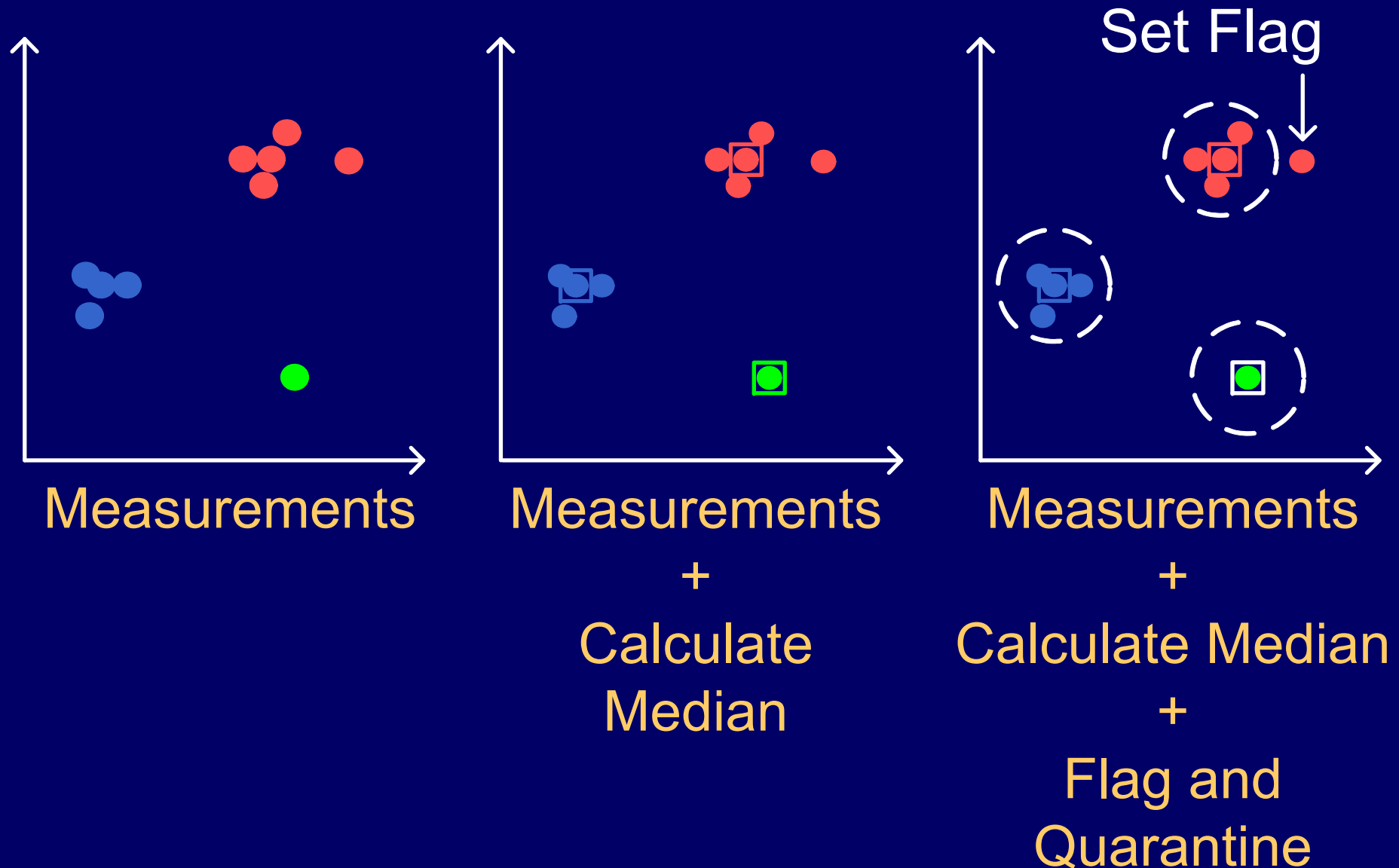
SOC:1191885889

FOS:950000

Improve Local Measurements



Identify and Quarantine Bad Data



Multiple Measurement Consistency Check

Phase A

Phase B

Phase C

Measurement 1



Measurement 2



Kirchoff consistency check

Phase A

Phase B

Phase C



Sequence Alarm

Zero Seq



Pos Seq



Neg Seq



