

# DYNAMIC MODEL VALIDATION LEVERAGING AMI 2.0 POINT-ON-WAVE MEASUREMENTS



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**U.S. DEPARTMENT OF  
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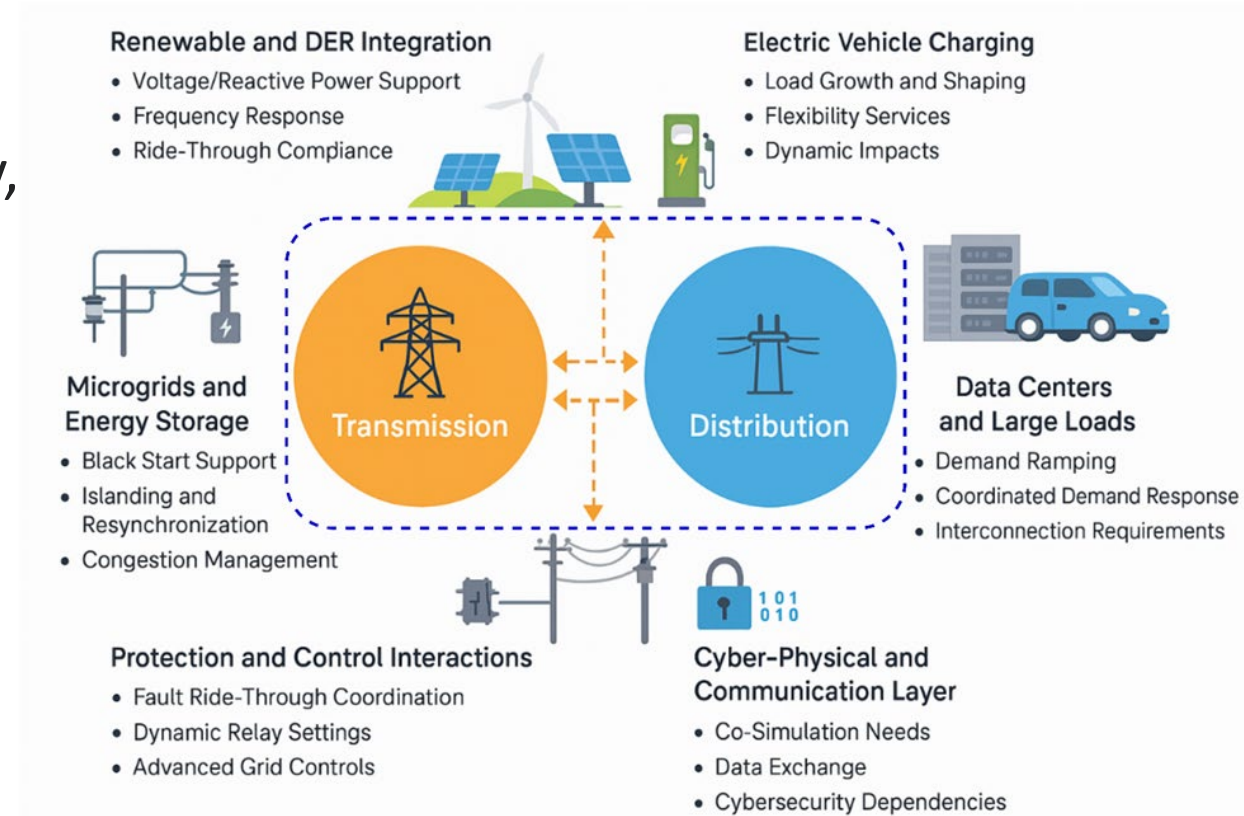


# OUTLINE OF THE TALK

- Introduction
- Motivation
- Processing AMI 2.0 data for Model Identification
- Aggregation of Distribution System.
- Identification of aggregated distribution system models using AMI data.
- Conclusion.

# INTRODUCTION

- Generation evolution with inverter-based resources (IBRs).
- Distribution system evolution with distributed generation (DG) like solar, battery, smarter loads that are responsive to price signals and grid disturbances.
- Development of microgrids that can operate in the islanded and interconnected modes to ensure its stable operation, etc.;
- Evolution in sensor deployment like phasor measurement units (PMUs) in T&D systems, advanced metering infrastructure, etc.;
- Evolution in data analytics and measurement-based controls; etc.



# INTRODUCTION

- **Market Access for DG Aggregations:** Enables aggregated DGs to participate in wholesale energy, capacity, and ancillary services markets
- **Aggregation Framework:** Allows multiple small distributed generation to be combined as a single market resource
- **Coordination with Distribution Utilities:** Requires coordination between: RTO/ISO ↔ Distribution Utility (DSO)
- **Performance & Visibility Requirements:** DER aggregations must meet same performance requirements as traditional resources



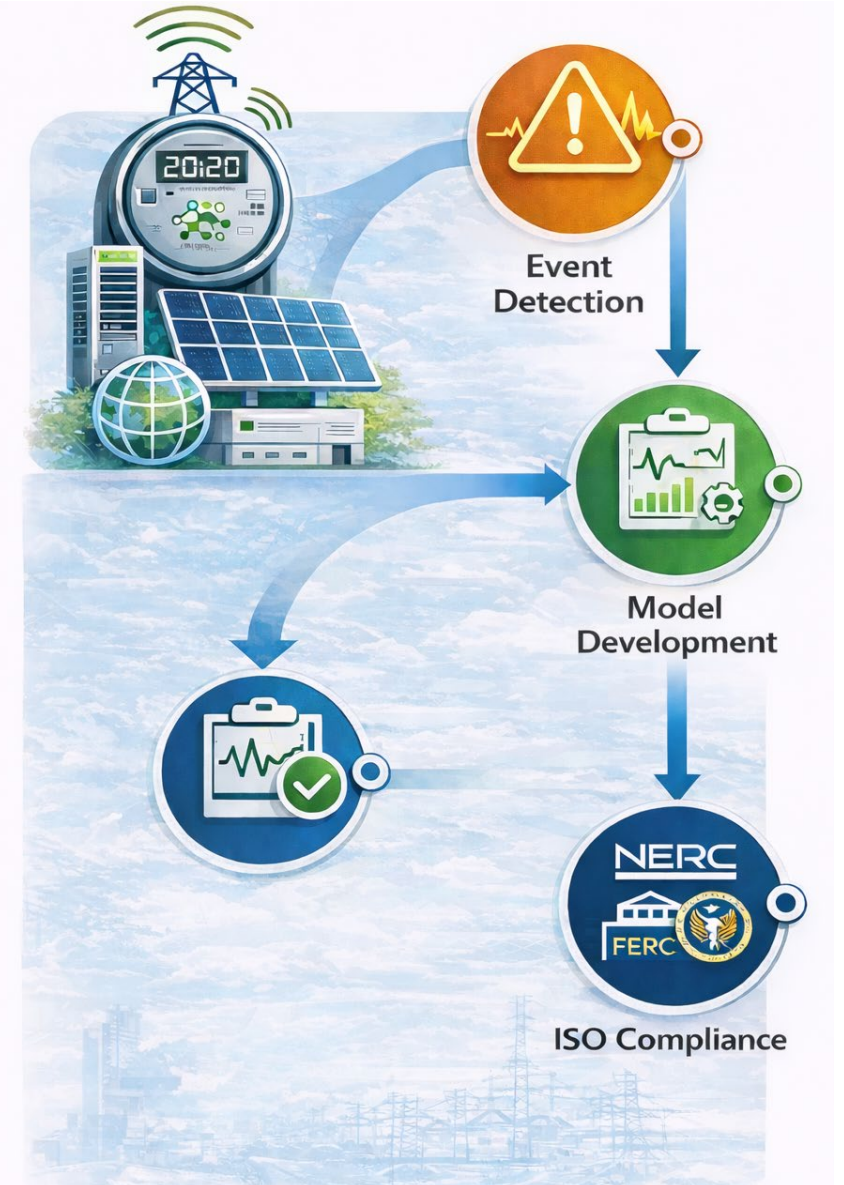
ISOs must have **sufficient visibility and data** to Model, dispatch and maintain reliability