Unbalance Alarm



IA

0.00 A 0.00 deg

IB

0.00 A 0.00 deg

IC

0.00 A 0.00 deg

IO

0.00 A 0.00 deg

I1

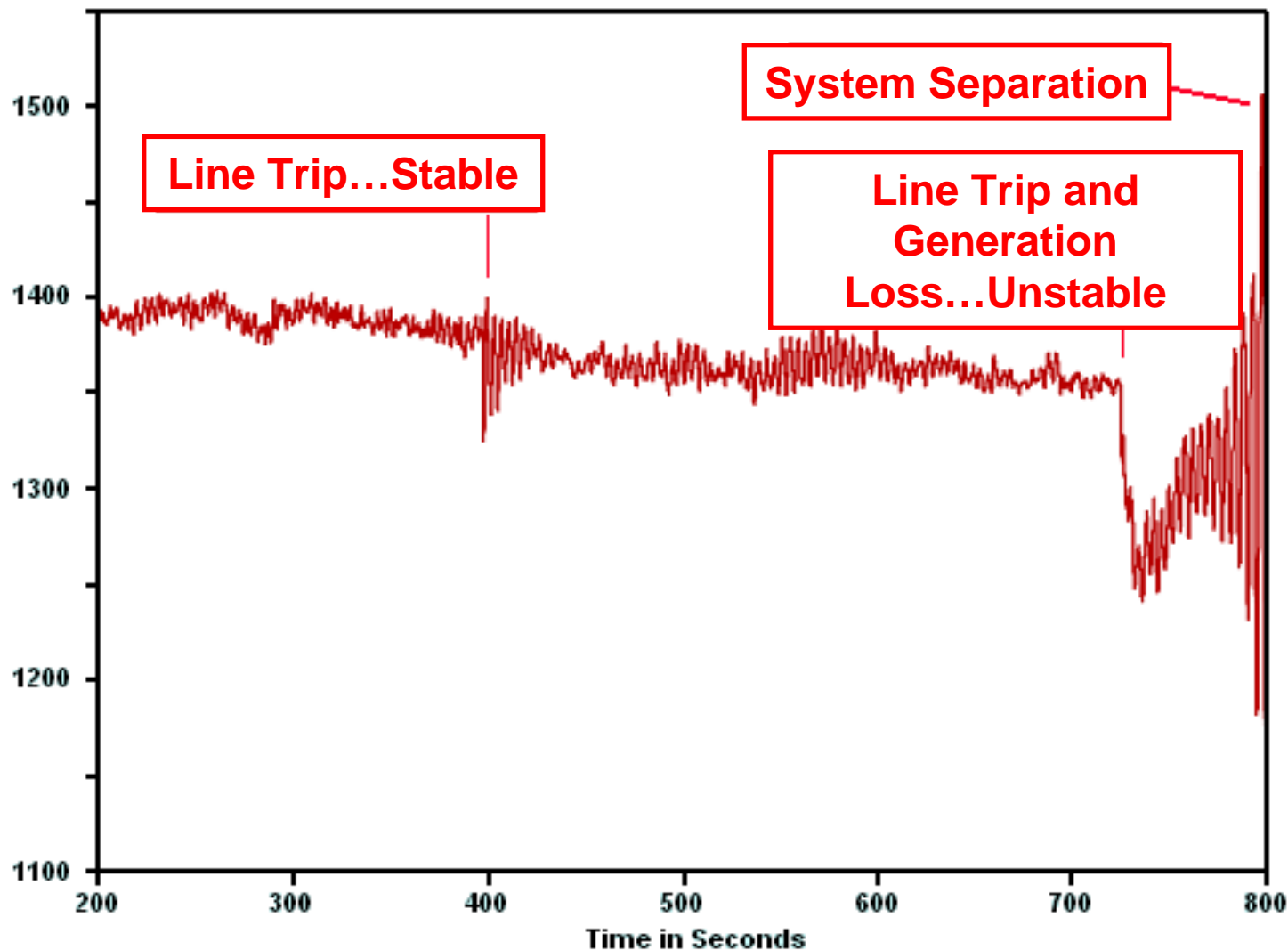
1.00 A 0.00 deg

I2

0.00 A 0.00 deg

Back to SSTP

Real-Time Modal Analysis Monitor Predicts System Disturbances



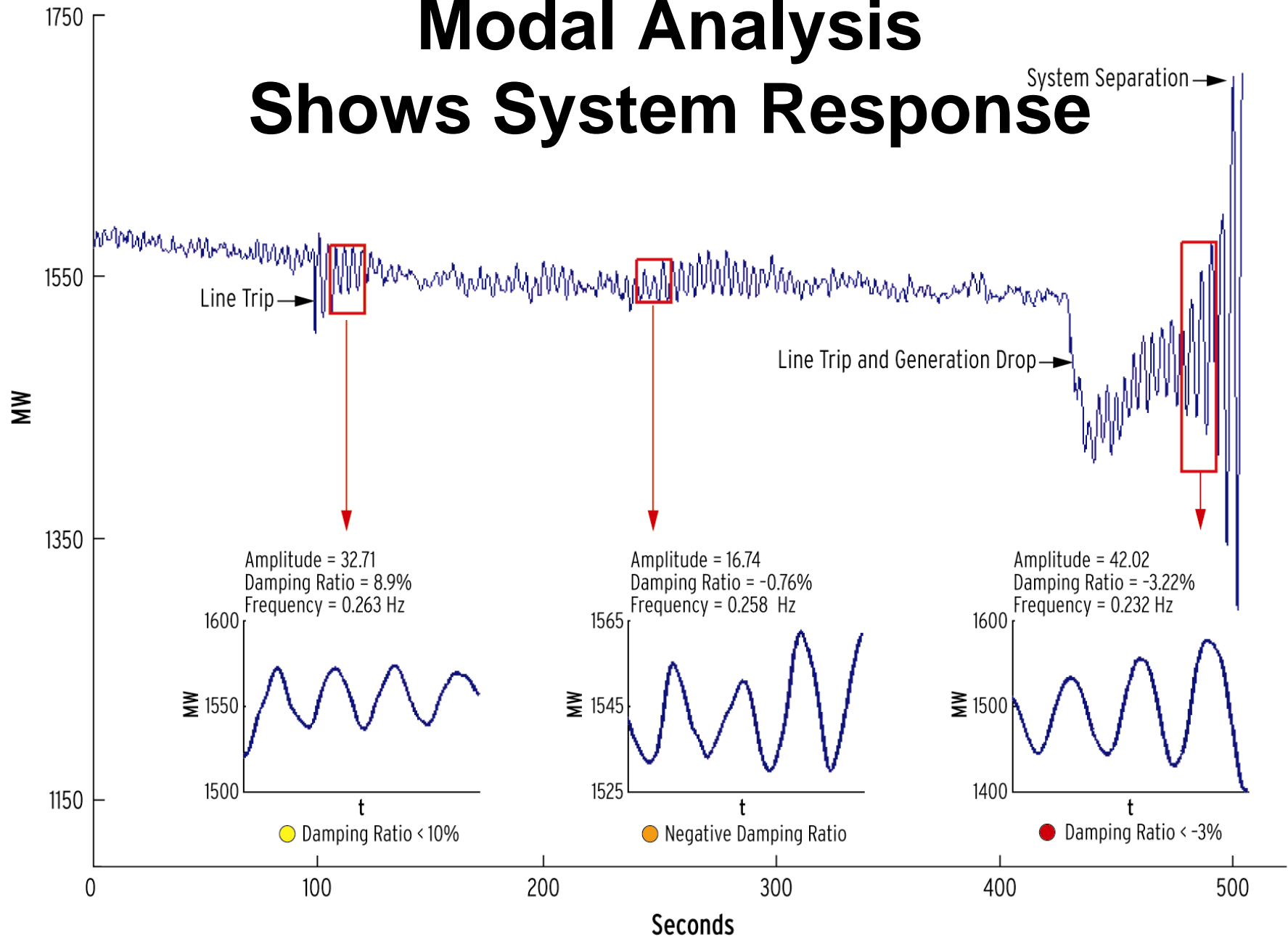
Use Oscillation Frequency and Damping Ratio

For the complex Eigen value pair: $\lambda = \sigma \pm j\omega_d$

Oscillation frequency is: $f_{\text{osc}} = \frac{\omega_d}{2\pi}$

Damping ratio is: $\zeta = -\frac{\sigma_i}{\sqrt{\sigma^2 + \omega_i^2}}$

Modal Analysis Shows System Response

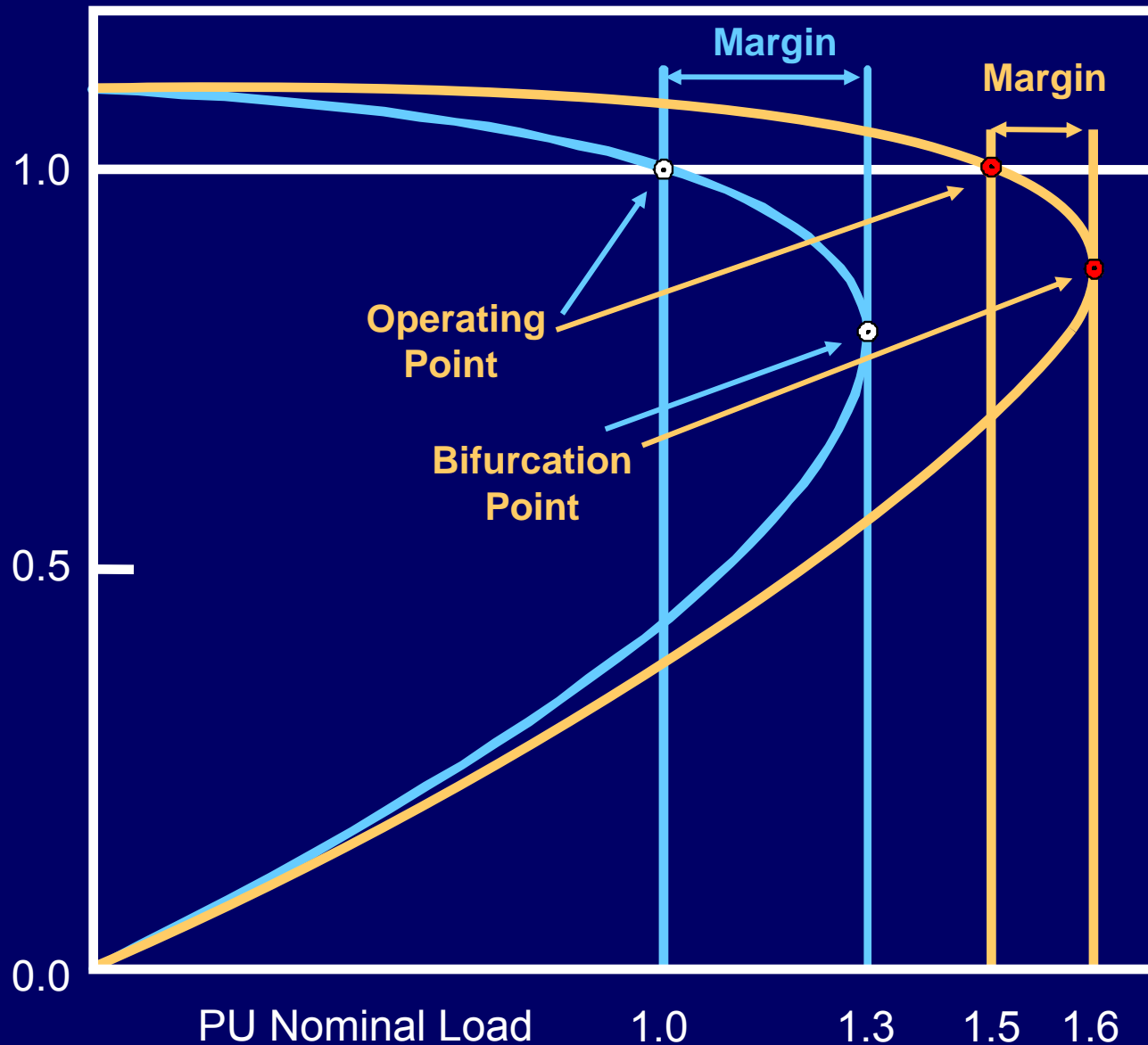


Develop Custom Applications

- Voltage Collapse Detection
- Instability of Distributed Generation
- Complex Power Swings
- Others ?



Utilities Are Operating Closer to the Edge



Long Island: Monitor Angles Between Transmission Distribution Buses to Detect and Prevent Voltage Collapse



Calculate Voltage Stability Index (VSI)

- SVP calculates maxima: P, Q, and S
- Calculate margins:

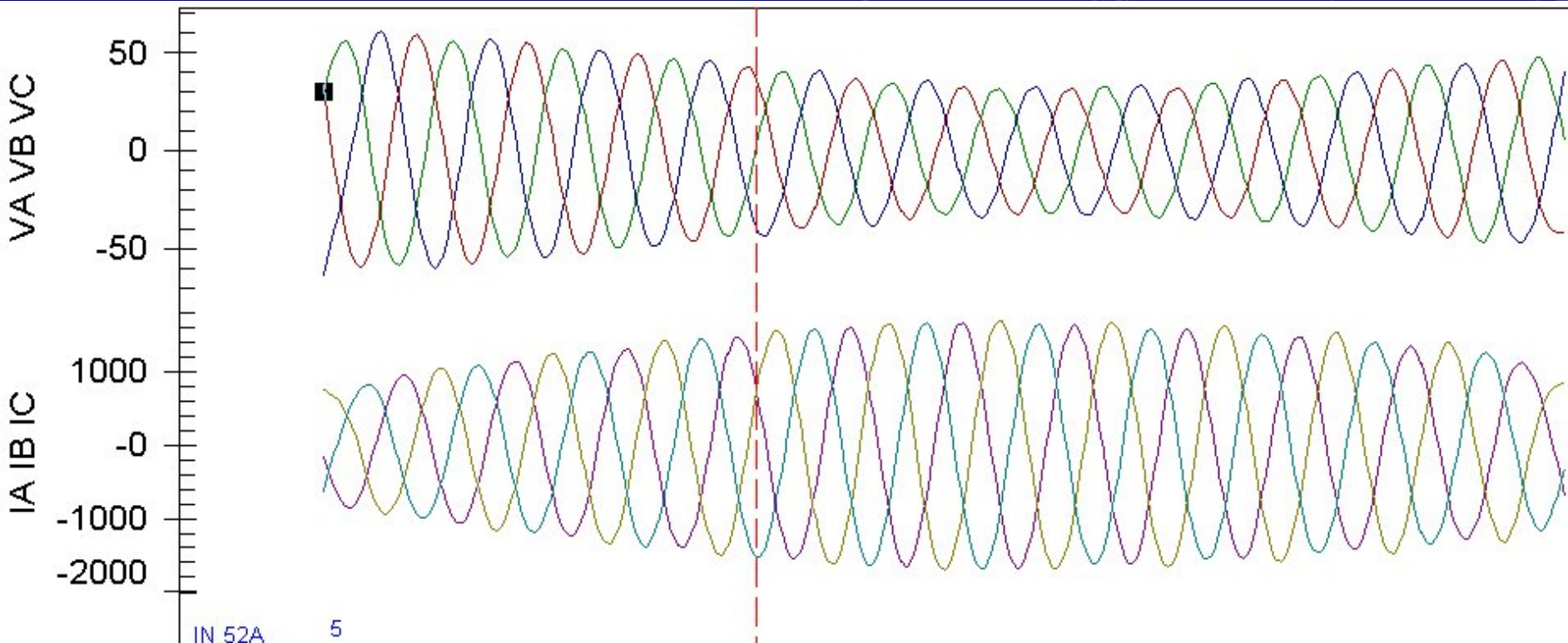
$$P_{\text{margin}} = P_{\text{max}} - P$$

$$Q_{\text{margin}} = Q_{\text{max}} - Q$$

$$S_{\text{margin}} = S_{\text{max}} - S$$

$$VSI = \min \left(\frac{P_{\text{margin}}}{P_{\text{max}}}, \frac{Q_{\text{margin}}}{Q_{\text{max}}}, \frac{S_{\text{margin}}}{S_{\text{max}}} \right)$$