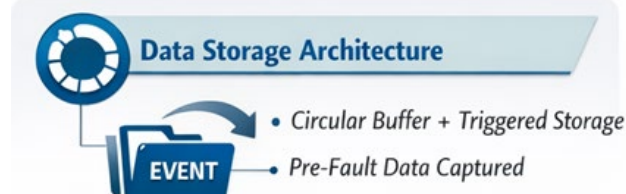
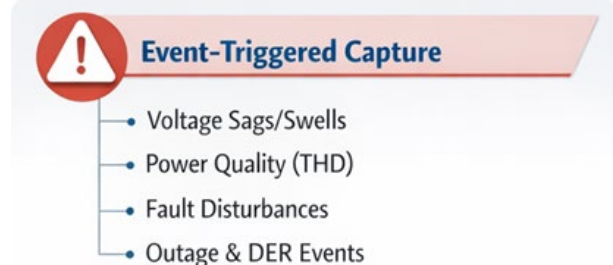
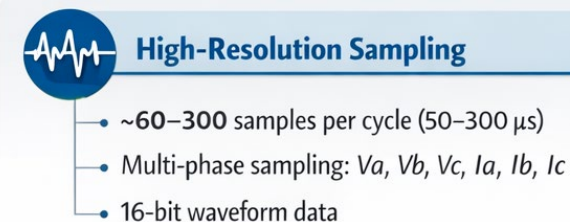
# MOTIVATION

- AMI 2.0 provides high-resolution **point-on-wave data** for accurate dynamic model development.
- Event-based measurements enable real disturbance **validation of distributed generation and load** models.
- Wide deployment offers **node-level observability** across distribution systems.
- AMI data helps characterize **aggregated DG** dynamic behavior and variability.
- Supports compliance with **NERC MOD-032** and **FERC 2222** model visibility requirements.



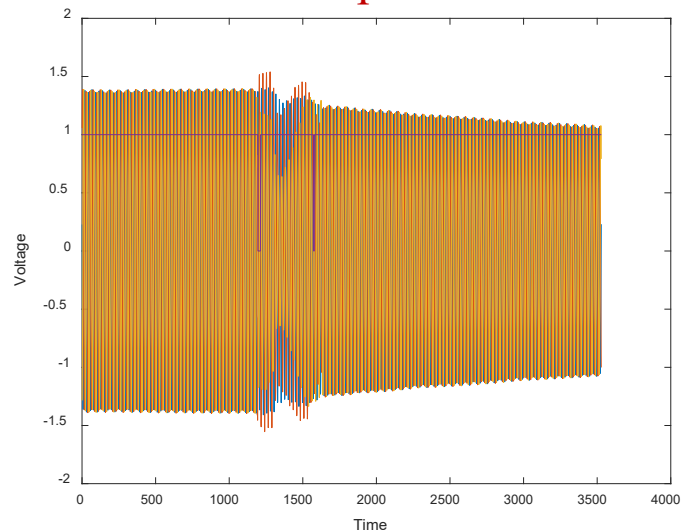
# AMI 2.0 MEASUREMENTS AND EVENT RECORDS

- Enables **continuous monitoring** of distribution system dynamics beyond traditional interval metering.
- Provides **localized insights** into feeder-level behavior and phase conditions.
- Supports **data-driven identification** of abnormal grid conditions and emerging issues.
- Enhances **visibility of DG** interactions with the distribution network.
- Improves **situational awareness** for operators through near real-time data streams.
- Serves as a foundation for **advanced analytics and grid digitalization** initiatives.

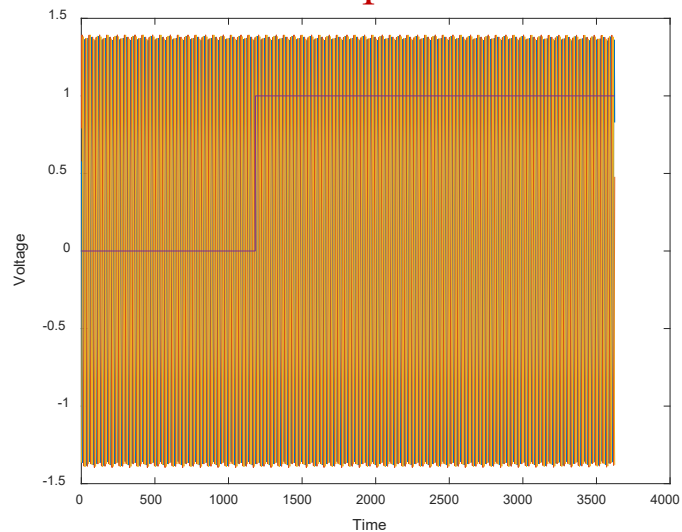


# SAMPLE RAW DATA

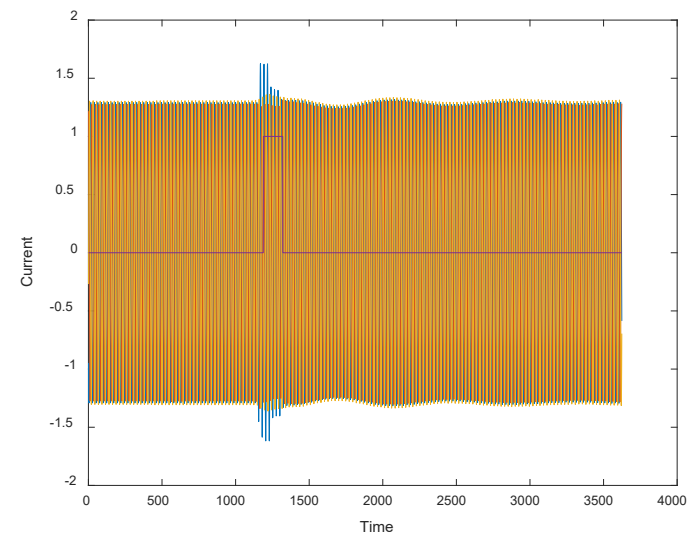
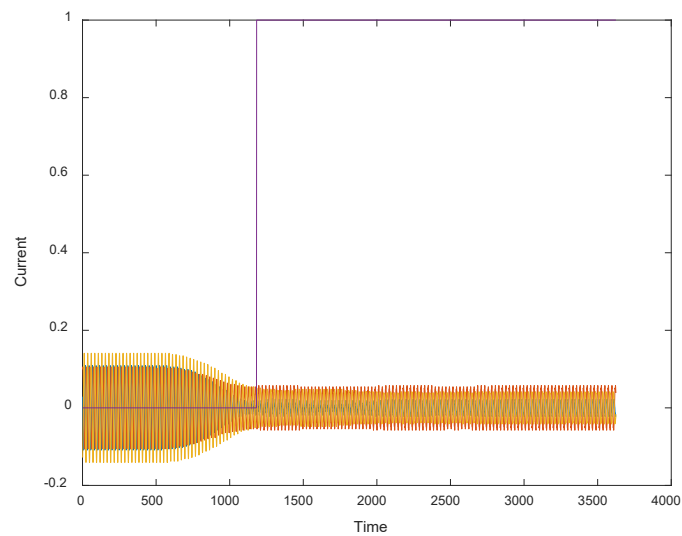
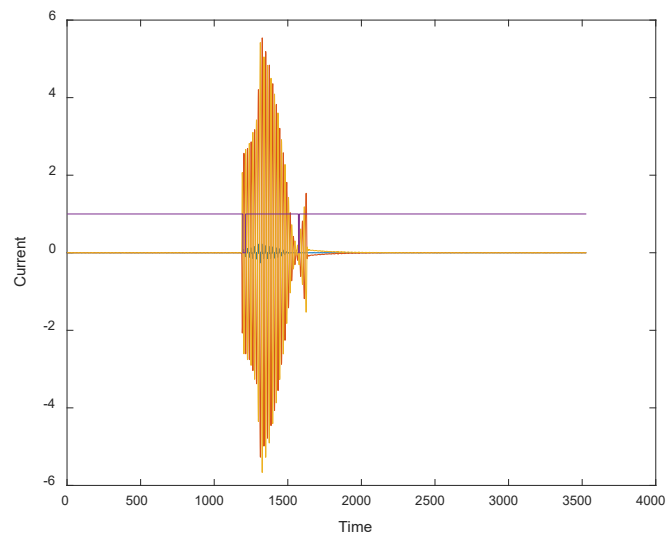
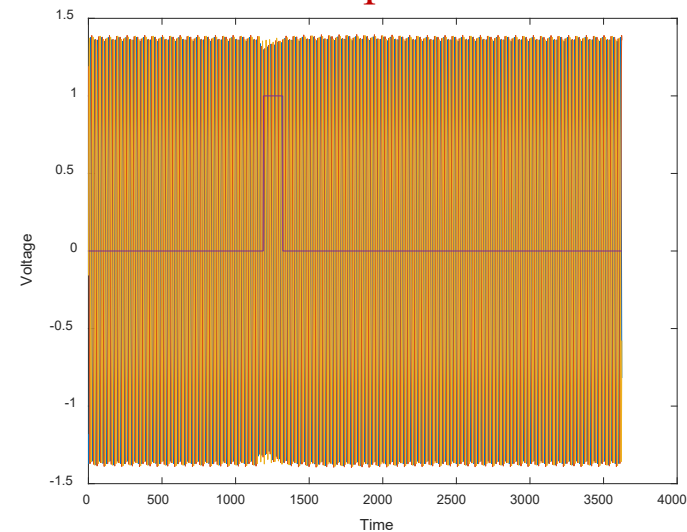
Sample 1