Improve Power Swing Detection

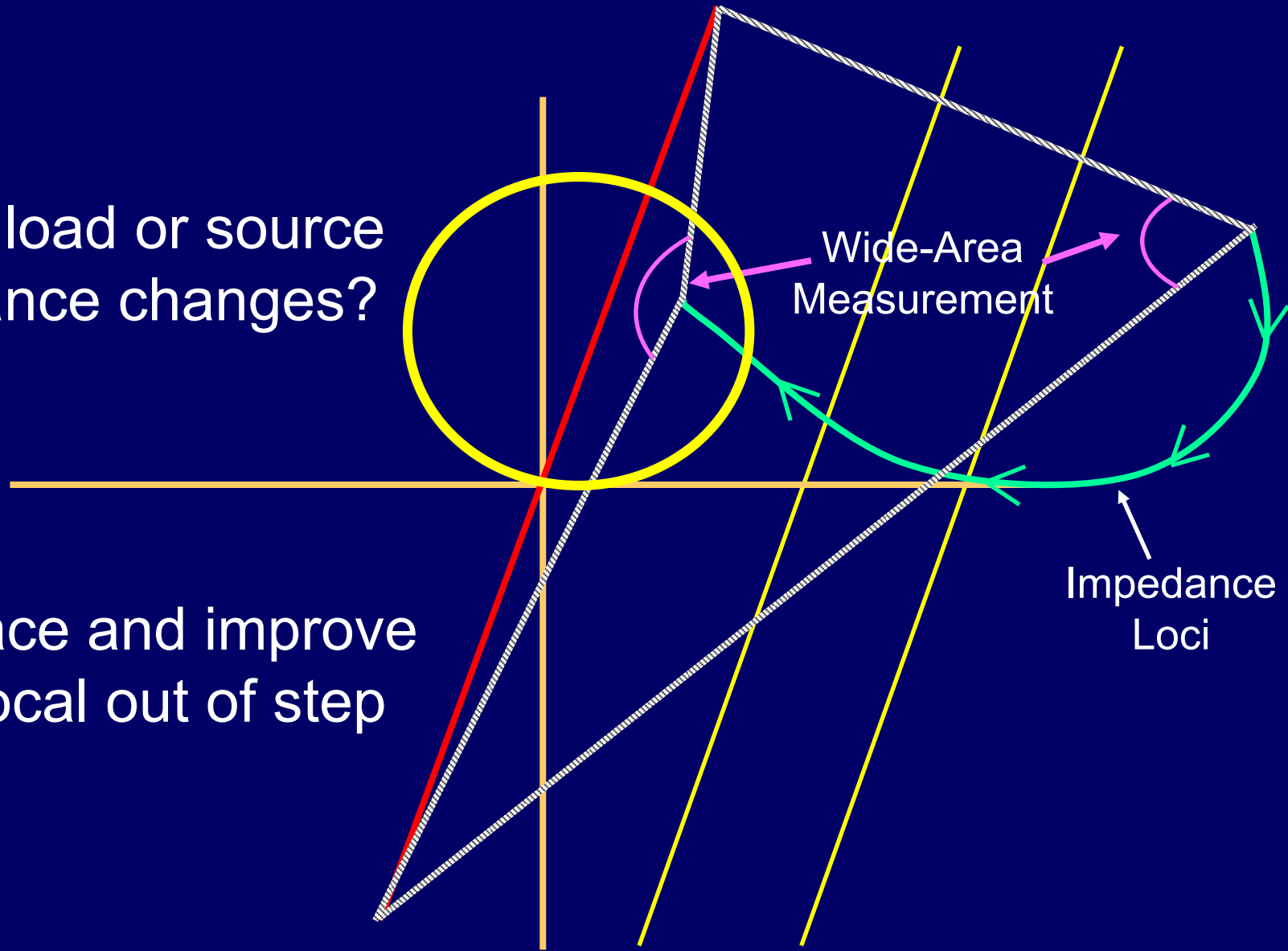


Actual Swing from 2003 Blackout