Sample 2

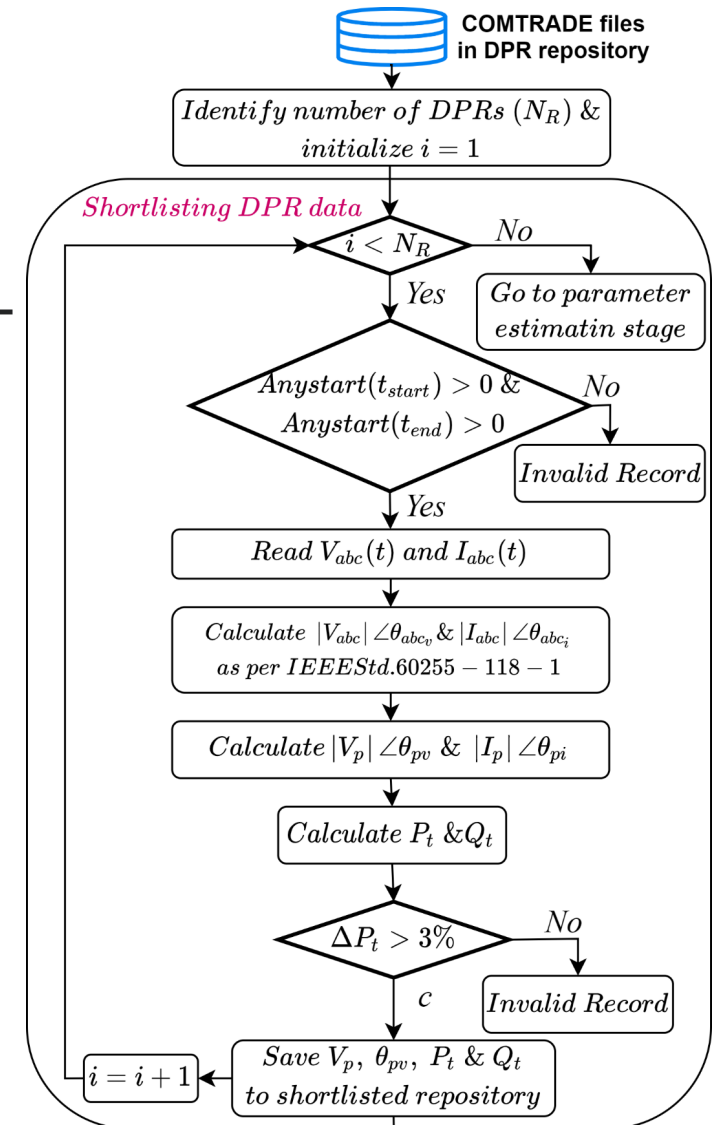


Sample 3



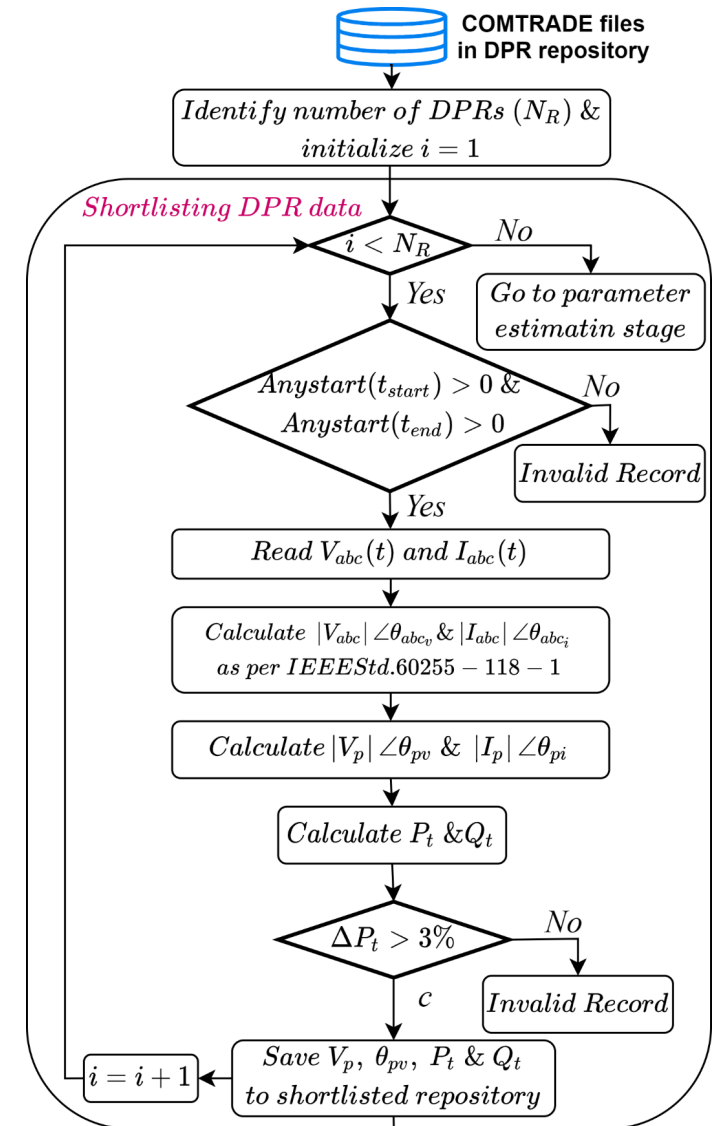
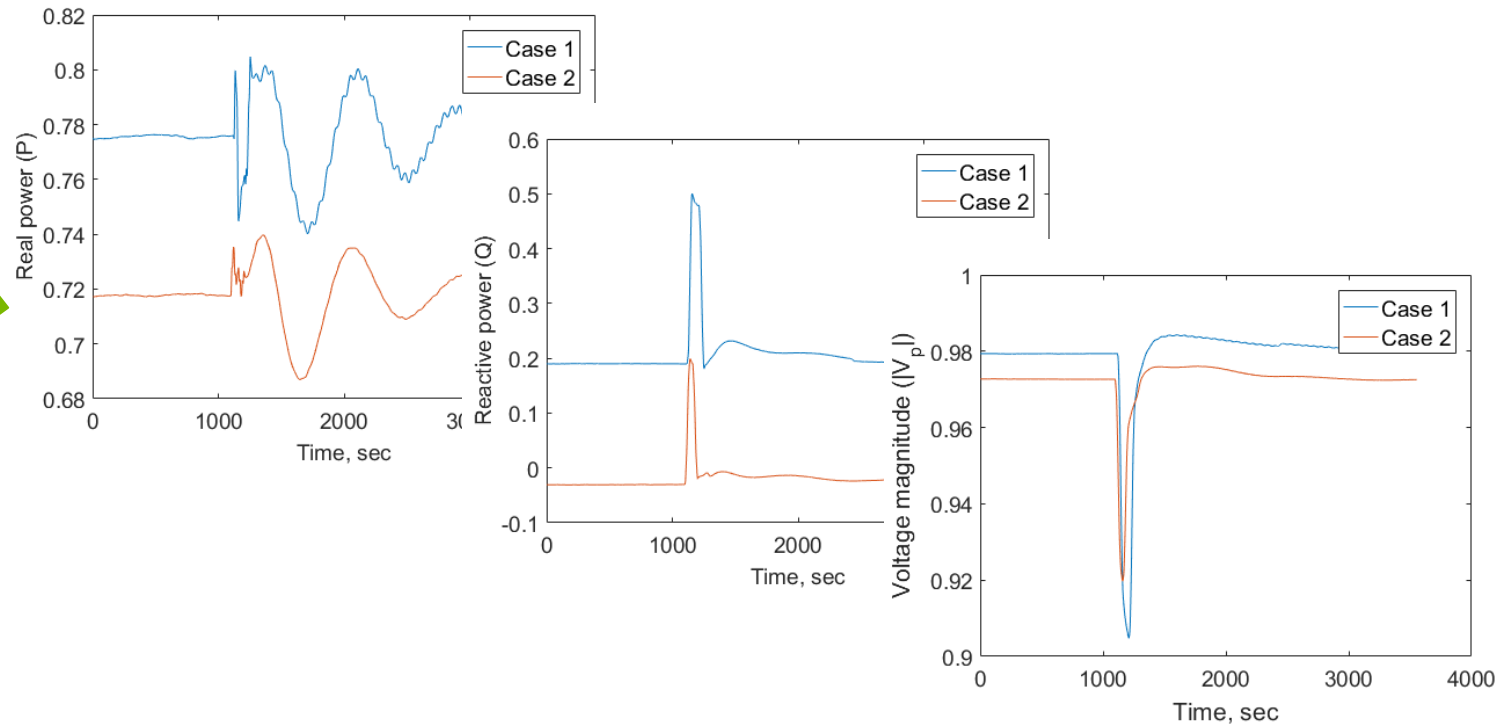
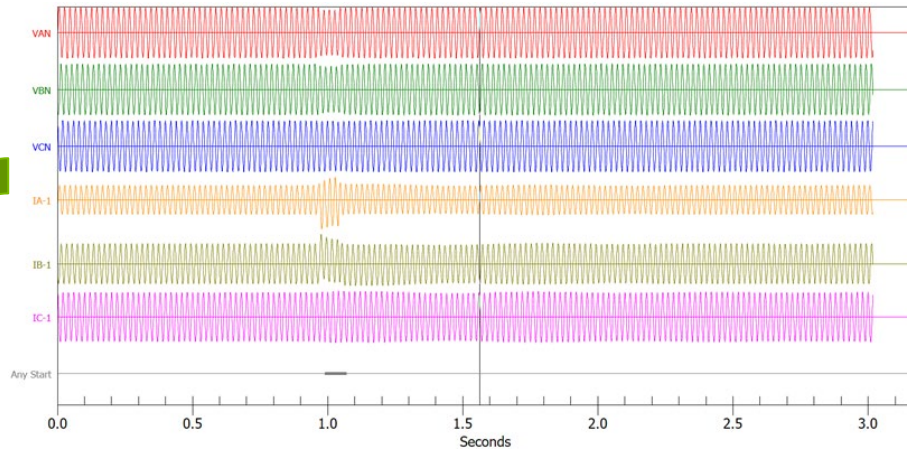
# PROCESSING OF AMI 2.0 RAW DATA