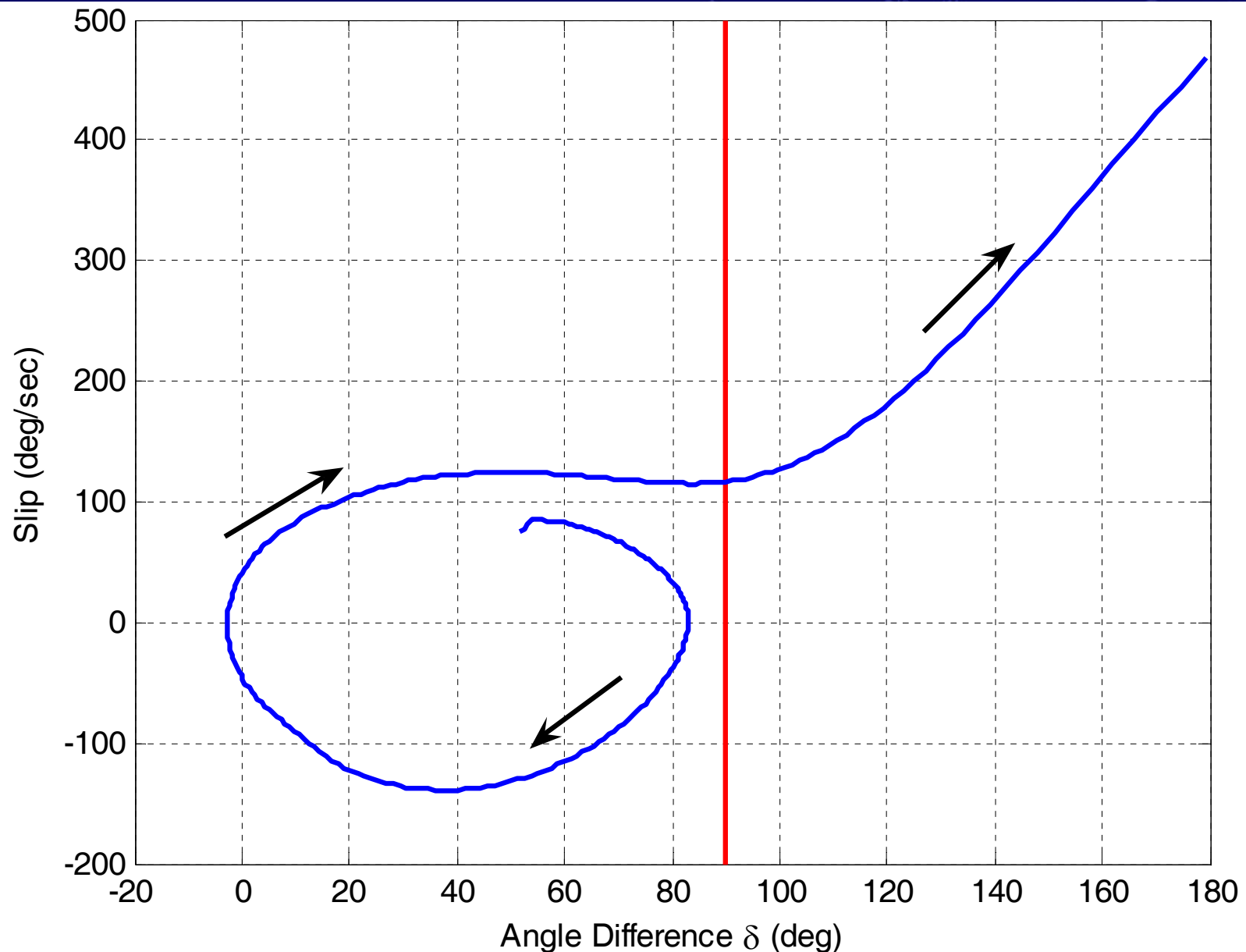
Wide-Area Measurement Is Better than Traditional “Blinder” Methods