- DPR records are available either as COMTRADE files, which consist of .CFG and .DAT files.
- Data in .DAT files need to be understood as per the .CFG file.
- After reading the instantaneous voltages and currents from .DAT files, positive sequence voltage phasor need to be calculated from voltages.
- All the calculations are performed using the per unit quantities.
- Individual processing of data is not preferred due to large number of available records.
- P, Q, V and theta are calculated not directly obtained from the records.
- An automated program is written to read all the COMTRADE files and calculate P,Q,V and  $\theta$  of all the **useful records** in a matrix.



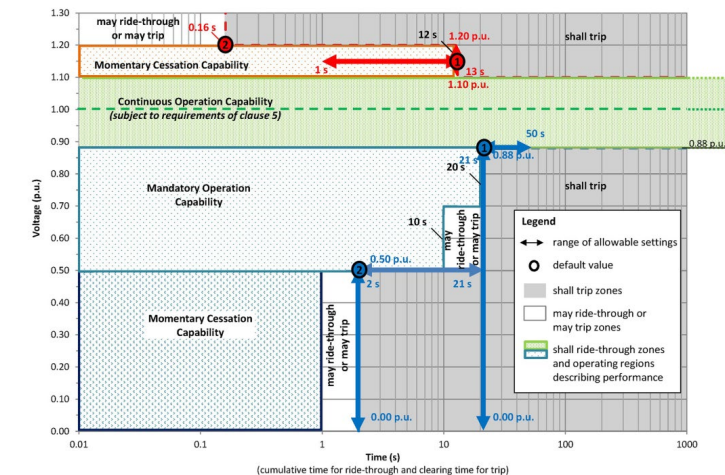


# PROCESSING OF AMI 2.0 RAW DATA

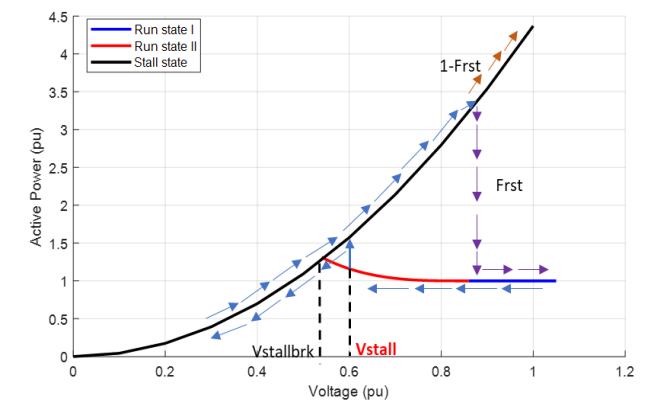


# IMPORTANT DEVICES FOR DISTRIBUTION SYSTEM DYNAMICS: DISTRIBUTED GENERATION AND MOTOR-D

- Distributed resources are required to have specific voltage tripping and ride-through capabilities to maintain grid stability and reliability during disturbances as per IEEE 1547 [1].
- Stalling behavior of the single-phase induction motors leads to the delayed voltage recovery during the disturbances. This behavior of single-phase motors is modeled.



IEEE Standard 1547 Voltage Sensitivity of DERs



Motor D stalling characteristics

# AGGREGATION OF DISTRIBUTION SYSTEM: COMPOSITE LOAD MODEL

The WECC composite load model structure includes the aggregated representation of static loads, electronic loads, constant-torque three-phase motors (A), high inertia speed squared load motors (B), low inertia speed-squared load motors (C), constant-torque single-phase motors (D), and DGs.

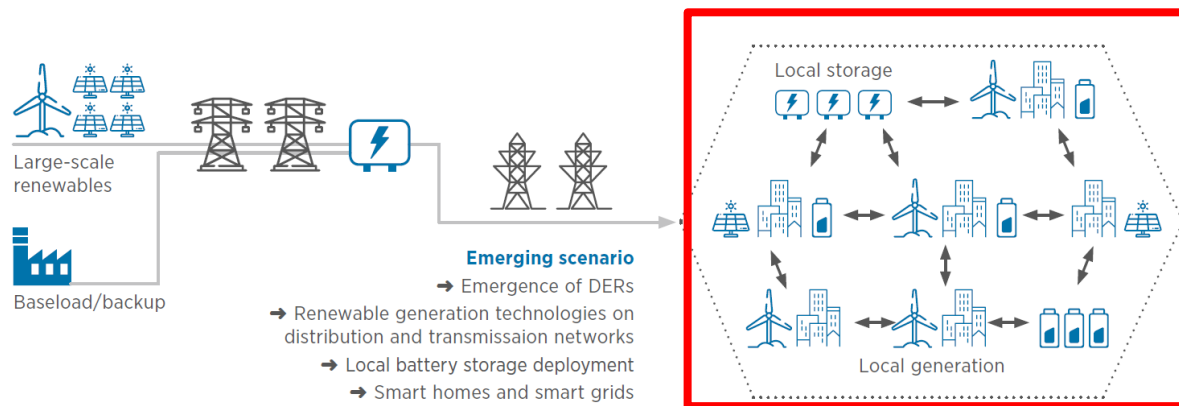
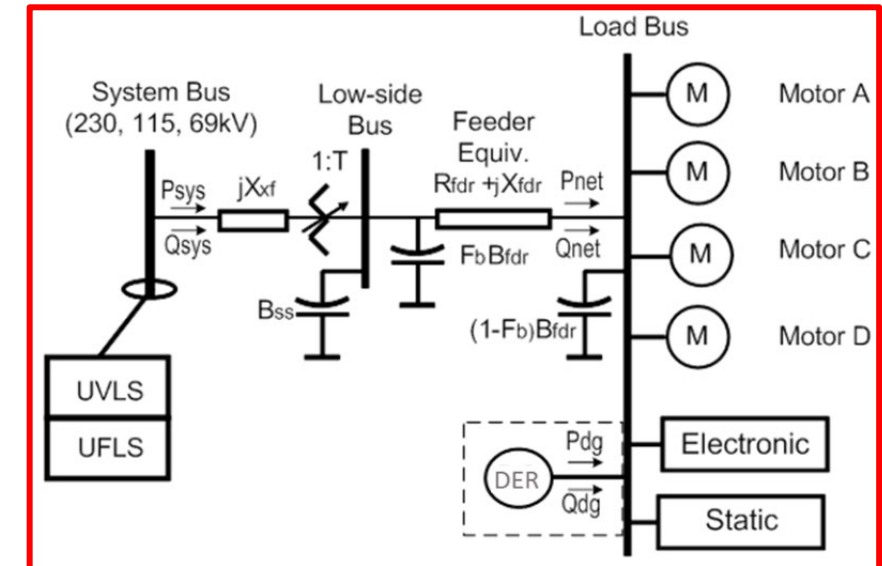


Fig 1. Power system due to the emergence of distributed energy resources [1]



[1] Arina Anisie, Francisco Boshell and Elena Ocenic, "Future role of distribution system operators: Innovation landscape brief", The International Renewable Energy Agency (IRENA), 2019.