What if load or source impedance changes?

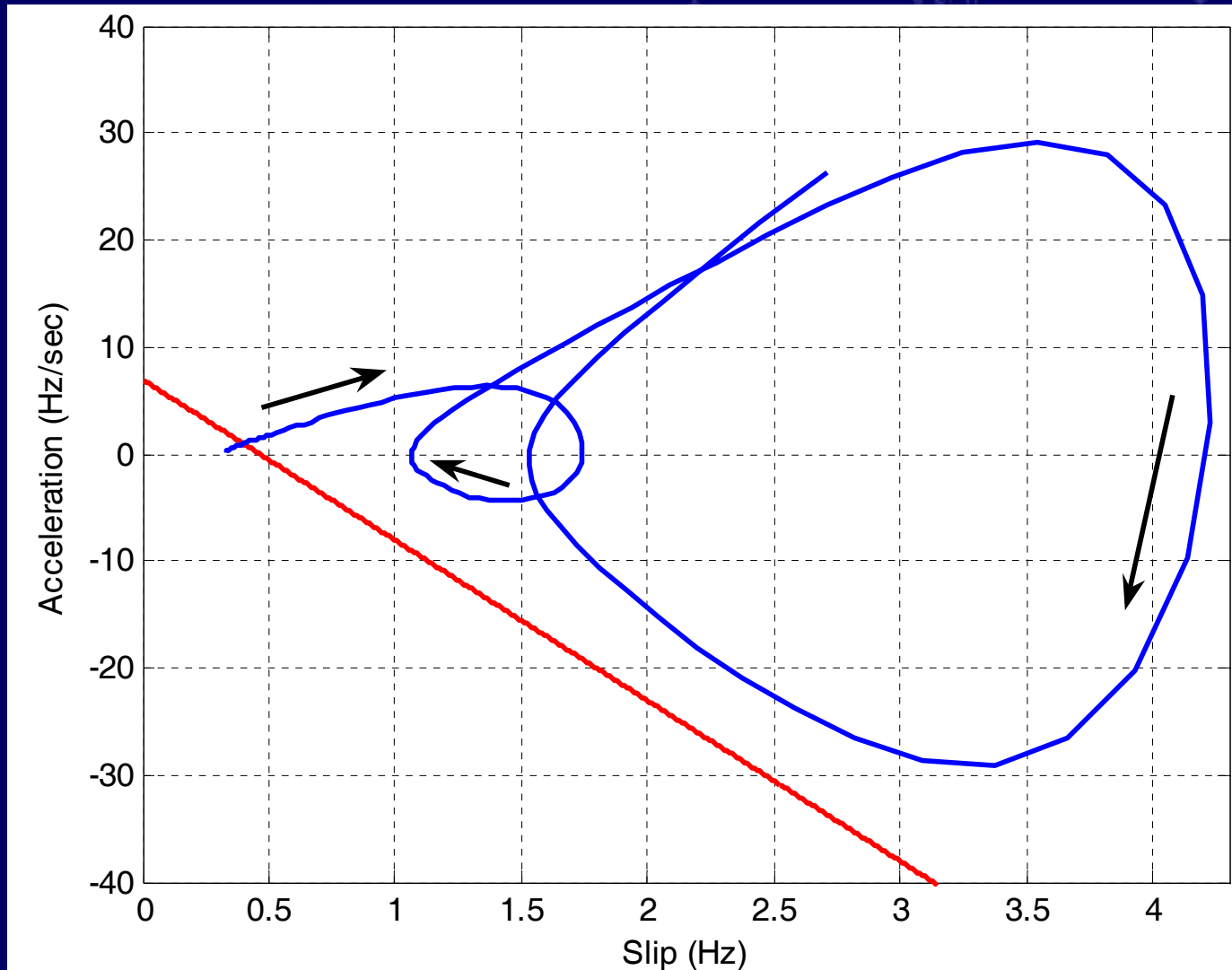
Replace and improve on local out of step