[2] Western Electricity Coordinating Council. "WECC Composite Load Model Specification", Modeling and Validation Subcommittee, WECC, April 2021.

# DISTRIBUTION SYSTEM CLUSTERING AND AMI LOCATIONS

- This clustering is based on calculating the impact of each nodal injection on the voltage with the conditions set by the inherent structure of the distribution network (DS admittances).
- Consider the admittance matrix (Y), eigen value diagonal matrix ( $diag(\lambda)$ ) and transition matrix (P). then

Admittance matrix can be represented as:  $Y = P \cdot diag(\lambda) \cdot P^{-1}$

Impedance matrix can be expressed as:  $Z = P \cdot diag\left(\frac{1}{\lambda}\right) \cdot P^{-1}$

Nodal voltages in the distribution network are:  $V = Z \cdot I$

$$V = \left[ P \cdot diag\left(\frac{1}{\lambda}\right) \cdot P^{-1} \right] \cdot I = \sum_n \frac{1}{\lambda_n} [S_n]^T \cdot I$$

$$[S_n] = \begin{bmatrix} \frac{\partial \lambda_n}{\partial Y_{11}} & \cdots & \frac{\partial \lambda_n}{\partial Y_{1N}} \\ \vdots & \ddots & \vdots \\ \frac{\partial \lambda_n}{\partial Y_{N1}} & \cdots & \frac{\partial \lambda_n}{\partial Y_{NN}} \end{bmatrix}$$

Eigen value sensitivity matrix is given by:  $[S_n]$

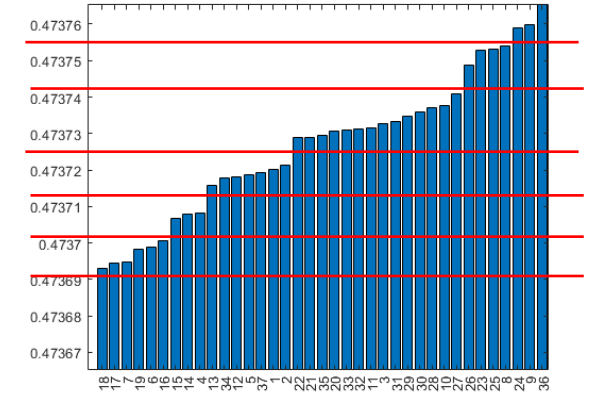


Fig. 1 Nodal sensitivity indices

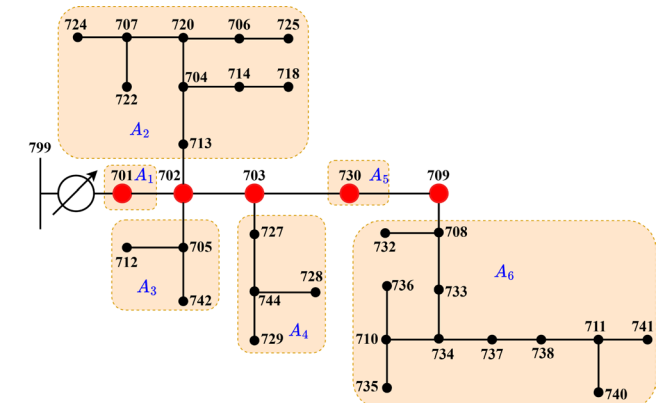


Fig. 2 DS with various components in the secondary circuits clustered based on electrical distance



# DS CLUSTER REPRESENTATION

- A full DS is clustered into multiple sub-models using the steady state nodal voltage sensitivities.
- Each cluster in the distribution system is represented by an equivalent composite load model.

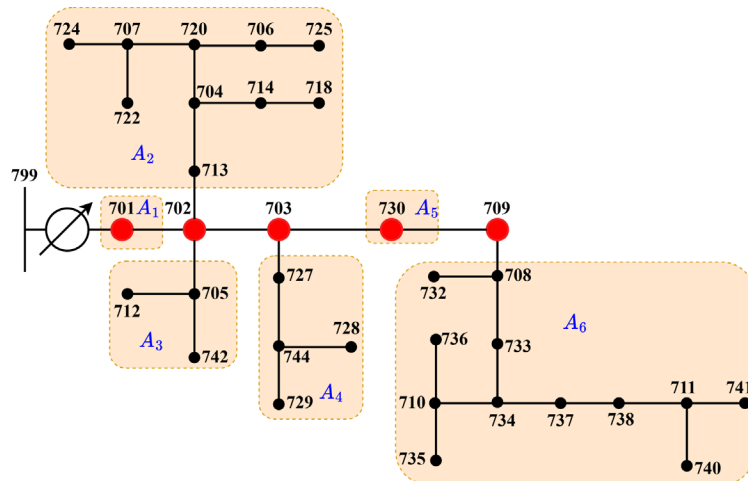


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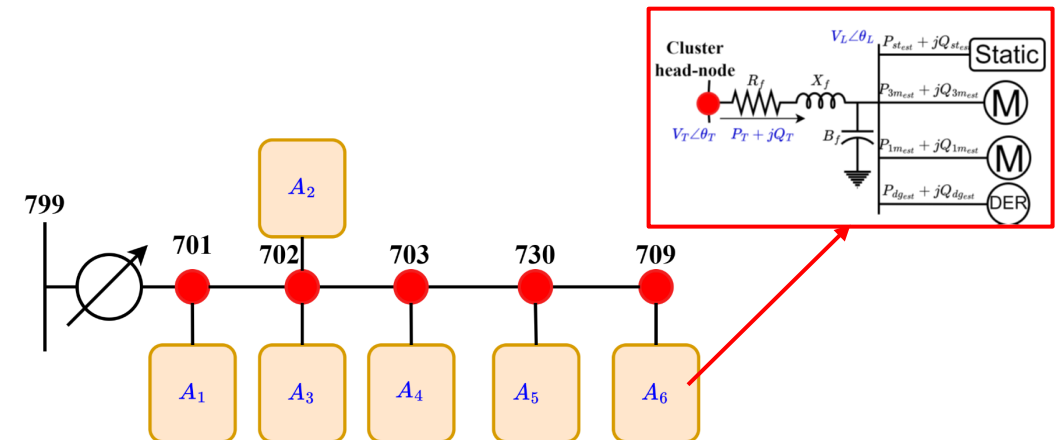


Fig. 2 Resulting DS-ROM with CLM sub-models

# DS CLUSTER REPRESENTATION

The parameters of the CLM corresponding to each sub-model in an aggregated DS shown in Fig. 2 are identified using the measurements at the cluster head node of the sub-model shown in Fig. 7 obtained through the simulated responses.

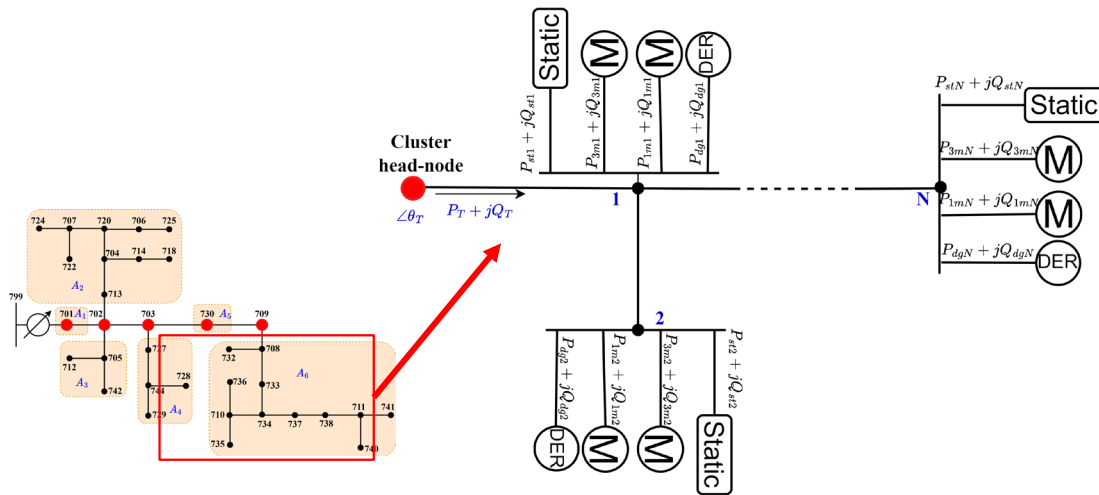


Fig. 1 Detailed representation of single cluster in DS

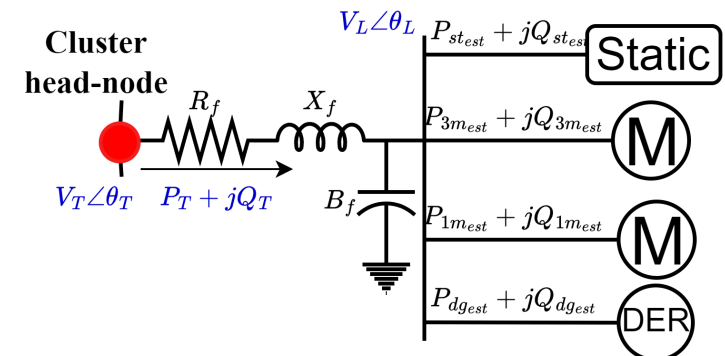
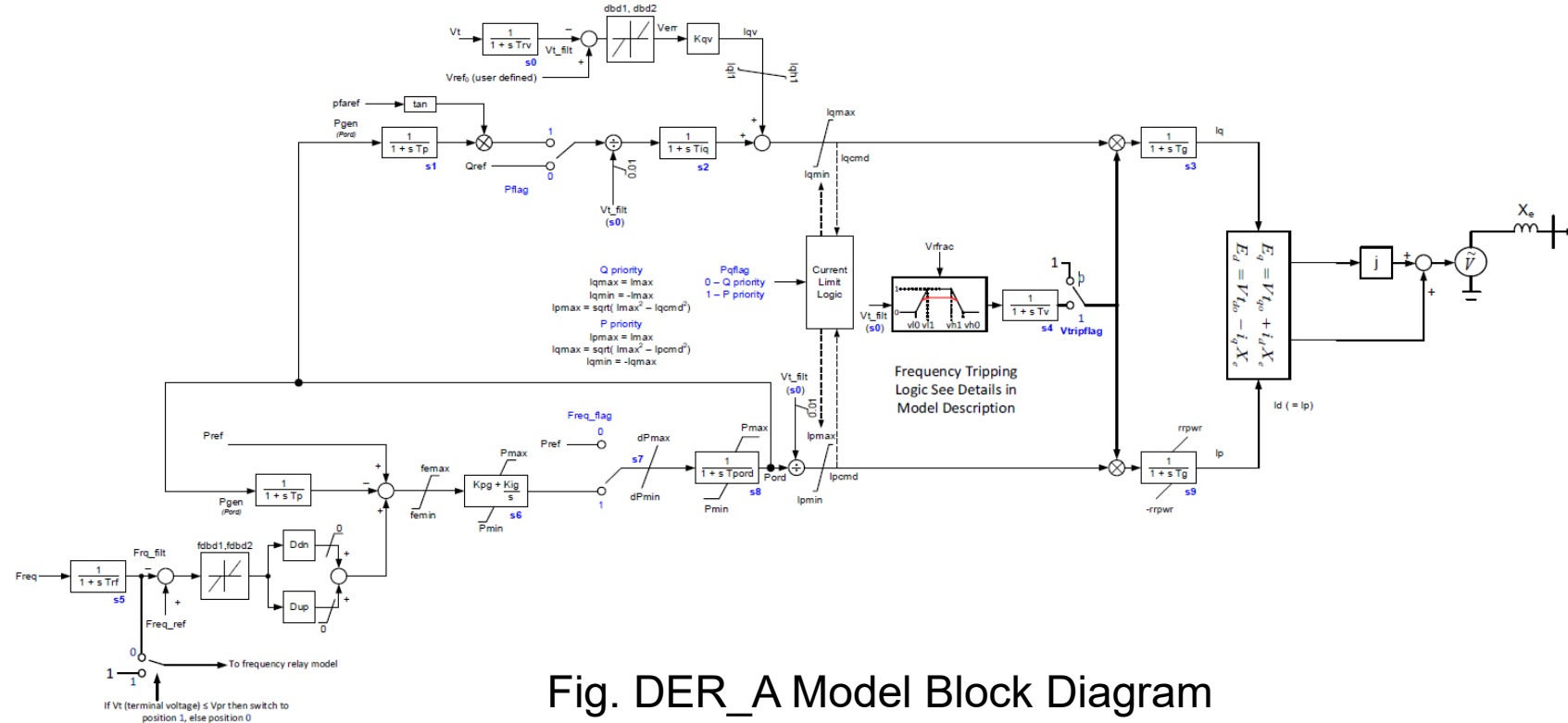


Fig. 2 Equivalent of a single cluster representation in DS

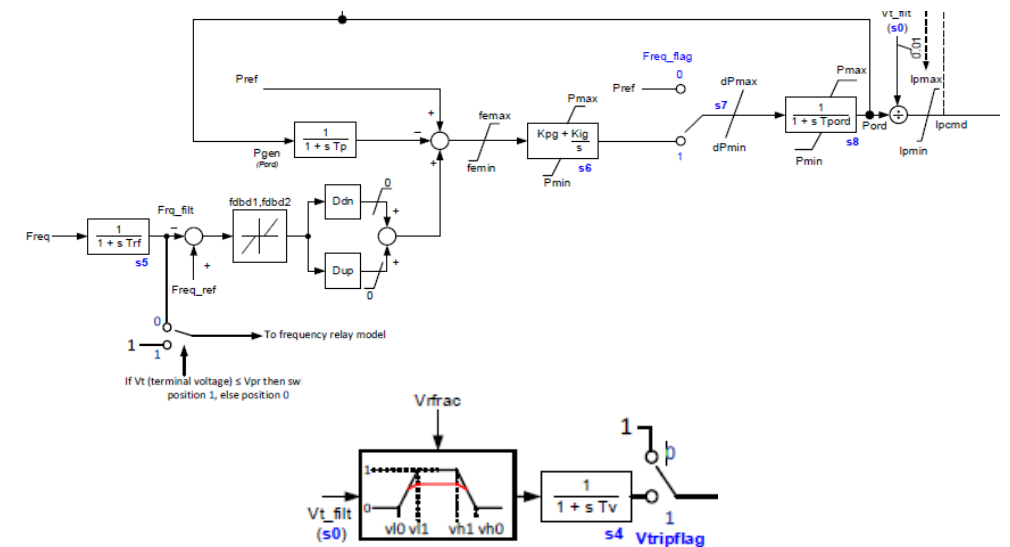
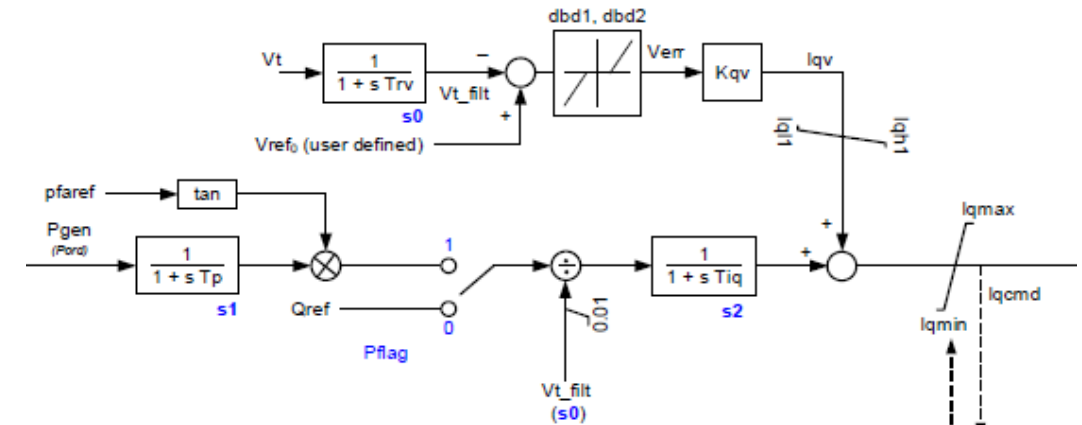
# DS CLUSTER MODEL IDENTIFICATION: DER PARAMETER SELECTION



- Fixing a control mode of operation, current limiting priority, and fault ride-through capability characteristics will limit the number of variable parameters in the model.
- Shortlisted few parameters for the estimation of CLM for each cluster.