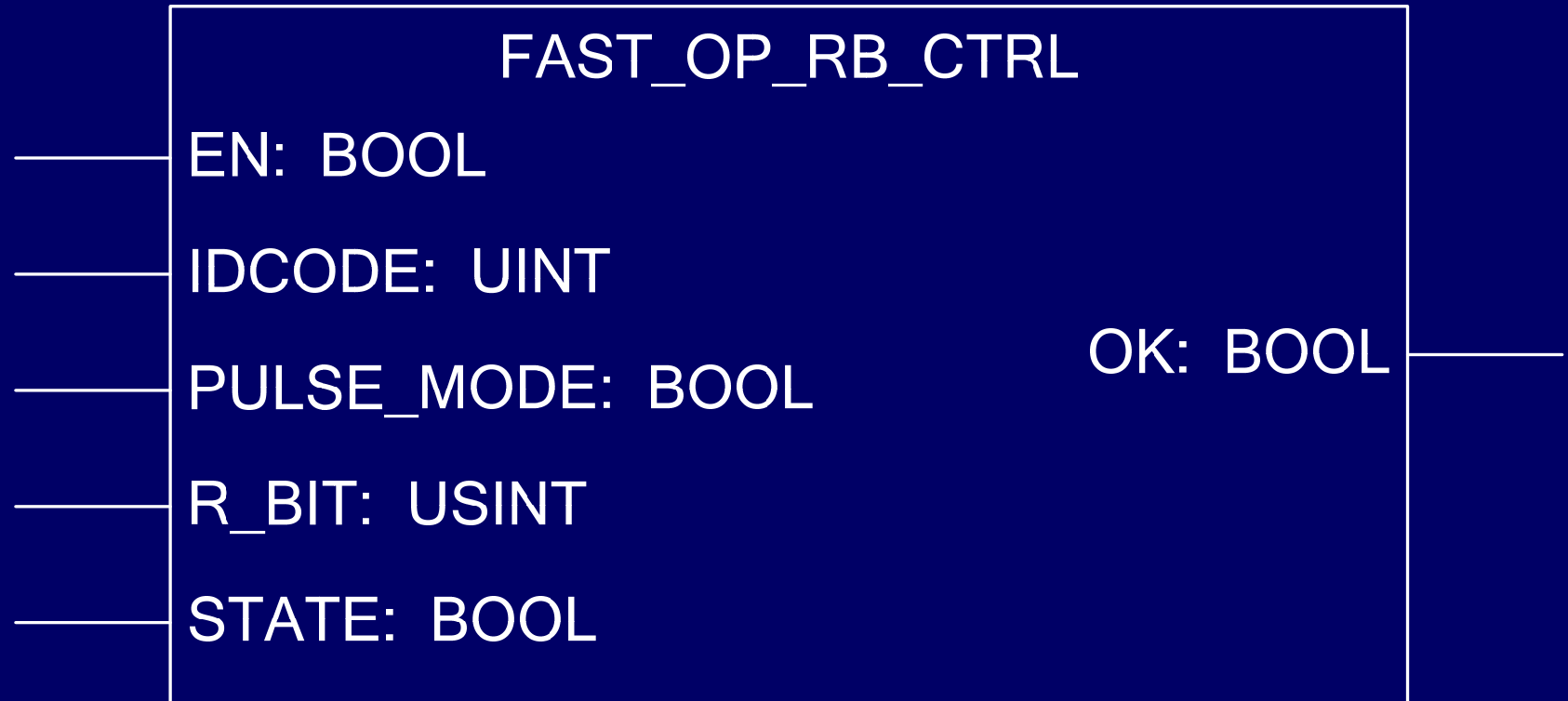
Delta/Delta-Dot Phase Plane Analysis



Delta-Dot Delta-Doubledot Phase Plane



Use Fast Operate Control Blocks for Closed-Loop Control



Synchrophasors Are Standard

SEL-421 IEEE C37.118

SEL-451

SEL-487E

NEW!

SEL-787

SEL-734 SEL Fast Message

SEL-311A, B, C

SEL-311L

SEL-351

SEL-351S

SEL-351A



Synchrophasors Provide New and Improved Capabilities

- Angle measurement
- Disturbance analysis
- Modal analysis
- Out-of-step detection
- Real-time control



What Else Can They Do For You?

Thank You!