# DS CLUSTER MODEL IDENTIFICATION: DER PARAMETER SELECTION

- Consider that the DERs in the test system to be operated in voltage control mode with constant reactive power reference, reactive power- voltage control loop consists of  $T_{rv}$ ,  $K_{qv}$  and  $T_{iq}$  as variables.
- When a DER is not responding to the frequency variations with the fixed real power reference, then the active power-frequency controls consist of  $T_{pord}$  as a variable.
- $V_{pr}$  and  $T_v$  represent the emulation of fractional tripping that is intended to represent a portion of the DER tripping due to voltage violations.





# DS CLUSTER MODEL IDENTIFICATION: EVENT PLAYBACK

- The time series data of VT , PT , and QT for every head-node of the cluster through the TD+DS simulations is utilized for the dynamic parameter identification of each cluster's CLM using a white-box model.
- The white-box model considers the voltages at the head node as input and real and reactive powers in each cluster as outputs.

$$\mathcal{O}(p) = \sum_{i=1}^k |P_{rec,i} - P_{cal,i}(p)|^2 + |Q_{rec,i} - Q_{cal,i}(p)|^2$$

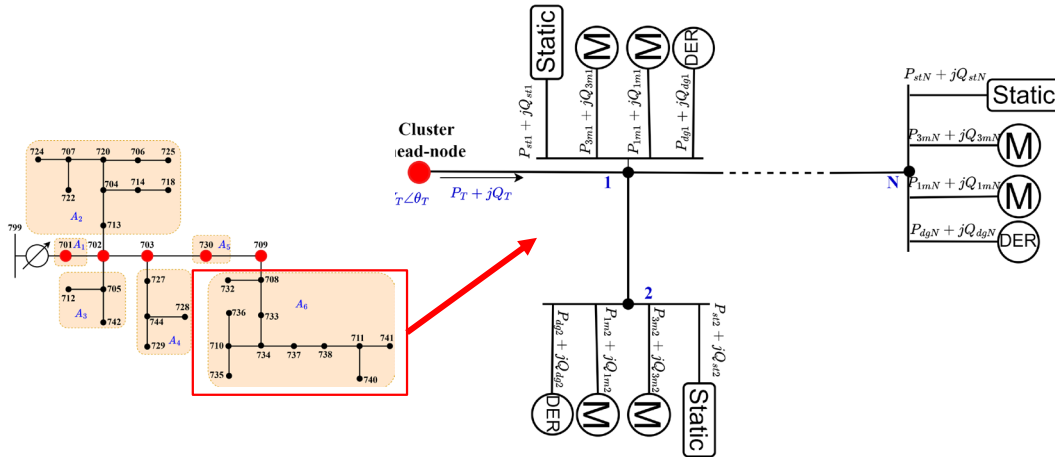


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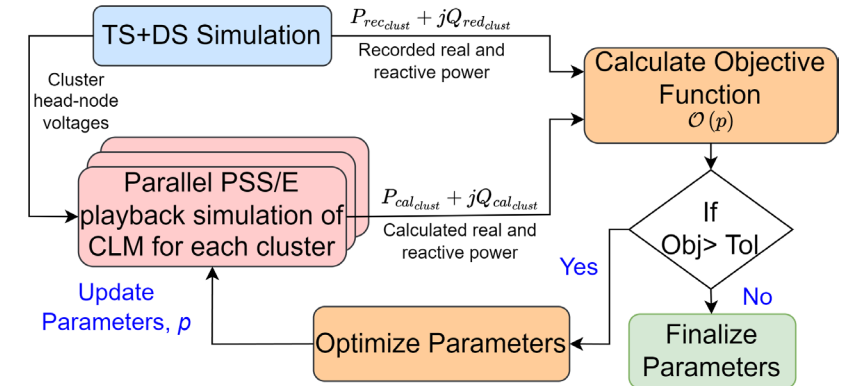


Fig. 2 The flowchart of the python based iterative parameter estimation methodology of the CLM Sub-models

# DS CLUSTER MODEL IDENTIFICATION: RESULTS

- Test system with IEEE 14-bus TS + 37-node DS is simulated to validate with proposed representation of distribution system [1].
- Voltage at 14<sup>th</sup> bus and real power from DG in DS for a fault at 6<sup>th</sup> bus after representing distribution system with ROM-DS are presented in Fig. 2.

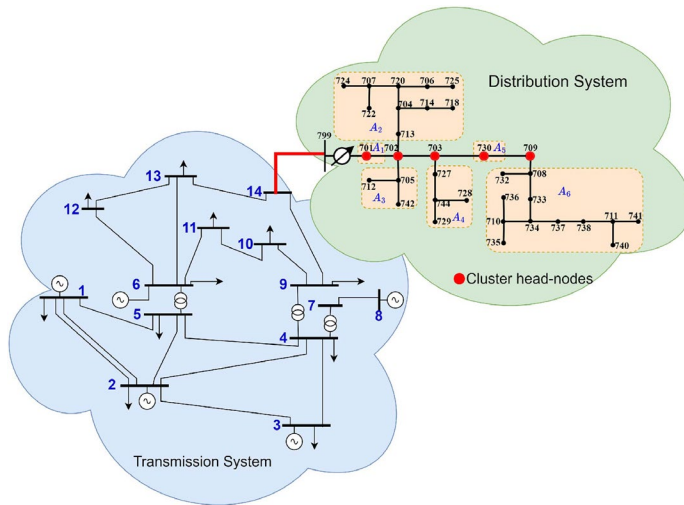


Fig. 1 TS+DS simulation setup to generate data from DS

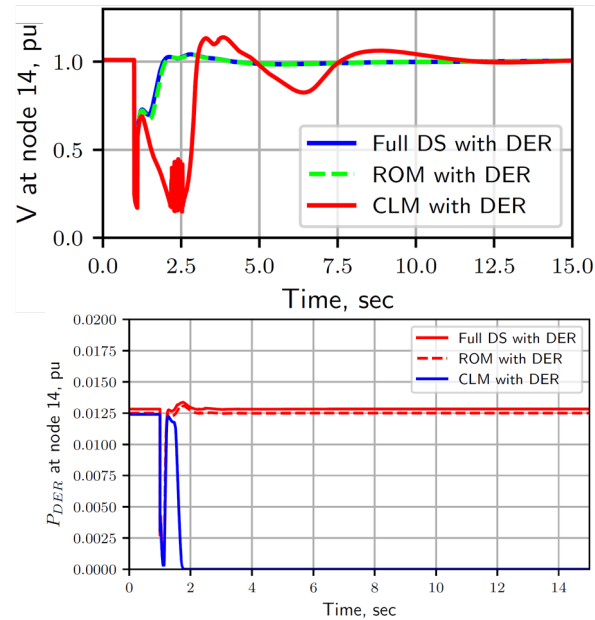


Fig. 2 Voltage at 14<sup>th</sup> bus and real power from DER

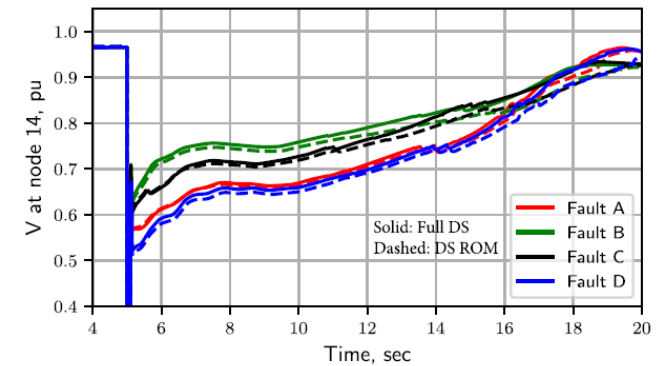


Fig. 3 Voltage at 14<sup>th</sup> bus for different faults

# DS CLUSTER MODEL IDENTIFICATION: RESULTS VALIDATION

- A feeder from a real distribution test system supplied by a 69 kV substation located in the Midwest region of the U.S with 240 nodes is considered in this study.
- The feeder is modified to have 12.4 MW load with 30% of 1- $\phi$  induction motors (motor-D) and 30% DER penetration.

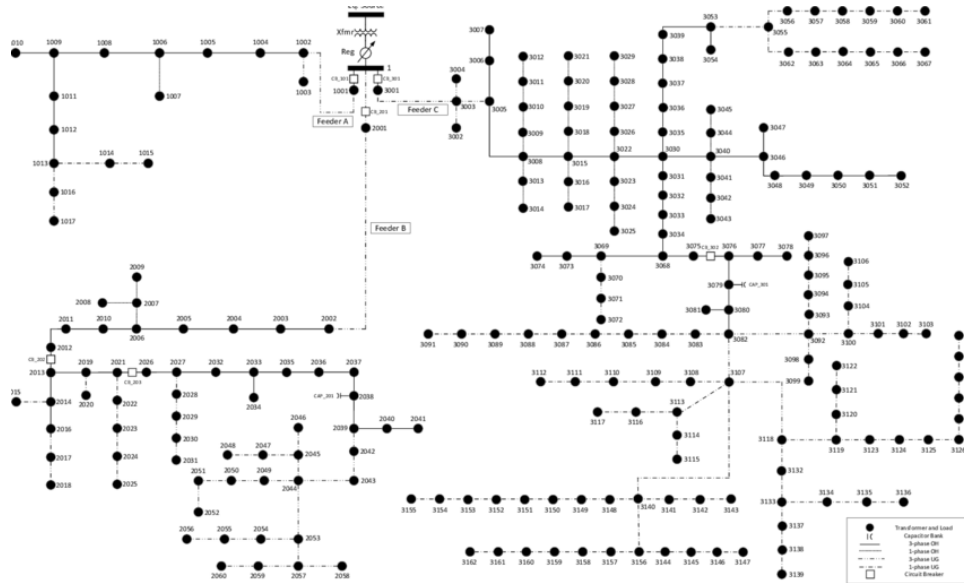


Fig. 1 240 Node Practical DS

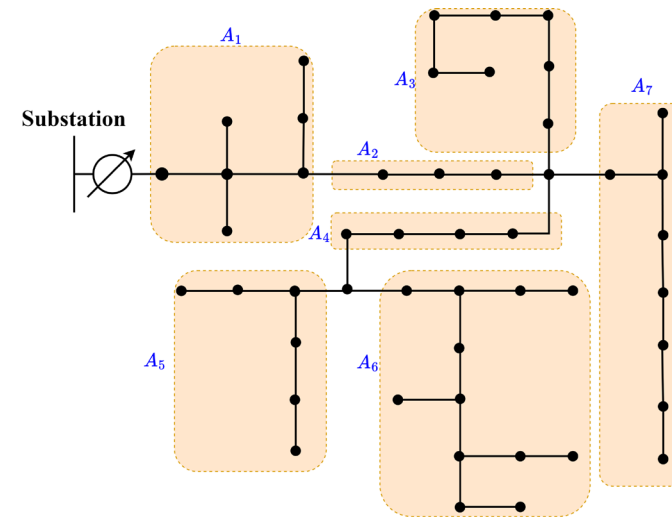


Fig. 2 Resulting DS-ROM with CLM sub-models

# DS CLUSTER MODEL IDENTIFICATION: RESULTS

## VALIDATION

- A feeder from a real distribution test system supplied by a 69 kV substation located in the Midwest region of the U.S with 240 nodes is considered in this study.
- Voltage at 6<sup>th</sup> bus and reactive power from DS for a fault at 14<sup>th</sup> bus after representing distribution system with ROM-DS are presented in Fig. 2.

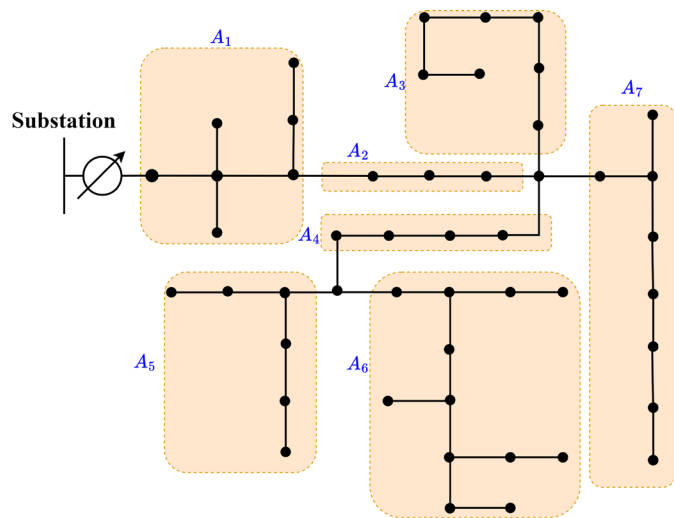


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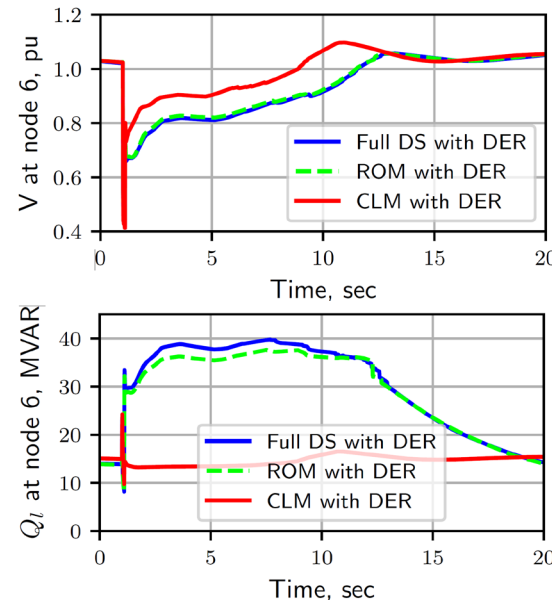


Fig. 2 Voltage at 6<sup>th</sup> bus and reactive power from DS

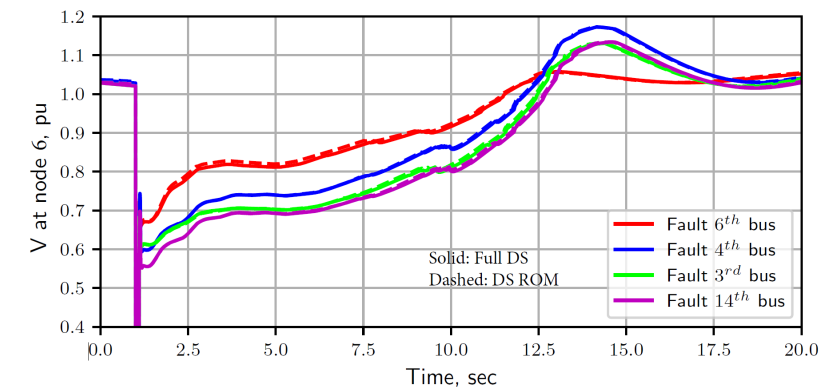


Fig. 3 Voltage at 6<sup>th</sup> bus for different faults



# CONCLUSIONS

- **Evolving Grid Dynamics:** High penetration of **IBRs in TS and DS** are shifting distribution systems from passive loads to **active grid participants**
- **Stronger Need for ISOs** to have **sufficient visibility and data** to Model, dispatch and maintain reliability
- **Event records from AMI 2.0** helps characterize **aggregated DG dynamic** behavior and variability.
- **Point-on-wave data from AMI** can be utilized to identify the model parameters of the DS clusters.
- A systematic approach is presented to **utilize the AMI 2.0 data** for the aggregated DS dynamics.

# FUTURE DIRECTIONS

- Develop a tool that processes the local AMI 2.0 data to obtain phasor information suitable for aggregated DS model identification.
- Explore advance AI to extract features in the event records and direct the users in sensitive parameters to be identified with the specific record.
- Validate the developed approaches using the utility AMI data.

**THANK YOU**